

Instabilities in free-surface Hartmann flow at low magnetic Prandtl numbers

D. GIANNAKIS¹†, R. ROSNER^{1,2,3} AND P. F. FISCHER³

¹Department of Physics, University of Chicago, Chicago, IL 60637, USA

²Department of Astronomy and Astrophysics, University of Chicago, Chicago, IL 60637, USA

³Argonne National Laboratory, Argonne, IL 60439, USA

(Received 7 August 2008; revised 15 April 2009; accepted 18 April 2009)

We study the linear stability of the flow of a viscous electrically conducting capillary fluid on a planar fixed plate in the presence of gravity and a uniform magnetic field, assuming that the plate is either a perfect electrical insulator or a perfect conductor. We first confirm that the Squire transformation for magnetohydrodynamics is compatible with the stress and insulating boundary conditions at the free surface but argue that unless the flow is driven at fixed Galilei and capillary numbers, respectively parameterizing gravity and surface tension, the critical mode is not necessarily two-dimensional. We then investigate numerically how a flow-normal magnetic field and the associated Hartmann steady state affect the soft and hard instability modes of free-surface flow, working in the low-magnetic-Prandtl-number regime of conducting laboratory fluids ($Pm \leq 10^{-4}$). Because it is a critical-layer instability (moderately modified by the presence of the free surface), the hard mode exhibits similar behaviour as the even unstable mode in channel Hartmann flow, in terms of both the weak influence of Pm on its neutral-stability curve and the dependence of its critical Reynolds number Re_c on the Hartmann number Ha . In contrast, the structure of the soft mode's growth-rate contours in the (Re, α) plane, where α is the wavenumber, differs markedly between problems with small, but non-zero, Pm and their counterparts in the inductionless limit, $Pm \searrow 0$. As derived from large-wavelength approximations and confirmed numerically, the soft mode's critical Reynolds number grows exponentially with Ha in inductionless problems. However, when Pm is non-zero the Lorentz force originating from the steady-state current leads to a modification of $Re_c(Ha)$ to either a sub-linearly increasing or a decreasing function of Ha , respectively for problems with insulating or perfectly conducting walls. In insulating-wall problems we also observe pairs of counter-propagating Alfvén waves, the upstream-propagating wave undergoing an instability driven by energy transferred from the steady-state shear to both of the velocity and magnetic degrees of freedom. Movies are available with the online version of the paper.

1. Introduction

Free-surface shear magnetohydrodynamic (MHD) flows arise in a variety of industrial and astrophysical contexts, including liquid-metal diverters in fusion reactors (Abdou *et al.* 2001; Bühler 2007), liquid-metal forced-flow targets (Shannon

† Email address for correspondence: dg227@uchicago.edu

et al. 1998), plasma oceans on white dwarfs and neutron stars (Bildsten & Cutler 1995; Alexakis *et al.* 2004) and accretion disks around stellar remnants (Rüdiger *et al.* 1999; Balbus & Henri 2007). Flows of this type typically take place at high Reynolds number $Re \gtrsim 10^4$ and within strong background magnetic fields ($Ha \gtrsim 10^2$, where Ha is the Hartmann number). Broadly speaking, one is interested in characterizing their stability properties because of either engineering requirements (e.g. in a fusion-reactor diverter) or the possibility of the involvement of a free-surface instability in the observed phenomena (such as classical novae and neutron star X-ray bursts).

When the magnetic Prandtl number Pm of the working fluid is small, the effect of an external magnetic field is known to be stabilizing and weakly dependent on Pm in a variety of flow configurations (see Müller & Bühler 2001 and the references therein). In particular, Takashima (1996) has numerically studied the stability of plane Poiseuille flow modified by a flow-normal magnetic field, hereafter called ‘channel Hartmann flow’, under insulating boundary conditions and has determined that the critical Reynolds number Re_c for instability increases monotonically with the Hartmann number. Moreover, for $Pm \leq 10^{-4}$ (an interval encompassing all known conducting laboratory fluids) Re_c was found to experience a mild, $O(10^{-3})$, decrease compared to its value in the inductionless limit $Pm \searrow 0$, where the magnetic field becomes a background variable decoupled from the flow. The free-surface version of the problem, hereafter referred to as ‘free-surface Hartmann flow’, has mainly been studied via weakly nonlinear analysis (Gordeev & Murzenko 1990; Korsunsky 1999; Mukhopadhyay, Dandapat & Mukhopadhyay 2008) and using asymptotic approximations of the linearized stability equations for large-wavelength gravity waves (Hsieh 1965; Ladikov 1966; Gupta & Rai 1968) or gravity–capillary waves (Lu & Sarma 1967). However, to the best of our knowledge, the degree of applicability of the inductionless approximation has not been discussed in the context of free-surface MHD stability problems (cf. the closed-channel calculations of Takashima 1996).

Making use of recently developed spectral Galerkin methods for Orr–Sommerfeld (OS) eigenvalue problems (Kirchner 2000; Melenk, Kirchner & Schwab 2000; Giannakis, Fischer & Rosner 2009), in the present work we pursue a temporal stability analysis for free-surface Hartmann flow at low (but non-zero) magnetic Prandtl numbers, assuming that the lower wall is either an insulator or a perfect electrical conductor. Our main result is that for large wavelengths ($\alpha \lesssim 1$, where α is the modal wavenumber), the spectrum of free-surface Hartmann flow contains two types of normal modes, neither of which is present in channel problems and whose stability is affected strongly by the dynamical response of the magnetic field to the fluid (which vanishes in the inductionless limit), even in the $Pm = O(10^{-5})$ regime of liquid metals.

The first of these modes is related to the unstable gravity wave, oftentimes referred to as the ‘soft instability mode’, encountered in non-MHD parallel flow down an inclined plane (Yih 1963, 1969; Lam & Bayazitoglu 1986; Floryan, Davis & Kelly 1987; Kelly *et al.* 1989). In inductionless problems, the gravity wave becomes stabilized when Ha is increased (Hsieh 1965; Gupta & Rai 1968), but in the strong-field limit its growth rate Γ does not follow the characteristic $|\Gamma| \propto Ha^2$ Lorentz damping of the shear modes in the spectrum. Instead, it transitions to an asymptotically neutral phase, where the Lorentz force nearly balances gravity, and the decay rate $|\Gamma| \propto Ha^{-2}$ decreases towards zero. In problems with non-zero, yet small, Pm , Lorentz forces originating from magnetic field perturbations are found to be sufficient to alter the near equilibrium attained in the inductionless limit, leading to high sensitivity of the mode’s stability contours in the (Re, α) plane to the magnetic Prandtl number.

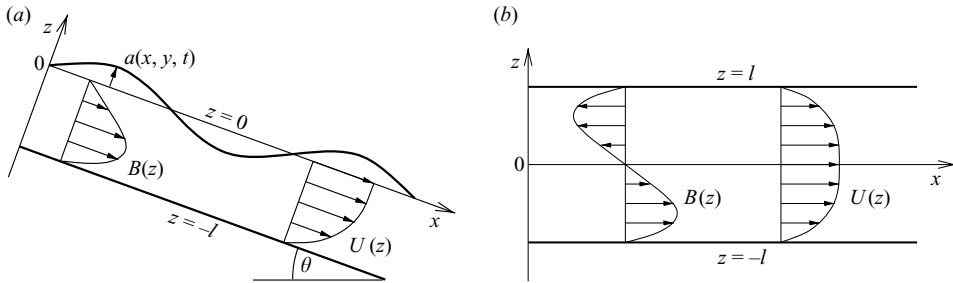


FIGURE 1. Geometry of (a) free-surface and (b) channel Hartmann flow. The steady-state velocity and induced magnetic field profiles are $U(z)$ and $B(z)$, respectively (see §2.4). The y axis is directed into the plane of the paper.

The second type of modes in question is travelling Alfvén waves, which we have only encountered in flows with an insulating lower wall. When the background fluid is at rest, these modes appear at sufficiently large Hartmann numbers as a pair of counter-propagating waves, whose phase speed and decay rate increase linearly with Ha . Their kinetic and magnetic energies are nearly equal, but in the large-wavelength cases studied here the majority of the magnetic energy is carried by the magnetic field penetrating into the region exterior to the fluid. When a steady-state flow is established, the upstream-propagating Alfvén mode becomes unstable due to positive Reynolds and Maxwell stresses as the Alfvén number Al is increased.

Aside from instabilities associated with gravity and Alfvén waves, free-surface flow also exhibits an instability of the critical-layer type (modified by the presence of the free surface), called the ‘hard instability’ (Lin 1967; De Bruin 1974; Floryan *et al.* 1987). Sharing a common origin with the even unstable mode in channel Hartmann flow (Lock 1955; Potter & Kutchev 1973; Takashima 1996), the critical parameters of the hard mode at small Pm are close to the corresponding ones in the inductionless limit. However, in light of the presence of gravity and Alfvén waves, our analysis suggests that the inductionless approximation must be used with caution when dealing with free-surface MHD.

The plan of this paper is as follows. In §2 we formulate the governing equations and boundary conditions of our stability problems and discuss the validity of the Squire transformation. In §3 we derive an energy-conservation law for temporal normal modes in free-surface MHD. We present our results in §4 and conclude in §5. The Appendix contains a discussion of large-wavelength ($\alpha \searrow 0$) perturbation theory. Movies illustrating the behaviour of the modal eigenvalues on the complex plane as Ha or Pm are varied are available with the online version of the paper.

2. Problem formulation

2.1. Geometrical configuration

Using x , y and z to respectively denote the streamwise, spanwise and flow-normal coordinates, oftentimes collected in the position vector $\mathbf{r} := (x, y, z)$, and t to denote time, we consider the flow geometries shown in figure 1. In free-surface problems the lower planar surface $z = -l$ is inclined at an angle θ with respect to the horizontal, and the upper fluid boundary has oscillation amplitude $z = a(x, y, t)$, with $a = 0$ in the steady state. In channel problems the flow takes place between two fixed parallel plates located at $z = \pm l$. In both cases, the working fluid is incompressible and

has density ρ , dynamic viscosity μ and electrical conductivity λ . Additionally, the free surface has surface tension σ and is also acted upon by a gravitational field $\mathbf{g} := g(\sin(\theta)\mathbf{x} - \cos(\theta)\mathbf{z})$. The fixed plates are treated as either electrical insulators or perfect electrical conductors.

For future convenience we introduce the function $A(\mathbf{r}, t) := z - a(x, y, t)$, which vanishes on the free surface and leads, through its gradient, to the expression

$$\mathbf{n} := \nabla A / \|\nabla A\| = (-\partial_x a, -\partial_y a, 1) + O(a^2) \quad (2.1)$$

for the free-surface outward unit normal (for our purposes it suffices to work at linear order in a). Moreover, we choose $\mathbf{t}^{(x)} := (1, 0, \partial_x a)$ and $\mathbf{t}^{(y)} := (0, 1, \partial_y a)$ as mutually orthogonal unit vectors tangent to the free surface ($\mathbf{t}^{(x)} \cdot \mathbf{n} = \mathbf{t}^{(y)} \cdot \mathbf{n} = \mathbf{t}^{(x)} \cdot \mathbf{t}^{(y)} = O(a^2)$). The divergence of \mathbf{n} is equal to twice the mean surface curvature κ , for which we compute

$$2\kappa = \nabla \cdot \mathbf{n} = -(\partial_x^2 a + \partial_y^2 a) + O(a^2). \quad (2.2)$$

2.2. Governing equations

Our starting point is the equations for incompressible resistive MHD (e.g. Müller & Bühler 2001),

$$\left. \begin{aligned} \partial_t \mathcal{U} + \mathcal{U} \cdot \nabla \mathcal{U} &= -\nabla \mathcal{P}' + \mathcal{F} + Re^{-1} \Delta \mathcal{U}, \\ \mathcal{F} := Rm \mathcal{J} \times \mathcal{B}, \quad \mathcal{J} &:= Rm^{-1} \nabla \times \mathcal{B} = \mathcal{E} + \mathcal{U} \times \mathcal{B}, \\ \partial_t \mathcal{B} + \mathcal{U} \cdot \nabla \mathcal{B} &= \mathcal{B} \cdot \nabla \mathcal{U} + Rm^{-1} \Delta \mathcal{B}, \\ \nabla \cdot \mathcal{U} &= 0, \quad \nabla \cdot \mathcal{B} = 0, \end{aligned} \right\} \quad (2.3)$$

obeyed by the velocity field $\mathcal{U}(\mathbf{r}, t)$, the pressure $\mathcal{P}'(\mathbf{r}, t)$, the Lorentz force $\mathcal{F}(\mathbf{r}, t)$, the current $\mathcal{J}(\mathbf{r}, t)$ and the magnetic and electric fields in the interior of the fluid, respectively $\mathcal{B}(\mathbf{r}, t)$ and $\mathcal{E}(\mathbf{r}, t)$. Here velocity has been non-dimensionalized by its steady-state value at $z=0$, U_* , and the characteristic values for the remaining dynamical variables are $P_* := \rho U_*^2$, $B_* := (\mu_0 \rho)^{1/2} U_*$, $E_* := U_* B_*$ and $J_* := \lambda E_*$, where each symbol with the subscript $*$ denotes the characteristic value for the corresponding variable in script type. Choosing l as the characteristic length (for both free-surface and channel problems), the resulting hydrodynamic and magnetic Reynolds numbers are $Re := U_* l / \nu$ and $Rm := U_* l / \eta$, where $\nu := \mu / \rho$ and $\eta := 1 / (\mu_0 \lambda)$ are the viscous and magnetic diffusivities. In the following, we frequently substitute for Rm using the magnetic Prandtl number $Pm := \nu / \eta = Rm / Re$.

We consider solutions of the form

$$\left. \begin{aligned} \mathcal{U}(\mathbf{r}, t) &= \mathbf{U}(z) + \mathbf{u}(\mathbf{r}, t), \quad \mathcal{P}'(\mathbf{r}, t) = P'(x, z) + p'(\mathbf{r}, t), \\ \mathcal{B}(\mathbf{r}, t) &= \mathbf{B}(z) + \mathbf{b}(\mathbf{r}, t), \quad \mathcal{J}(\mathbf{r}, t) = \mathbf{J}(z) + \mathbf{j}(\mathbf{r}, t), \quad \mathcal{E}(\mathbf{r}, t) = \mathbf{E}(z) + \mathbf{e}(\mathbf{r}, t), \end{aligned} \right\} \quad (2.4)$$

consisting of steady-state components and linear perturbations, respectively denoted by uppercase and lowercase symbols. The steady-state flow $\mathbf{U}(z) := (U(z), 0, 0)$ is assumed to be streamwise invariant and unidirectional and to take place within a uniform, externally applied magnetic field $\mathbf{B}' := (B'_x, B'_y, B'_z)$, which, for the time being, is allowed to be of arbitrary direction. The applied field permeates the fluid, and assuming its components perpendicular to \mathbf{U} are non-zero, the associated induced current generates a secondary internal magnetic field $\mathbf{I} := (I_x(z), I_y(z), 0)$. Thus, in the interior of the fluid the steady-state magnetic field is $\mathbf{B} := \mathbf{B}' + \mathbf{I}$.

We remark that in free-surface problems the pressure field \mathcal{P}' includes a contribution from the gravitational potential, which will be set by the boundary conditions in §2.3. Since both pressure and the gravitational potential affect the dynamics solely through their gradient, we have allowed P' to depend on the streamwise coordinate x (though in light of the streamwise invariance of the steady state that dependence can be at most linear). Moreover, the flow-normal component of the induced magnetic field has been set to zero in order to meet the divergence-free condition $\nabla \cdot \mathbf{I} = 0$ (a constant non-zero I_z can be absorbed in B'_z). We also note that with our choice of characteristic magnetic field, \mathcal{U} and \mathcal{B} are naturally additive. In particular, using $\hat{\mathbf{B}}'$ and B'_* to respectively denote a unit vector in the direction of \mathbf{B}' and the magnitude of the dimensional external magnetic field, \mathbf{B}' can be expressed as $\mathbf{B}' = \hat{\mathbf{B}}'/Al$, where $Al := U_*(\mu_0\rho)^{1/2}/B'_*$ is the Alfvén number of the flow (for an overview of dimensionless groups in MHD, see Shercliff 1965). An alternative option for reduction to non-dimensional form, frequently encountered in the literature for Hartmann flow (e.g. Takashima 1996, 1998; Müller & Bühler 2001; Bühler 2007), is to set $B_* = B'_*$, in which case the resulting dimensionless magnetic field $\bar{\mathcal{B}}$ is related to ours via $\bar{\mathcal{B}} = Al \mathcal{B}$. Rather than using Al , in the ensuing analysis we mainly parameterize the background magnetic field strength by means of the Hartmann number $Ha := B'_*l(\lambda/\mu)^{1/2} = (ReRm)^{1/2}/Al$, where Ha^2 measures the ratio of Lorentz to viscous stresses.

In problems with insulating boundaries a further dynamical variable is the magnetic field $\mathcal{B}'(\mathbf{r}, t) := \mathbf{B}' + \mathbf{b}'(\mathbf{r}, t)$ in the region exterior to the fluid. As follows from Ampère's law, the perturbation \mathbf{b}' is expressible as the gradient of the magnetic potential $\psi(\mathbf{r}, t)$, which, in light of the solenoidal condition $\nabla \cdot \mathbf{b}' = 0$, obeys Laplace's equation; i.e.

$$\mathbf{b}' = -\nabla\psi, \quad \text{with} \quad \Delta\psi = 0. \quad (2.5a, b)$$

The equations governing the steady state and the perturbations follow by substituting (2.4) into (2.3) and neglecting quadratic terms in the perturbed fields. Using D to denote differentiation with respect to z , the non-zero components of the time-independent equations read

$$Re^{-1}D^2U + B'_zDI_x - \partial_x P = 0, \quad Rm^{-1}D^2I_x + B'_zDU = 0, \quad DP = 0, \quad (2.6a-c)$$

$$B'_zDI_y = 0, \quad D^2I_y = 0, \quad (2.6d, e)$$

where $P(x, z) := P'(x, z) + \mathbf{B}(z) \cdot \mathbf{B}(z)/2$ is the total steady-state pressure, consisting of hydrodynamic, magnetic and (in free-surface problems) gravitational contributions. As for the perturbations, we obtain

$$\partial_t \mathbf{u} + U\partial_x \mathbf{u} + u_z D\mathbf{u} = -\nabla p' + \mathbf{f} + Re^{-1} \Delta \mathbf{u}, \quad (2.7a)$$

$$\mathbf{f} := Rm(\mathbf{j} \times \mathbf{B} + \mathbf{J} \times \mathbf{b}), \quad \mathbf{j} = Rm^{-1} \nabla \times \mathbf{b} = \mathbf{e} - Ub_z \mathbf{y} + \mathbf{u} \times \mathbf{B}, \quad (2.7b, c)$$

$$\partial_t \mathbf{b} + U\partial_x \mathbf{b} + u_z D\mathbf{b} = \mathbf{B} \cdot \nabla \mathbf{u} + b_z D\mathbf{u} + Rm^{-1} \Delta \mathbf{b}, \quad (2.7d)$$

$$\nabla \cdot \mathbf{u} = 0, \quad \nabla \cdot \mathbf{b} = 0, \quad (2.7e, f)$$

where \mathbf{f} is the Lorentz force acting on the perturbed velocity field.

From the linearized Ampère and Ohm laws (2.7c), one can make the heuristic estimate $\|\mathbf{b}\|/\|\mathbf{u}\| = O((PmHa)^{1/2})$ (see Hunt 1966 for similar scaling arguments), where $\|\cdot\|$ denotes suitable norms for the velocity and magnetic field perturbations. This suggests that as $Pm \searrow 0$ with Re and Ha fixed, i.e. in the so-called inductionless limit (Müller & Bühler 2001), \mathbf{b} is negligible, and as a consequence, electromagnetic forces only arise from currents generated by the perturbed electric field \mathbf{e} and from currents induced by the perturbed fluid motions within the steady-state magnetic

field. Moreover, as follows from Faraday's law, $\nabla \times \mathbf{e} = -\partial_t \mathbf{b} \approx 0$, the electric field $\mathbf{e} \approx -Al^{-1} \nabla \phi$ can be determined from the gradient of a potential $\phi(\mathbf{r}, t)$. These observations suggest that for sufficiently small Pm , (2.7b–d,f) can be replaced by the approximate relations

$$\mathbf{f} = Ha^2 Re^{-1} (\nabla \phi + \mathbf{u} \times \hat{\mathbf{B}}') \times \hat{\mathbf{B}}', \quad \Delta \phi = \hat{\mathbf{B}}' \cdot \nabla \times \mathbf{u}, \quad (2.8a, b)$$

where (2.8b) follows from $\nabla \cdot \mathbf{j} \propto \nabla \cdot \nabla \times \mathbf{b} = 0$. If, in addition, the flow is two-dimensional (i.e. none of the dynamical variables depends on y ; the y component of \mathbf{u} and \mathbf{b} is zero; and the only non-zero component of \mathbf{e} and \mathbf{j} may be spanwise), the perturbed electric field $\mathbf{e} = e_y \mathbf{y} \propto \partial_y \phi = 0$ vanishes (equivalently, ϕ becomes an unimportant constant), resulting in a significant reduction of the analytical and computational complexity of the stability problem. The fact that all known conducting laboratory fluids have small magnetic Prandtl numbers ($Pm \lesssim 10^{-5}$) has led to a widespread adoption of the inductionless approximation (Hsieh 1965; Gupta & Rai 1968; Gordeev & Murzenko 1990; Korsunsky 1999; Mukhopadhyay *et al.* 2008). However, the small- $\|\mathbf{b}\|$ assumption is not guaranteed to hold *a priori*, and the full problem must be solved to confirm that the scheme is valid in the parameter regime of interest (Takashima 1996).

2.3. Boundary conditions

The governing equations presented in the preceding section must be solved subject to appropriate initial and boundary conditions. In the temporal stability analysis that follows, initial conditions, as well as periodic boundary conditions on the streamwise and spanwise domain boundaries, are implicitly assumed. However, care must be taken in the choice of boundary conditions on the non-periodic boundaries, as this has led to errors in the past (Lin 1967 and Potter & Kutchev 1973, as indicated by De Bruin 1974 and Takashima 1996, respectively).

Let z_w collectively denote the flow-normal wall coordinates. (In the dimensionless representation, $z_w := \{-1\}$ for free-surface problems and $z_w := \{\pm 1\}$ for channel problems.) In insulating-wall problems we assume that no surface charges and surface currents are present at the fluid–wall interface. Then, in accordance with Maxwell's equations and charge–current conservation (e.g. Shercliff 1965), we set

$$\mathcal{B}|_{z=z_w} = \mathcal{B}'|_{z=z_w}, \quad \mathbf{z} \cdot \mathcal{J}|_{z=z_w} = 0, \quad (2.9)$$

which leads to the boundary conditions

$$I_x(z_w) = 0, \quad I_y(z_w) = 0 \quad (2.10a, b)$$

and

$$(\mathbf{b} + \nabla \psi)|_{z=z_w} = \mathbf{0}, \quad \mathbf{z} \cdot \nabla \times \mathbf{b}|_{z=z_w} = (\partial_x b_y - \partial_y b_x)|_{z=z_w} = 0, \quad (2.11a, b)$$

respectively for the steady-state fields and the perturbations. If, on the other hand, the wall is perfectly conducting, the tangential electric field components are required to vanish at the boundary, and the wall-normal magnetic field $\mathbf{z} \cdot \mathcal{B}$ is set to the externally imposed value B'_z , giving

$$DI_x(z_w) = 0, \quad DI_y(z_w) = 0 \quad (2.12a, b)$$

and

$$\left. \begin{aligned} b_z|_{z=z_w} = 0, \quad \mathbf{x} \cdot \nabla \times \mathbf{b}|_{z=z_w} = (\partial_y b_z - D b_y)|_{z=z_w} = 0, \\ \mathbf{y} \cdot \nabla \times \mathbf{b}|_{z=z_w} = (D b_x - \partial_x b_z)|_{z=z_w} = 0, \end{aligned} \right\} \quad (2.13)$$

where we have used (2.7c) to substitute for the electric field \mathbf{e} in terms of \mathbf{b} . Turning now to the free surface, we assume throughout that the exterior region $z > a$ is electrically insulating. Then, on the basis of similar electrodynamic arguments as those used to write (2.9), we demand

$$\mathbf{t}^{(x)} \cdot (\mathcal{B} - \mathcal{B}')|_{z=a} = \mathbf{t}^{(y)} \cdot (\mathcal{B} - \mathcal{B}')|_{z=a} = \mathbf{n} \cdot (\mathcal{B} - \mathcal{B}')|_{z=a} = 0, \quad \mathbf{n} \cdot \mathcal{J}|_{z=a} = 0. \quad (2.14)$$

In order to evaluate the expressions above for the perturbed quantities, we analytically continue the induced magnetic field \mathbf{I} in the region $0 < z \leq a$. A Taylor expansion to linear order in a then yields the boundary conditions

$$I_x(0) = 0, \quad I_y(0) = 0 \quad (2.15a, b)$$

and

$$\left. \begin{aligned} (\partial_x \psi + b_x)|_{z=0} + \text{DB}_x(0)\partial_x a = 0, \quad (\partial_y \psi + b_y)|_{z=0} + \text{DB}_y(0)\partial_y a = 0, \\ (\text{D}\psi + b_z)|_{z=0} = 0, \quad (\partial_x b_y - \partial_y b_x)|_{z=0} + \text{DB}_y(0)\partial_x a - \text{DB}_x(0)\partial_y a = 0, \end{aligned} \right\} \quad (2.16)$$

which now involve the free-surface amplitude (cf. (2.11)). The requirement that whenever present, the external magnetic field perturbations vanish at infinity completes the specification of boundary conditions for the magnetic field.

Regarding the velocity field, we impose, as usual, no-slip conditions

$$U(z_w) = 0, \quad \mathbf{u}|_{z=z_w} = 0, \quad (2.17a, b)$$

at the solid walls, and consider the kinematics and stress balance to establish boundary conditions at the free surface (for a discussion on interfacial dynamics, see Batchelor 1967). First, noting that the free surface is, by definition, a material surface, leads to the kinematic boundary condition, $\text{d}A/\text{d}t := (\partial_t + \mathcal{U}|_{z=a} \cdot \nabla)A = 0$, which, upon linearization, becomes

$$\partial_t a + U(0)\partial_x a = u_z|_{z=0}. \quad (2.18)$$

In order to formulate the stress conditions, we introduce the stress tensors in the fluid and exterior domains, whose components in the (x, y, z) coordinate system are given by

$$\mathcal{T}_{ij} := -\mathcal{P}\delta_{ij} + \mathcal{B}_i\mathcal{B}_j + \text{Re}^{-1}\mathcal{S}_{ij}, \quad \mathcal{T}'_{ij} := -(\Phi + \mathcal{P}_{B'})\delta_{ij} + \mathcal{B}'_i\mathcal{B}'_j, \quad (2.19)$$

respectively. Here $\mathcal{P} := \mathcal{P}' + \mathcal{B} \cdot \mathcal{B}/2$ is the resultant of the hydrodynamic and magnetic pressures and the gravitational potential; $\mathcal{S}_{ij} := \partial_i \mathcal{U}_j + \partial_j \mathcal{U}_i$ are the components of the rate-of-strain tensor; $\mathcal{P}_{B'}(\mathbf{r}, t) := \mathcal{B}' \cdot \mathcal{B}'/2$ is the external magnetic pressure; and $\Phi(\mathbf{r}) := (-x \sin \theta + z \cos \theta)/Fr^2$ is the gravitational potential, expressed in terms of the Froude number $Fr := U_*/(gl)^{1/2}$. Using $We := \rho l U_*^2/\sigma$ to denote the Weber number, the free-surface curvature κ (2.2), in conjunction with surface tension, introduces a discontinuity $\Sigma := 2\kappa/We$ in the normal stress, such that

$$n_j(\mathcal{T}'_{ij} - \mathcal{T}_{ij})|_{z=a} = \Sigma n_i, \quad (2.20)$$

where n_i are the components of the normal vector \mathbf{n} (2.1), and summation is assumed over repeated indices. Forming the contraction of (2.20) with the orthonormal vectors \mathbf{n} , $\mathbf{t}^{(x)}$ and $\mathbf{t}^{(y)}$ then leads to three stress conditions that we enforce at the free surface, namely the normal-stress boundary condition

$$n_i n_j (\mathcal{T}'_{ij} - \mathcal{T}_{ij})|_{z=a} = \Sigma \quad (2.21)$$

and the shear-stress conditions

$$t_i^{(x)} n_j (\mathcal{T}'_{ij} - \mathcal{T}_{ij})|_{z=a} = t_i^{(y)} n_j (\mathcal{T}'_{ij} - \mathcal{T}_{ij})|_{z=a} = 0. \quad (2.22)$$

Evaluating (2.21) and (2.22) to linear order in the perturbed quantities and eliminating $b'_i|_{z=a}$ using (2.16) yields

$$P(x, 0) = -\sin(\theta)Fr^{-2}x + \mathbf{B}(0) \cdot \mathbf{B}(0)/2, \quad DU(0) = 0 \quad (2.23a, b)$$

and

$$\left. \begin{aligned} (p - p_B - 2Re^{-1}Du_z)|_{z=0} &= (\cos(\theta)Fr^{-2} + \mathbf{B}(0) \cdot D\mathbf{B}(0))a \\ &\quad - 2Re^{-1}DU(0)\partial_x a - We^{-1}(\partial_x^2 a + \partial_y^2 a), \\ (\partial_x u_z + Du_x)|_{z=0} &= -D^2U(0)a, \quad (\partial_y u_z + Du_y)|_{z=0} = 0, \end{aligned} \right\} \quad (2.24)$$

where $p_B := \mathbf{B} \cdot \mathbf{b}$ is the internal magnetic-pressure perturbation. We note that the pressure field P in (2.23a) has a non-zero gradient with respect to x because it includes a contribution from the gravitational force (in addition to the hydrodynamic and magnetic-pressure terms) by construction; in treatments in which P is considered as a pure hydrodynamic pressure (e.g. Yih 1969, chapter 7) $\partial_x P$ would vanish identically.

Besides We and Fr , alternative dimensionless groups for the capillary and normal gravitational forces are the capillary number $Ca := \mu U_* / \sigma = We / Re$ and the Galilei number $Ga := gl^3 \cos \theta / \nu^2 = Re^2 \cos(\theta) / Fr^2$. As we will see in §2.5, unlike We , Fr and θ , the parameters Ga and Ca are invariant under the Squire transformation from three-dimensional to two-dimensional normal modes, and for this reason we have opted to perform the calculations in §4 in the latter representation.

2.4. Steady-state configuration

In the present linear-stability analysis we employ the physically motivated Hartmann velocity and magnetic field profiles, which are the solutions to (2.6a–c). (In anticipation of the Squire transformation in §2.5, we do not explicitly consider the spanwise induced magnetic field I_y .) For convenience we make the substitutions $I_x(z) = B'_z Rm B(z) = Pm^{1/2} H_z B(z)$ and, taking into account (2.6c), $P = -\Pi x + P_0$, where $H_z := (Re Rm)^{1/2} B'_z$, Π and P_0 are respectively a Hartmann number defined in terms of the flow-normal component of the applied magnetic field, the streamwise gradient of the pressure field P and an unimportant constant. Equations (2.6a, b) then become

$$D^2U + H_z^2 DB + Re\Pi = 0, \quad D^2B + DU = 0, \quad (2.25)$$

the general solution of which can be expressed as

$$U(z) = C_0 + C_1 \frac{\sinh(H_z z)}{H_z} + C_2 \frac{\cosh(H_z) - \cosh(H_z z)}{\cosh(H_z) - 1}, \quad (2.26a)$$

$$B(z) = K_0 + K_1 z + C_1 \frac{1 - \cosh(H_z z)}{H_z^2} + C_2 \frac{\sinh(H_z z) - \sinh(H_z)z}{H_z(\cosh(H_z) - 1)}, \quad (2.26b)$$

where C_0 , C_1 , C_2 , K_0 and K_1 are constants such that

$$\Pi = (C_2 H_z \coth(H_z/2) - H_z^2 K_1) / Re. \quad (2.27)$$

We remark that the terms proportional to C_1 correspond to antisymmetric velocity and symmetric magnetic field solutions with respect to z , whereas the constant C_2 gives rise to symmetric velocity and antisymmetric magnetic field profiles. Moreover, the term proportional to K_1 in (2.26b) can be interpreted as the magnetic field due to a uniform current of magnitude K_1/Rm , driven in the spanwise direction. For values

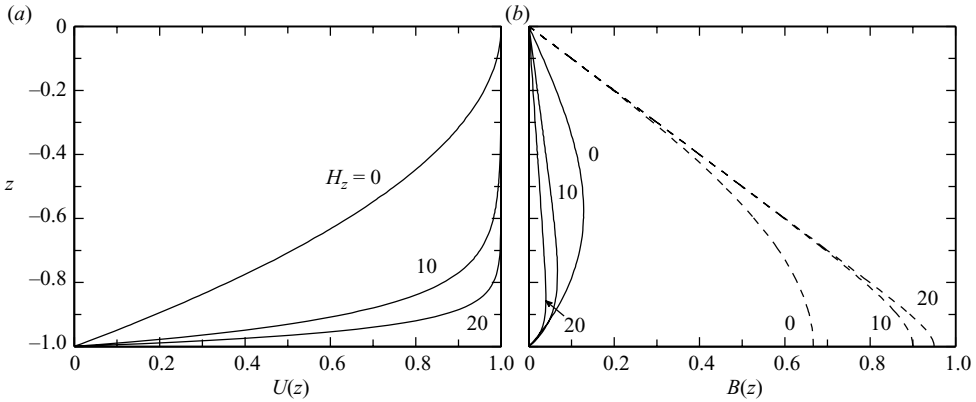


FIGURE 2. (a) Steady-state velocity and (b) magnetic field profile for Hartmann flow with $H_z \in \{0, 10, 20\}$. In (b), the solid (dashed) lines correspond to insulating (perfectly conducting) boundary conditions at $z = -1$.

of the Hartmann number approaching zero, (2.26) becomes

$$U(z) = C_0 + C_1 z + C_2(1 - z^2) + O(H_z^2), \quad (2.28a)$$

$$B(z) = K_0 + K_1 z - C_1 z^2/2 - C_2 z(1 - z^2)/3 + O(H_z^2), \quad (2.28b)$$

and (2.27) reduces to $\Pi = 2C_2/Re$. As expected, in this non-MHD limit U is a quadratic function of z , and even though $B(z)$ is non-zero, the streamwise induced field $I_x = Pm^{1/2} H_z B$ vanishes.

In both of the free-surface and channel problems considered here, the choice of velocity normalization ($U(0)=1$) and boundary conditions ((2.17a) and (2.23b)) implies that $C_0 = C_1 = 0$ and $C_2 = 1$. Moreover, if the walls are insulating, the constants K_0 and K_1 vanish due to (2.10a) and (2.15a). In problems with perfectly conducting walls K_0 is again set to zero, either because of (2.15a) or, in channel problems, by convention (a non-zero K_0 can be absorbed in the applied magnetic field B'_x). However, $K_1 = (\sinh(H_z) - H_z \cosh(H_z))/(H_z(\cosh(H_z) - 1))$ is in this case non-vanishing, due to (2.12a).

Figure 2 illustrates the functional form of these two classes of velocity and magnetic field profiles for Hartmann numbers in the range 0–20. Compared to the parabolic profile in non-MHD flows, Hartmann velocity profiles are characterized by a flat core region and exponential boundary layers of thickness $O(1/H_z)$ near the no-slip walls. Moreover, the mean steady-state velocity, given by

$$\langle U \rangle := \int_{-1}^0 dz U(z) = \frac{\cosh(H_z) - \sinh(H_z)/H_z}{\cosh(H_z) - 1}, \quad (2.29)$$

increases monotonically from its non-MHD ($H_z = 0$) value of $2/3$ to unity as $H_z \rightarrow \infty$. In problems with perfectly conducting walls, $|B(z)|$ peaks at $|z|=1$, and its gradient, which is proportional to the spanwise induced current $J_y = Rm^{-1} DI_x = H_z(ReRm)^{-1/2} DB$, attains its maximum magnitude at $z=0$, where $|DB|=1$. Also, for large H_z the current is close to its maximal value throughout the core. On the other hand, in the insulating-wall case, the current distribution becomes concentrated over the Hartmann layer as H_z grows, with the magnetic-profile gradient reaching its maximum absolute value $|DB(\pm 1)| = (\cosh(H_z) - \sinh(H_z)/H_z)/(\cosh(H_z) - 1) = O(1)$

at the walls, while at the core, where $|DB| = O(1/H_z)$, the current tends to an H_z -independent value.

Before proceeding, it is worthwhile to note a prominent qualitative difference between MHD and non-MHD velocity profiles, which concerns the existence of inflection points. Because the non-MHD velocity profile (2.28a) is quadratic in z , it has constant second derivative. On the other hand, it is possible to show that for suitable choices of the constants C_1 and C_2 and for sufficiently large H_z , the MHD velocity profile (2.26a) possesses an inflection point, so that an inviscid instability can potentially exist. In all of the flows studied here, the choice of boundary conditions completely suppresses the antisymmetric component of U ($C_1 = 0$) and eliminates the possibility of inflectional instabilities. However, one can imagine situations (e.g. a sheared free surface) in which the conditions for the inflection point to exist are satisfied. Whether the non-ideal MHD flow develops in practice an instability mode of inviscid origin would be an interesting topic to investigate in the future.

2.5. Three-dimensional normal modes and the associated Squire transformation

In the three-dimensional temporal-normal-mode analysis we work with the Ansatz

$$\left. \begin{aligned} \mathbf{u} &= \text{Re}((\hat{u}_x(z), \hat{u}_y(z), \hat{u}_z(z))e^{i(\alpha x + \beta y) + \gamma t}), & p &= \text{Re}((\hat{p}(z)e^{i(\alpha x + \beta y) + \gamma t}), \\ \mathbf{b} &= \text{Re}((\hat{b}_x(z), \hat{b}_y(z), \hat{b}_z(z))e^{i(\alpha x + \beta y) + \gamma t}), & \psi &= \text{Re}((\hat{\psi}(z)e^{i(\alpha x + \beta y) + \gamma t}), \end{aligned} \right\} \quad (2.30)$$

where $p := p' + \mathbf{B} \cdot \mathbf{b}$ is the linear perturbation of the pressure field \mathcal{P} ; \hat{u}_i , \hat{p} , \hat{b}_i and $\hat{\psi}$ are complex functions of z ; $\alpha \geq 0$ and $\beta \geq 0$ are respectively the streamwise and spanwise wavenumbers; and $\gamma \in \mathbf{C}$ is the complex growth rate. In channel problems with perfectly conducting walls $\hat{\psi}$ is omitted, while in free-surface problems we also set

$$a = \text{Re}(\hat{a}e^{i(\alpha x + \beta y) + \gamma t}), \quad (2.31)$$

where $\hat{a} \in \mathbf{C}$ is the complex free-surface amplitude. In (2.30) and (2.31) we have adopted the convention used by Ho (1989), under which $\text{Re}(\gamma) =: \Gamma$ gives the modal growth rate, whereas $C := -\text{Im}(\gamma)/(\alpha^2 + \beta^2)^{1/2}$ is the phase velocity. The complex phase velocity $c := i\gamma/(\alpha^2 + \beta^2)^{1/2}$, where $\text{Re}(c) = C$ and $\text{Im}(c)(\alpha^2 + \beta^2)^{1/2} = \Gamma$ is frequently employed in the literature (e.g. Yih 1963, 1969; Takashima 1996) in place of γ .

Substituting (2.30) into (2.2b) and (2.7) leads to the set of coupled ordinary differential equations

$$\Lambda \hat{u}_x = i\alpha \hat{p} - i(\alpha B_x + \beta B_y)\hat{b}_x - B_z D\hat{b}_x - D(B_x)\hat{b}_z + (DU)\hat{u}_z, \quad (2.32a)$$

$$\Lambda \hat{u}_y = i\beta \hat{p} - i(\alpha B_x + \beta B_y)\hat{b}_y - B_z D\hat{b}_y - D(B_y)\hat{b}_z, \quad (2.32b)$$

$$\Lambda \hat{u}_z = D\hat{p} - i(\alpha B_x + \beta B_y)\hat{b}_z - B_z D\hat{b}_z, \quad (2.32c)$$

$$0 = i(\alpha \hat{u}_x + \beta \hat{u}_y) + D\hat{u}_z, \quad (2.32d)$$

$$\Lambda_m \hat{b}_x = -i(\alpha B_x + \beta B_y)\hat{u}_x - B_z D\hat{u}_x + (DB_x)\hat{u}_z - (DU)\hat{b}_z, \quad (2.32e)$$

$$\Lambda_m \hat{b}_y = -i(\alpha B_x + \beta B_y)\hat{u}_y - B_z D\hat{u}_y + (DB_y)\hat{u}_z, \quad (2.32f)$$

$$\Lambda_m \hat{b}_z = -i(\alpha B_x + \beta B_y)\hat{u}_z - B_z D\hat{u}_z, \quad (2.32g)$$

$$0 = i(\alpha \hat{b}_x + \beta \hat{b}_y) + D\hat{b}_z, \quad (2.32h)$$

$$0 = D^2 \hat{\psi} - (\alpha^2 + \beta^2) \hat{\psi}, \quad (2.32i)$$

where $\Lambda := (D^2 - (\alpha^2 + \beta^2))Re^{-1} - (\gamma + i\alpha U)$ and $\Lambda_m := (D^2 - (\alpha^2 + \beta^2))Rm^{-1} - (\gamma + i\alpha U)$. Here, the velocity eigenfunctions are subject to the homogeneous boundary conditions

$$\hat{u}_x(z_w) = \hat{u}_y(z_w) = \hat{u}_z(z_w) = 0 \quad (2.33)$$

at the no-slip boundaries, which follow from (2.17b). Moreover, if the walls are insulating, (2.11) leads to

$$\left. \begin{aligned} \hat{b}_x(z_w) + i\alpha\hat{\psi}(z_w) &= 0, & \hat{b}_y(z_w) + i\beta\hat{\psi}(z_w) &= 0, \\ \hat{b}_z(z_w) + D\hat{\psi}(z_w) &= 0, & \alpha\hat{b}_y(z_w) - \beta\hat{b}_x(z_w) &= 0, \end{aligned} \right\} \quad (2.34)$$

while boundary conditions for the magnetic field eigenfunctions in conducting-wall problems are, in accordance with (2.13),

$$D\hat{b}_x(z_w) = D\hat{b}_y(z_w) = \hat{b}_z(z_w) = 0. \quad (2.35)$$

At the free surface, the kinematic and stress conditions, respectively (2.18) and (2.24), yield

$$\hat{u}_z(0) - (\gamma + i\alpha U(0))\hat{a} = 0, \quad (2.36a)$$

$$D\hat{u}_x(0) + i\alpha\hat{u}_z(0) + D^2U(0)a = 0, \quad D\hat{u}_y(0) + i\beta\hat{u}_z(0) = 0, \quad (2.36b, c)$$

$$\begin{aligned} 0 &= \hat{p}(0) - 2Re^{-1}D\hat{u}_z(0) - (B_x(0)\hat{b}_x(0) + B_y(0)\hat{b}_y(0) + B_z(0)\hat{b}_z(0)) \\ &\quad - \left(\frac{\cos\theta}{Fr^2} + \frac{\alpha^2 + \beta^2}{We^2} + B_x(0)DB_x(0) + B_y(0)DB_y(0) - \frac{2i\alpha}{Re}DU(0) \right) \hat{a}, \end{aligned} \quad (2.36d)$$

while the insulating boundary conditions (2.16) become

$$\hat{b}_x(0) + i\alpha\hat{\psi}(0) + DB_x(0)\hat{a} = 0, \quad \hat{b}_y(0) + i\beta\hat{\psi}(0) + DB_y(0)\hat{a} = 0, \quad (2.37a, b)$$

$$\hat{b}_z(0) + D\hat{\psi}(0) = 0, \quad \alpha\hat{b}_y(0) - \beta\hat{b}_x(0) + (\alpha DB_y(0) - \beta DB_x(0))\hat{a} = 0. \quad (2.37c, d)$$

Equations (2.32), in conjunction with the prescribed boundary conditions (in channel problems these are (2.33) and either (2.34) or (2.35), while in free-surface problems the boundary conditions are (2.33), (2.36), (2.37) and either (2.34) or (2.35)), constitute a differential eigenvalue problem, which must be solved for the eigenvalue γ , the eigenfunctions \hat{u}_i , \hat{p} , \hat{b}_i and, where appropriate, $\hat{\psi}$ and/or \hat{a} . As with several other hydrodynamic stability problems, it is possible to derive a Squire transformation (Squire 1933), mapping each three-dimensional normal mode to a two-dimensional one ($B_y = \beta = \hat{u}_y = \hat{b}_y = 0$) with smaller or equal growth rate $Re(\gamma)$. In the free-surface MHD flows studied here the Squire-transformed variables are

$$\tilde{\alpha} := (\alpha^2 + \beta^2)^{1/2}, \quad \tilde{\gamma} := \tilde{\alpha}\gamma/\alpha, \quad (2.38a)$$

$$\tilde{Re} := \alpha Re/\tilde{\alpha}, \quad \tilde{Pm} = Pm, \quad \tilde{Ga} := Ga, \quad \tilde{Ca} := Ca, \quad (2.38b)$$

$$\tilde{U} := U, \quad \tilde{B}_x := (\alpha B_x + \beta B_y)/\alpha, \quad \tilde{B}_z := \tilde{\alpha} B_z/\alpha, \quad (2.38c)$$

$$\tilde{u}_x := (\alpha\hat{u}_x + \beta\hat{u}_y)/\tilde{\alpha}, \quad \tilde{u}_z := \hat{u}_z, \quad \tilde{b}_x := (\alpha\hat{b}_x + \beta\hat{b}_y)/\tilde{\alpha}, \quad \tilde{b}_z = \hat{b}_z, \quad (2.38d)$$

$$\tilde{p} := \tilde{\alpha}\hat{p}/\alpha, \quad \tilde{a} := \alpha\hat{a}/\tilde{\alpha}, \quad \tilde{\psi} := \hat{\psi}, \quad (2.38e)$$

where, for reasons that will become clear below, we have opted to express the transformations for Rm , Fr and We implicitly through the corresponding ones for Pm , Ga and Ca . It is well known (e.g. Stuart 1954; Lock 1955; Betchov & Criminale 1967) that \tilde{u}_i , \tilde{b}_i , \tilde{p} and $\tilde{\psi}$ satisfy (2.32 a, c–e, g–i) with $\hat{u}_i \mapsto \tilde{u}_i$, $\hat{b}_i \mapsto \tilde{b}_i$, $\hat{p} \mapsto \tilde{p}$,

$\tilde{\psi} \mapsto \tilde{\psi}$, $U \mapsto \tilde{U}$, $B_i \mapsto \tilde{B}_i$, $\alpha \mapsto \tilde{\alpha}$, $\gamma \mapsto \tilde{\gamma}$, $Re \mapsto \tilde{Re}$, $Rm \mapsto \tilde{Rm} := \tilde{Pm}\tilde{Re}$ and, importantly, $\beta \mapsto 0$. Here we verify that the transformation is also compatible with the non-trivial boundary conditions in free-surface MHD but only if U meets the shear-free boundary condition (2.23b). Specifically, making suitable linear combinations of (2.36) and using (2.37d), it is possible to derive the relations

$$\tilde{u}_z(0) - (\tilde{\gamma} + i\tilde{\alpha}\tilde{U}(0))\tilde{a} = 0, \quad D\tilde{u}_x(0) + i\tilde{\alpha}\tilde{u}_z(0) + D^2\tilde{U}(0)\tilde{a} = 0, \quad (2.39a, b)$$

$$0 = \tilde{p}(0) - 2\tilde{Re}^{-1}D\tilde{u}_z(0) - (\tilde{B}_x(0)\tilde{b}_x(0) + \tilde{B}_z(0)\tilde{b}_z(0)) \\ - (\cos(\tilde{\theta})\tilde{Fr}^{-2} + \tilde{\alpha}^2\tilde{We}^{-1} + \tilde{B}_x(0)D\tilde{B}_x(0) - 2i(\tilde{Re}\tilde{\alpha})^{-1}D\tilde{U}(0))\tilde{a}, \quad (2.39c)$$

where $\tilde{Fr} := \tilde{Re}\tilde{Ga}^{-1/2}$ and $\tilde{We} := \tilde{Ca}/\tilde{Re}$, while linear combinations of (2.37) lead to

$$\tilde{b}_x(0) + i\tilde{\alpha}\tilde{\psi}(0) + D\tilde{B}_x(0)\tilde{a} = 0, \quad \tilde{b}_z(0) + D\tilde{\psi}(0) = 0. \quad (2.40a, b)$$

Equations (2.39a,b) and (2.40a,b) are structurally similar to (2.36a,c) and (2.37a,c), respectively, and it is also straightforward to check that \tilde{u}_i and \tilde{b}_i satisfy Squire-transformed versions of (2.33)–(2.35). On the other hand, a comparison immediately reveals that (2.36d) and (2.39c) are compatible only if $DU(0)=0$. Thus, unlike channel problems, the validity of the transformation in free-surface flows depends on the functional form of the steady-state velocity.

In plane Poiseuille flow, the correspondence between three- and two-dimensional modes implies that for the purpose of determining the minimum (critical) Reynolds number for instability it suffices to restrict attention to two-dimensional normal modes. That is it follows from the inequalities $\text{Re}(\tilde{\gamma}) \geq \text{Re}(\gamma)$ and $\tilde{Re} \leq Re$, which are a consequence of (2.38a,b), that to each unstable three-dimensional mode there corresponds a less or equally stable two-dimensional one at smaller or equal Reynolds number. However, in the multiple-parameter problems studied here the question of whether or not the critical mode is two-dimensional depends on the path followed in parameter space as Re is increased. In particular, if the process of increasing the Reynolds number modifies any of the flow parameters that are unchanged by the Squire transformation, the critical mode is not guaranteed to be of vanishing spanwise wavenumber.

The latter observation has been made by Hunt (1966) for channel MHD flows under purely streamwise applied magnetic fields ($B_y = B_z = 0$), where, according to (2.38c), B_x and, equivalently, the Alfvén number $Al = 1/B_x$ are unchanged by the transformation. If Al and Pm are held fixed as the Reynolds number of the three-dimensional problem is increased, then indeed the first mode that becomes unstable has $\beta = 0$. However, if one requires the channel width, the fluid's material properties and the external magnetic field strength all to remain fixed while the flow speed is increased (as was assumed by Hunt), then as Re grows Al necessarily increases as well, and three-dimensional modes may become unstable first.

In the problems with flow-normal external magnetic field ($B'_x = B_y = 0$) studied here, (2.38b,c) implies that the Hartmann number $\tilde{Ha} := \tilde{Pm}^{1/2}\tilde{Re}\tilde{B}_z = Ha$ and the induced magnetic field profile $\tilde{B} := \tilde{B}_x/(\tilde{Pm}^{1/2}\tilde{Ha}) = B$ of the two-dimensional flow are the same as in the three-dimensional case. Since the Hartmann number is independent of the characteristic velocity U_* , this in turn indicates that when channel Hartmann flow is driven at progressively higher speeds with all geometrical and material parameters held fixed (as can be accomplished by means of a pump generating the streamwise pressure gradient Π (2.27)), the critical mode has purely

streamwise wave vector. In free-surface problems, (2.38b) necessitates that Ga and Ca are additionally constrained, but this cannot be accomplished simply by varying U_* with all other aspects of the problem fixed. This is because (i) the capillary number Ca directly depends on U_* , and (ii) the boundary condition (2.23a), in conjunction with (2.27), introduces the parameter interdependence

$$Re = Ga \tan(\theta) \tanh(Ha/2)/Ha \quad \text{or} \quad Re = Ga \tan(\theta)(\text{sech}(Ha) - 1)/Ha^2, \quad (2.41a, b)$$

valid respectively for problems with insulating and perfectly conducting walls. In the expressions above only Re depends on U_* , indicating that the steady-state velocity cannot be changed without modifying at least some of the remaining properties of the flow. An option compatible with (2.38) would be to fix U_* and vary Re by changing the fluid thickness l , the inclination angle θ and the external magnetic field B_z in a manner that Ga and Ha remain constant.

2.6. Two-dimensional normal modes

In the two-dimensional normal-mode formulation, where β , \hat{u}_y , \hat{b}_y and B_y are all set to zero, the divergence-free conditions (2.32d, h) can be used to eliminate the streamwise velocity and magnetic field eigenfunctions, giving

$$\mathbf{u}(\mathbf{r}, t) = \text{Re}((iD\hat{u}(z)/\alpha, 0, \hat{u}(z))e^{i\alpha x + \gamma t}), \quad \mathbf{b}(\mathbf{r}, t) = \text{Re}((iD\hat{b}(z)/\alpha, 0, \hat{b}(z))e^{i\alpha x + \gamma t}) \quad (2.42a, b)$$

for the perturbed velocity and magnetic fields, where we have dropped the z subscript from \hat{u}_z and \hat{b}_z for notational clarity. Substituting (2.42) into (2.32a, c, g) and eliminating the pressure eigenfunction then leads to the coupled OS and induction equations (e.g. Betchov & Criminale 1967; Müller & Bühler 2001),

$$Re^{-1}(D^2 - \alpha^2)^2 \hat{u} - (\gamma + i\alpha U)(D^2 - \alpha^2)\hat{u} + i\alpha(D^2 U)\hat{u} + (i\alpha B_x + B_z D)(D^2 - \alpha^2)\hat{b} - i\alpha(D^2 B_x)\hat{b} = 0 \quad (2.43a)$$

and

$$Rm^{-1}(D^2 - \alpha^2)\hat{b} - (\gamma + i\alpha U)\hat{b} + (i\alpha B_x + B_z D)\hat{u} = 0, \quad (2.43b)$$

respectively.

Whenever applicable, we write

$$\mathbf{b}' = \text{Re}((iD\hat{b}'(z)/\alpha, 0, \hat{b}'(z))e^{i\alpha x + \gamma t}) = -\text{Re}(i\alpha\hat{\psi}(z), 0, D\hat{\psi}(z)e^{i\alpha x + \gamma t}) \quad (2.44)$$

for the external magnetic field perturbation. Laplace's equation (2.32i) for the magnetic potential then becomes $(D^2 - \alpha^2)\hat{\psi} = 0$, which, in conjunction with the condition that $\hat{\psi}$ vanishes at infinity, has the closed-form solutions

$$\hat{\psi}(z) = \begin{cases} \hat{\psi}(0)e^{-\alpha z}, & z > 0, \\ \hat{\psi}(-1)e^{\alpha(z+1)}, & z < -1, \end{cases} \quad \hat{\psi}(z) = \begin{cases} \hat{\psi}(1)e^{-\alpha(z-1)}, & z > 1, \\ \hat{\psi}(-1)e^{\alpha(z+1)}, & z < -1, \end{cases} \quad (2.45a, b)$$

respectively for free-surface and channel problems with insulating walls. If the walls are perfectly conducting, only the expression valid for $z > 0$ is retained in free-surface problems, whereas in channel problems $\hat{\psi}$ is dropped altogether from the formulation.

In inductionless problems, (2.8) substituted into (2.7a) leads to the modified OS equation (Stuart 1954; Lock 1955)

$$(D^2 - \alpha^2)^2 \hat{u} - (i\alpha H_x + H_z D)^2 \hat{u} - Re(\gamma + i\alpha U)(D^2 - \alpha^2)\hat{u} + i\alpha Re(D^2 U)\hat{u} = 0, \quad (2.46)$$

where $H_x := (ReRm)^{1/2}B_x$. Equation (2.46), which replaces the coupled system (2.43), can also be obtained by letting $Pm \searrow 0$ with H_x and H_z fixed. In that limit, the induced magnetic field I_x vanishes (see §2.4), and (2.43b) reduces to

$$(i\alpha B_x + B_z D)(D^2 - \alpha^2)\hat{b} = -Rm(i\alpha B_x + B_z D)\hat{u}, \quad (2.47)$$

leading to (2.46) upon substitution in (2.43a).

As for the boundary conditions, substituting for \hat{u}_x , \hat{b}_x and \hat{p} in the no-slip, kinematic and stress conditions (2.33) and (2.36) by means of (2.32 *c, d, h*), leads to

$$\hat{u}(z_w) = D\hat{u}(z_w) = 0, \quad (2.48a)$$

$$\hat{u}(0) - (\gamma + i\alpha U(0))\hat{a} = 0, \quad D^2\hat{u}(0) + \alpha^2\hat{u}(0) - i\alpha D^2U(0)\hat{a} = 0 \quad (2.48b, c)$$

and

$$\begin{aligned} &(((D^2 - 3\alpha^2)D - Re(\gamma + i\alpha U)D + i\alpha Re(DU))\hat{u})|_{z=0} + Re(B_z(D^2 - \alpha^2) - i\alpha(DB_x))\hat{b}|_{z=0} \\ & - \alpha^2(GaRe^{-1} + \alpha^2Ca^{-1} + ReB_x(0)DB_x(0) - 2i\alpha DU(0))\hat{a} = 0. \end{aligned} \quad (2.48d)$$

Moreover, using (2.45) to eliminate $\hat{\psi}$, the magnetic field boundary conditions at insulating boundaries, (2.34) and (2.37), yield

$$D\hat{b}(\pm 1) \pm \alpha\hat{b}(\pm 1) = 0 \quad (2.49)$$

and

$$D\hat{b}(-1) - \alpha\hat{b}(-1) = 0, \quad D\hat{b}(0) + \alpha\hat{b}(0) - i\alpha DB_x(0)\hat{a} = 0, \quad (2.50a, b)$$

respectively for channel and free-surface problems. If, on the other hand, the walls are perfectly conducting (2.35) leads to

$$\hat{b}(z_w) = 0. \quad (2.51)$$

In inductionless problems, the boundary conditions for \hat{b} are not required, and (2.48d) becomes

$$\begin{aligned} &((D^2 - 3\alpha^2)D - Re(\gamma + i\alpha U)D + i\alpha Re(DU) - H_z(i\alpha H_x + H_z D))\hat{u}|_{z=0} \\ & - \alpha^2(GaRe^{-1} + \alpha^2Ca^{-1} - 2i\alpha DU(0))\hat{a} = 0. \end{aligned} \quad (2.52)$$

To summarize, in both of the free-surface and channel MHD stability problems studied here, the steady-state configuration and the governing differential equations are respectively (2.26) (with z restricted to the appropriate interval and the integration constants set according to the wall conductivity) and (2.43). The boundary conditions for free-surface problems with an insulating wall are (2.48) and (2.50), while if the wall is perfectly conducting (2.51) is enforced in place of (2.50a). In channel problems the boundary conditions are (2.48a) and either (2.49) or (2.51). In inductionless problems, the governing equations are replaced by (2.46); the magnetic field boundary conditions (2.49)–(2.51) are omitted; and (2.48d) is replaced by (2.52).

3. Energy balance

3.1. Formulation for two-dimensional perturbations

Following the analysis by Stuart (1954) and Kelly *et al.* (1989) (for similar considerations applied to shear-driven problems, see Smith & Davis 1982), respectively for channel flows with homogeneous boundary conditions and non-MHD free-surface

flows, we now derive energy-balance relations for normal modes in free-surface MHD with insulating boundary conditions. The resulting formulation will contribute towards a physical interpretation of the results presented in §4 and can also provide consistency checks for numerical schemes (Smith & Davis 1982; Giannakis *et al.* 2009). In order to keep complexity at a minimum, we restrict attention to two-dimensional normal modes, setting the spanwise wavenumber β equal to zero and assigning an arbitrary length L_y to the size of the domain in the y direction. Moreover, we assume that the steady-state velocity and magnetic field profiles satisfy (2.25) subject to the boundary conditions (2.10a), (2.15a), (2.17a) and (2.23b). Similar energy equations apply for the other types of stability problems studied here, but in the interest of brevity, we do not explicitly consider their derivation. In this section we work in Cartesian tensor notation, using u_i , b_i and b'_i to respectively denote the components of \mathbf{u} , \mathbf{b} and \mathbf{b}' in the (x, y, z) coordinate system and ϵ_{ijk} to denote the Levi–Civita symbol. Summation is assumed over repeated tensorial indices.

First, we define the kinetic energy density and the internal magnetic energy density of the perturbations as $\mathcal{E}_u := u_i u_i / 2$ and $\mathcal{E}_b := b_i b_i / 2$, respectively. The integrals of these quantities over the unperturbed fluid domain $\Omega := (0, L_x) \times (0, L_y) \times (-1, 0)$, where $L_x := 2\pi/\alpha$ is the modal wavelength, then yield the total kinetic and internal magnetic energies

$$E_u := \int_{\Omega} dV \mathcal{E}_u, \quad E_{b_i} := \int_{\Omega} dV \mathcal{E}_b, \quad (3.1a, b)$$

where $dV := dx dy dz$. Similarly, the magnetic energy density in the exterior of the fluid, given by $\mathcal{E}_{b'}$:= $b'_i b'_i / 2$, leads to the external magnetic energies

$$E_{b'_-} := \int_{\Omega_-} dV \mathcal{E}_{b'}, \quad E_{b'_+} := \int_{\Omega_+} dV \mathcal{E}_{b'}, \quad E_{b'} := E_{b'_-} + E_{b'_+}, \quad (3.2)$$

where $\Omega_- := (0, L_x) \times (0, L_y) \times (-\infty, -1)$ and $\Omega_+ := (0, L_x) \times (0, L_y) \times (0, \infty)$. We use $E_b := E_{b_i} + E_{b'}$ to denote the total magnetic energy. The two forms of energy associated with the free surface are the potential energy E_p and the surface-tension energy E_{σ} , defined in terms of the corresponding densities (per unit surface) as

$$E_p := \int_{\partial\Omega_s} dS \mathcal{E}_p, \quad E_{\sigma} := \int_{\partial\Omega_s} dS \mathcal{E}_{\sigma}, \quad (3.3)$$

where $\partial\Omega_s := (0, L_x) \times (0, L_y)$, $dS := dx dy$ and

$$\mathcal{E}_p := (\cos(\theta)Fr^{-2} + B_x(0)DB_x(0))a^2/2, \quad \mathcal{E}_{\sigma} := (\partial_x a)^2/(2We). \quad (3.4)$$

We remark that E_p is equal to the work needed to displace the free surface from $z = 0$ to $z = a(x, y, t)$ in the presence of the gravitational field and the flow-normal gradient of the steady-state magnetic pressure. Also, noting that $(1 + (\partial_x a)^2)^{1/2} dx dy = (1 + (\partial_x a)^2/2 + O(a^4)) dx dy$ is the area element on the free surface, \mathcal{E}_{σ} is equal to the work done against surface tension in order to increase the free-surface area from its unperturbed value to that corresponding to the amplitude $a(x, y, t)$. The potential and surface-tension energies make up the total free-surface energy

$$E_a := E_p + E_{\sigma}. \quad (3.5)$$

The time evolution of the energy in the fluid domain follows from the linearized equations (2.7), which, upon elimination of the Lorentz force \mathbf{f} in (2.7a) by means

of (2.7b), read

$$\partial_t u_i = -U_j \partial_j u_i - u_j \partial_j U_i + b_j \partial_j B_i + Re^{-1} \Delta u_i + B_j \partial_j b_i - \partial_i p, \quad (3.6a)$$

$$j_i = Rm^{-1} \epsilon_{ijk} \partial_j b_k = e_i + \epsilon_{ijk} U_j b_k + \epsilon_{ijk} u_j B_k, \quad (3.6b)$$

$$\partial_t b_i = -U_j \partial_j b_i + b_j \partial_j U_i - u_j \partial_j B_i + Rm^{-1} \Delta b_i + B_j \partial_j u_i, \quad (3.6c)$$

$$\partial_i u_i = 0, \quad \partial_i b_i = 0. \quad (3.6d, e)$$

In particular, forming the contraction of (3.6a) with u_i and the contraction of (3.6b) with b_i , and adding the results together, leads to the energy equation

$$\partial_t (\mathcal{E}_u + \mathcal{E}_b) = g_R + g_M + g_J + g_v + g_\eta + \partial_i (-q_i^{(\mathcal{E})} + q_i^{(em)} + q_i^{(mech)}), \quad (3.7)$$

where

$$g_R := -u_i u_j \partial_j U_i, \quad g_M := b_i b_j \partial_j U_i, \quad g_J := u_i u_j (\partial_j B_i - \partial_i B_j), \quad (3.8a-c)$$

$$g_v := -s_{ij} s_{ij} / (2Re), \quad g_\eta := -Rm j_i j_i, \quad (3.8d, e)$$

with $s_{ij} := \partial_i u_j + \partial_j u_i$ and

$$q_i^{(\mathcal{E})} := U_i (\mathcal{E}_u + \mathcal{E}_b), \quad q_i^{(em)} := \epsilon_{ijk} b_j (e_k + \epsilon_{klm} U_l b_m), \quad (3.9a, b)$$

$$q_i^{(mech)} := u_j (-p - p_b) \delta_{ij} + Re^{-1} s_{ij}, \quad p_b := B_i b_i. \quad (3.9c, d)$$

We remark that in deriving (3.7) we have used the divergence-free conditions (2.7e, f) (as well as the corresponding ones for U_i and B_i) and the relations

$$u_i \Delta u_i = \partial_i (u_j s_{ij}) - s_{ij} s_{ij} / 2, \quad Rm^{-1} b_i \Delta b_i = \partial_i (\epsilon_{ijk} b_j j_k) - Rm j_i j_i. \quad (3.10)$$

In a similar manner, Faraday's law $\partial_t b'_i = -\epsilon_{ijk} \partial_j e'_k$, governing b'_i and the external electric field e'_i , in conjunction with the curl-free property $\epsilon_{ijk} \partial_j b'_k = 0$ (this holds due to the insulating nature of the medium surrounding the fluid) yields the energy equation

$$\partial_t \mathcal{E}_{b'} = \epsilon_{ijk} \partial_i (b'_j e'_k) \quad (3.11)$$

for the external magnetic energy density. As for the surface energies (3.4), multiplying the kinematic boundary condition (2.18) by the free-surface amplitude a and suitable constants leads to the rate equations

$$\partial_t \mathcal{E}_g = -U(0) \partial_x \mathcal{E}_g + (\cos(\theta) Fr^{-2} + B_x(0) DB_x(0)) a u_z|_{z=0}, \quad (3.12a)$$

$$\partial_t \mathcal{E}_\sigma = -U(0) \partial_x \mathcal{E}_\sigma + (\partial_x (u_z|_{z=0} \partial_x a) - u_z|_{z=0} \partial_x^2 a) / We. \quad (3.12b)$$

Each of the terms on the right-hand side of (3.7) has a physical interpretation. First, the source terms g_R and g_M are respectively the energy transfer rates between the basic flow and the velocity and magnetic field perturbations, i.e. the energy transfer rates associated with the Reynolds and Maxwell stresses. Physically, g_R is an outcome of the mechanical exchange of energy occurring as the velocity perturbations transport mass within the non-uniform steady-state velocity field. In contrast, the energy transfer mechanism corresponding to g_M is electromagnetic in nature. Its origin lies in the stretching/shrinking of the perturbed magnetic field \mathbf{b} by the basic flow. Also, noting that $\partial_j B_i - \partial_i B_j = Rm \epsilon_{jik} J_k$, where $J_k := Rm^{-1} \epsilon_{klm} \partial_l B_m$ is the steady-state current, g_J is interpreted as the rate of work done on the fluid by the Lorentz force associated with the basic current, the so-called current interaction, while g_v and g_η are the viscous and resistive dissipation terms. Among the fluxes $\{q_i^{(\mathcal{E})}, q_i^{(em)}, q_i^{(mech)}\}$, $q_i^{(\mathcal{E})}$ is the perturbation energy transported by the basic flow; $q_i^{(em)}$ is the electromagnetic

energy flux, evaluated in the rest frame of the unperturbed fluid (recall that in the non-relativistic limit the electric field perturbation in the rest frame of the unperturbed fluid is $\mathbf{e} + \mathbf{U} \times \mathbf{b}$); and $q_i^{(mech)}$ is the momentum flux due to mechanical stresses acting on the fluid.

We derive a global version of the above energy equations by integrating (3.7) over Ω and making use of the divergence theorem to reduce the volume integrals of $q_i^{(\mathcal{E})}$, $q_i^{(em)}$ and $q_i^{(mech)}$ to surface integrals. To begin, a consequence of the assumed periodicity in x is that $\int_{\Omega} dV \partial_i q_i^{(\mathcal{E})}$ vanishes and that the surface energies (3.3) obey

$$\partial_t E_p = \int_{\partial\Omega_s} dS (\cos(\theta) Fr^{-2} + B_x(0) DB_x(0)) a u_z|_{z=0}, \quad (3.13a)$$

$$\partial_t E_\sigma = - \int_{\partial\Omega_s} dS We^{-1} \partial_x^2 a u_z|_{z=0}. \quad (3.13b)$$

Also, integrating (3.11) over $\Omega_- \cup \Omega_+$, and using the magnetic field boundary conditions (2.11) and (2.16), leads to

$$\partial_t E_{b'} = - \int_{\Omega} dV \partial_i q_i^{(em)} - DB_x(0) \int_{\partial\Omega_s} dS a e_y|_{z=0} - U(0) \int_{\partial\Omega_s} dS (b_x b_z)|_{z=0}, \quad (3.14)$$

while the relation

$$\partial_t (E_p + E_\sigma) = - \int_{\Omega} dV \partial_i q_i^{(mech)} - \frac{D^2 U(0)}{Re} \int_{\partial\Omega_s} dS a u_x|_{z=0} \quad (3.15)$$

follows from the stress boundary conditions (2.24). Then, integrating (3.7), and eliminating $q_i^{(em)}$ and $q_i^{(mech)}$ by means of (3.14) and (3.15), we arrive at the conservation equation

$$\partial_t E = G_R + G_M + G_J + G_v + G_\eta + G_{av} + G_{aJ} \quad (3.16)$$

for the total energy $E := E_u + E_{bi} + E_{b'} + E_p + E_\sigma$. Here the volume terms

$$\left. \begin{aligned} G_R &:= \int_{\Omega} dV g_R, & G_M &:= \int_{\Omega} dV g_M, & G_J &:= \int_{\Omega} dV g_J, \\ G_v &:= \int_{\Omega} dV g_v, & G_\eta &:= \int_{\Omega} dV g_\eta \end{aligned} \right\} \quad (3.17)$$

are energy transfer rates respectively associated with the Reynolds stress, Maxwell stress, current interaction, viscous dissipation and resistive dissipation. Moreover, the surface terms

$$G_{aU} := - \frac{D^2 U(0)}{Re} \int_{\partial\Omega_s} dS a u_x|_{z=0}, \quad (3.18a)$$

$$G_{aJ} := -Rm J_y(0) \int_{\partial\Omega_s} dS a (j_y - (B_x u_z - B_z u_x))|_{z=0} \quad (3.18b)$$

represent the energy transferred to the free surface by viscous and electromagnetic forces, respectively. In particular, noting that $B_x u_z - B_z u_x$ is the current induced by the velocity field perturbations within the steady-state magnetic field, the quantity $j_y - (B_x u_z - B_z u_x)$ in (3.18b) can be interpreted as the current induced by the steady-state fluid motion within the perturbed magnetic field (Hunt 1966).

3.2. Energy balance for two-dimensional normal modes

The results of the preceding section can be applied to the special case of the two-dimensional normal mode solutions. First, the expressions

$$E_u = Le^{2\Gamma t} \int_{-1}^0 dz \hat{E}_u(z), \quad E_{bi} = Le^{2\Gamma t} \int_{-1}^0 dz \hat{E}_b(z) \quad (3.19)$$

follow by substituting for u_i and b_i in (3.1) using (2.42), where $L := L_x L_y / 4\alpha^2$ is a constant and

$$\hat{E}_u := |D\hat{u}|^2 + \alpha^2 |\hat{u}|^2, \quad \hat{E}_b := |D\hat{b}|^2 + \alpha^2 |\hat{b}|^2 \quad (3.20)$$

are the modal kinetic and magnetic energy densities, averaged over the streamwise and spanwise directions. The external magnetic energy E'_b (3.2) can be computed in terms of the internal magnetic field using the solution (2.45a) for $\hat{\psi}$ to evaluate the integral over z and the insulating boundary conditions (2.34) and (2.37) to substitute for the magnetic potential at the fluid domain boundaries. Specifically, we have

$$E'_b = Le^{2\Gamma t} \left(\int_{-\infty}^{-1} dz + \int_0^{\infty} dz \right) (|D\hat{b}'(z)|^2 + \alpha^2 |\hat{b}'(z)|^2) = Le^{2\Gamma t} \alpha (|\hat{b}(-1)|^2 + |\hat{b}(0)|^2). \quad (3.21)$$

In addition, the normal-mode solution (2.31) (with $\beta = 0$) for the free-surface displacement in conjunction with (3.3) yields

$$E_p = Le^{2\Gamma t} \alpha^2 (\cos(\theta) Fr^{-2} + B_x(0) DB_x(0)) |\hat{a}|^2, \quad E_\sigma = Le^{2\Gamma t} \alpha^4 We^{-1} |\hat{a}|^2. \quad (3.22)$$

We treat the source terms on the right-hand side of (3.16) in a similar manner. The volume terms (3.17) become

$$\left. \begin{aligned} G_R &= Le^{2\Gamma t} \int_{-1}^0 dz \hat{g}_R(z), & G_M &= Le^{2\Gamma t} \int_{-1}^0 dz \hat{g}_M(z), \\ G_J &= Le^{2\Gamma t} \int_{-1}^0 dz \hat{g}_J(z), & G_v &= Le^{2\Gamma t} \int_{-1}^0 dz \hat{g}_v(z), & G_\eta &= Le^{2\Gamma t} \int_{-1}^0 dz \hat{g}_\eta(z), \end{aligned} \right\} \quad (3.23)$$

where

$$\hat{g}_R := 2\alpha(DU)\text{Im}(\hat{u}^* D\hat{u}), \quad \hat{g}_M := -2\alpha(DU)\text{Im}(\hat{b}^* D\hat{b}), \quad (3.24a, b)$$

$$\hat{g}_J := 2\alpha DB_x \text{Im}(\hat{u}^* D\hat{b} - \hat{b}^* D\hat{u}), \quad (3.24c)$$

$$\hat{g}_v := -Re^{-1} (|D^2 \hat{u}|^2 - 2\alpha^2 \text{Re}(\hat{u}^* D^2 \hat{u}) + \alpha^4 |\hat{u}|^2), \quad (3.24d)$$

$$\hat{g}_\eta := -Rm^{-1} (|D^2 \hat{b}|^2 - 2\alpha^2 \text{Re}(\hat{b}^* D^2 \hat{b}) + \alpha^4 |\hat{b}|^2). \quad (3.24e)$$

Moreover, the surface terms (3.18) equate to

$$G_{aU} = -Le^{2\Gamma t} 2\alpha Re^{-1} D^2 U(0) \text{Im}(\hat{a} D\hat{u}^*(0)), \quad (3.25a)$$

$$\begin{aligned} G_{aJ} &= Le^{2\Gamma t} 2\alpha (J_y(0) \text{Im}((D^2 \hat{b}(0) - \alpha^2 \hat{b}(0)) \hat{a}^*) \\ &\quad - B_z DB_x(0) \text{Im}(\hat{a} D\hat{u}^*(0)) + \alpha B_x(0) DB_x(0) \text{Re}(\hat{a} \hat{u}^*(0))). \end{aligned} \quad (3.25b)$$

Finally, noting that the energy growth rate of the normal-mode solutions (2.31) and (2.42) satisfies $\partial_t E = 2\Gamma E$ and inserting (3.24) and (3.25) into (3.16), we obtain

$$\Gamma = \Gamma_R + \Gamma_M + \Gamma_J + \Gamma_\eta + \Gamma_v + \Gamma_{aU} + \Gamma_{aJ}, \quad (3.26)$$

where $\Gamma_{[\cdot]} := G_{[\cdot]}/2E$.

Equation (3.26) expresses the modal growth rate as a sum of contributions from the various MHD energy generation and dissipation mechanisms. In the ensuing discussion, we oftentimes aggregate the terms on its right-hand side, writing $\Gamma = \Gamma_{mech} + \Gamma_{em}$, where

$$\Gamma_{mech} := \Gamma_R + \Gamma_{aU} + \Gamma_J + \Gamma_v, \quad \Gamma_{em} := \Gamma_M + \Gamma_{aJ} + \Gamma_\eta \quad (3.27a, b)$$

represent the net mechanical and electromagnetic contributions to Γ , respectively. Moreover, we introduce normalized versions of the energy transfer densities (3.24), writing $\hat{\Gamma}_{[\cdot]}(z) := L\hat{g}_{[\cdot]}(z)/(2E)|_{t=0}$ for each of the source terms in (3.24), which gives $\int_{-1}^0 dz \hat{\Gamma}_{[\cdot]}(z) = \Gamma_{[\cdot]}$. We also note that the corresponding energy transfer decomposition for inductionless problems can be obtained from (3.26) by formally setting the magnetic field energies, E_{bi} and E'_b , the Maxwell stress term Γ_M and the magnetic field gradient DB_x to zero and, as follows from (2.47), replacing (3.24e) with

$$\hat{g}_\eta = -Re^{-1}(H_z^2|D\hat{u}|^2 + 2\alpha H_x H_z \text{Im}(\hat{u}^* D\hat{u}) + \alpha^2 H_x^2 |\hat{u}|^2). \quad (3.28)$$

4. Results and discussion

We now investigate the stability properties of the models established in §2, restricting attention to two-dimensional problems with a purely flow-normal external magnetic field (i.e. $H_x = 0$ and $H_z = Ha$) and magnetic Prandtl number no greater than 10^{-4} (including the inductionless limit $Pm \searrow 0$). Albeit small, the chosen upper boundary for Pm encompasses all known conducting laboratory and industrial fluids. Our focus will be on the stability of travelling gravity and Alfvén waves, neither of which are present in channel Hartmann flow. In addition, the behaviour of the hard instability mode, which is the free-surface analogue of the even unstable mode in channel problems (Takashima 1996), will be examined. All numerical work was carried out using a spectral Galerkin method for the coupled OS and induction equations for free-surface MHD (Giannakis *et al.* 2009).

Following a review of non-MHD free-surface flow in §4.1, we consider in §4.2 inductionless problems and then in §4.3 flows at non-zero Pm . In the interest of commonality with the literature for channel Hartmann flow, we frequently use the complex phase velocity $c := i\gamma/\alpha = C + i\Gamma/\alpha$, where C and Γ are respectively the modal phase velocity and growth rate, in place of the complex growth rate γ . The complex phase velocity will also be employed whenever reference is made to neutral-stability curves in the (Re, α) plane. In particular, we consider these curves to be the loci $\text{Im}(c(Re, \alpha)) = 0$, a definition that does not necessarily agree on the $\alpha = 0$ axis with the equivalent one, $\text{Re}(\gamma(Re, \alpha)) = 0$, in terms of γ (see §4.3.1). We denote throughout the critical Reynolds number for the onset of instability and the wavenumber and phase velocity of the critical mode by Re_c , α_c and C_c , respectively.

Motivated by the discussion of the Squire transformation in §2.5, we have opted to perform our analysis using the parameter set $\{\alpha, Re, Pm, Ha, Ga, Ca\}$, rather than, say, parameterizing gravity by means of the Froude number Fr and the inclination angle θ and surface tension by means of the Weber number We . In particular, all ensuing calculations in which Re is varied (namely eigenvalue contours in the (Re, α) plane and critical-Reynolds-number calculations) are performed at constant $\{Pm, Ha, Ga, Ca\}$, as under that condition the onset of instability is governed by two-dimensional ($\beta = \hat{u}_y = \hat{b}_y = 0$) modes. Computing eigenvalue contours at constant Ha and, where applicable, Pm is also the conventional choice in the literature for channel Hartmann flow (e.g. Lock 1955; Potter & Kutchev 1973; Takashima 1996).

However, in free-surface flow these calculations are typically performed at fixed inclination angle (Yih 1963; Hsieh 1965; Lin 1967; Gupta & Rai 1968; Yih 1969; De Bruin 1974; Lam & Bayazitoglu 1986; Floryan *et al.* 1987; Kelly *et al.* 1989), rather than fixed Ga . Yet, as follows from (2.41), as long as $ReHa/\tanh(Ha/2) \ll Ga$ or $ReHa^2/(\text{sech}(Ha) - 1) \ll Ga$, respectively for insulating and conducting lower wall, θ remains small, which is the case for several of the calculations presented here. Among the various dimensionless groups associated with surface tension, our capillary number Ca is equivalent to the parameter $S' = 3/(2Ca)$ employed by Yih (1963), whereas, for instance, Lu & Sarma (1967) and Kelly *et al.* (1989) use We , while Smith & Davis (1982), Lam & Bayazitoglu (1986) and Floryan *et al.* (1987) respectively use $S = Re/Ca$, $S_t = 1/We = 1/(ReCa)$ and $\zeta = 3^{1/3}(Ga/\cos(\theta))^{2/3} \sin(\theta)/(2Ca)$.

Unless otherwise stated, we set $Ga = 8.3 \times 10^7$, which for a typical liquid metal with kinematic viscosity $\nu = 3 \times 10^{-7} \text{ m}^2 \text{ s}^{-1}$ in a $g = 9.81 \text{ m s}^{-2}$ gravitational field corresponds to $l^3 \cos(\theta) \simeq (0.01 \text{ m})^3$. Taking $\lambda = 3 \times 10^{-6} \Omega^{-1} \text{ m}^{-1}$ to be a characteristic value of the fluid's electrical conductivity (Nornberg *et al.* 2008) then leads to the estimate $\tan(\theta) \simeq 5 \times 10^{-7} Re(B_*/1 \text{ kG})(l/1 \text{ cm})$ for the inclination angle (2.41a) in insulating-wall problems, expressed in terms of a dimensional applied magnetic field B_* and fluid thickness l meeting the condition $\tanh(Ha/2) = \tanh(B_*l(\lambda/\mu)^{1/2}/2) \approx 1$. Noting that with the above choices of μ and λ , together with $l = 1 \text{ cm}$ and $B_* = 1 \text{ kG}$, the Hartmann number is roughly 50 (i.e. $\tanh(Ha/2) \approx 1$), it follows that in flows with an insulating wall involving centimetre-thick liquid-metal films and kilogauss-sized magnetic fields (studied experimentally by Alpher *et al.* 1960; Ji *et al.* 2005; Nornberg *et al.* 2008), the inclination angle remains small ($\theta \lesssim 1^\circ$) up to Reynolds numbers of order 10^4 . On the other hand, flows with a perfectly conducting wall require substantially larger inclination angles in order to be driven under strong applied fields because, as follows from (2.41b), in this case $\tan(\theta)$ increases exponentially with B_* for $Ha \gtrsim 1$. However, it is questionable whether this regime is practically realizable, given the magnitude of the induced current J_y (see §2.4) and the associated heat load on the fluid.

Capillary effects are of minor importance for the instabilities we wish to explore (cf. Lu & Sarma 1967, who studied MHD gravity–capillary waves), but we nominally work at $Ca = 0.07$, which is the capillary number computed for dynamic viscosity $\mu = 1.5 \times 10^{-3} \text{ N s m}^{-2}$ and surface-tension coefficient $\sigma = 0.1 \text{ N m}^{-1}$ (both of which are typical liquid-metal values), assuming a velocity scale $U_* = 4.7 \text{ m s}^{-1}$.

4.1. Non-MHD flow

Our baseline scenario is non-MHD parallel flow down an inclined plane with the parabolic velocity profile $U(z) = 1 - z^2$. As shown in the spectrum in figure 3 and table 1, evaluated at $Re = 7 \times 10^5$ and $\alpha = 2 \times 10^{-3}$, the eigenvalues form the characteristic three-branch structure in the complex plane encountered in plane Poiseuille flow (Mack 1976; Dongarra, Straughan & Walker 1996; Kirchner 2000; Melenk *et al.* 2000), with the difference that because they lack reflection symmetry with respect to z , the modes do not arise as symmetric–antisymmetric pairs. Following standard nomenclature (Mack 1976), we label the branches A, P and S, where $0 < \text{Re}(c) < \langle U \rangle = 2/3$ and $\langle U \rangle < \text{Re}(c) < 1$, respectively for modes in the A and P families, while S modes have $C = \langle U \rangle$, asymptotically as $\text{Im}(c) \rightarrow -\infty$ (Grosch & Salwen 1964). Among the A, P and S modes, only the ones at the top end of the spectrum carry appreciable surface energy. For instance, in table 1, E_a/E drops from 0.00652 for mode P_1 to $O(10^{-7})$ for mode S_2 .

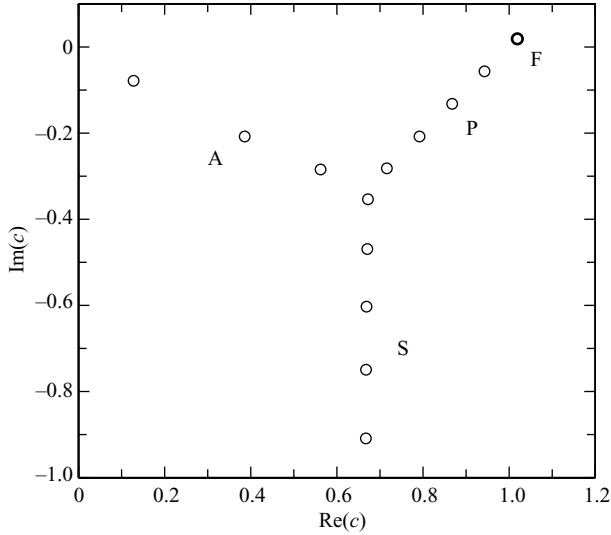


FIGURE 3. Eigenvalues for non-MHD free-surface flow at $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-3}$, $Ga = 8.3 \times 10^7$ and $Ca = 0.07$, showing the A, P and S branches on the complex- c plane. Mode F, represented by a boldface marker, is unstable and has growth rate $\Gamma = \alpha \text{Im}(c) = 3.7447 \times 10^{-5}$ and energy transfer rates (the terms on the right-hand side of (3.26) with $\Gamma_M, \Gamma_J, \Gamma_\eta$ and Γ_{aJ} set to zero) $\Gamma_R = -7.7875 \times 10^{-6}$, $\Gamma_v = -1.1048 \times 10^{-4}$ and $\Gamma_{aU} = 1.5572 \times 10^{-4}$.

		c	E_a/E
1	F	$1.019322365642126 \times 10^0 + 1.872373565774912 \times 10^{-2} i$	3.81670×10^{-2}
2	P ₁	$9.430932551528158 \times 10^{-1} - 5.660800610069469 \times 10^{-2} i$	6.52344×10^{-3}
3	A ₁	$1.280197187921976 \times 10^{-1} - 7.844228782612407 \times 10^{-2} i$	1.61245×10^{-4}
4	P ₂	$8.676593690519436 \times 10^{-1} - 1.322655312947944 \times 10^{-1} i$	6.09230×10^{-4}
5	P ₃	$7.920814474574365 \times 10^{-1} - 2.078761371940656 \times 10^{-1} i$	1.14211×10^{-4}
6	A ₂	$3.862388506852979 \times 10^{-1} - 2.079139567980078 \times 10^{-1} i$	1.41771×10^{-4}
7	P ₄	$7.161372374734705 \times 10^{-1} - 2.819337921185398 \times 10^{-1} i$	2.31032×10^{-5}
8	A ₃	$5.621911688341056 \times 10^{-1} - 2.845782600055865 \times 10^{-1} i$	3.99770×10^{-5}
9	S ₁	$6.724206086971892 \times 10^{-1} - 3.536832210862633 \times 10^{-1} i$	3.85934×10^{-6}
10	S ₂	$6.706989371744410 \times 10^{-1} - 4.693930705398125 \times 10^{-1} i$	1.01726×10^{-7}

TABLE 1. Complex phase velocity c and free-surface energy E_a (normalized by the total modal energy $E = E_u + E_a$) of the 10 least stable modes of the spectrum in figure 3. The modes are tabulated in order of decreasing $\text{Im}(c)$ and labelled A_{*i*}, P_{*i*}, S_{*i*}, or F according to their family, where i denotes the rank, again in order of decreasing $\text{Im}(c)$, within a given family.

In addition to the above shear modes, the depicted free-surface spectrum contains an unstable surface mode, denoted by F, which propagates downstream with phase velocity greater than the steady-state velocity at the free surface (i.e. $\text{Re}(c) > 1$). This so-called soft instability is driven by viscous stresses acting on the free surface (Yih 1963; Kelly *et al.* 1989). In the notation of § 3, the corresponding energy transfer rate $\Gamma_{aU} > |\Gamma_v + \Gamma_R|$ to mode F exceeds the net rate of energy dissipated through viscous and Reynolds stresses (see also Kelly *et al.* 1989), resulting in a positive growth rate $\Gamma = \Gamma_{aU} + \Gamma_v + \Gamma_R$.

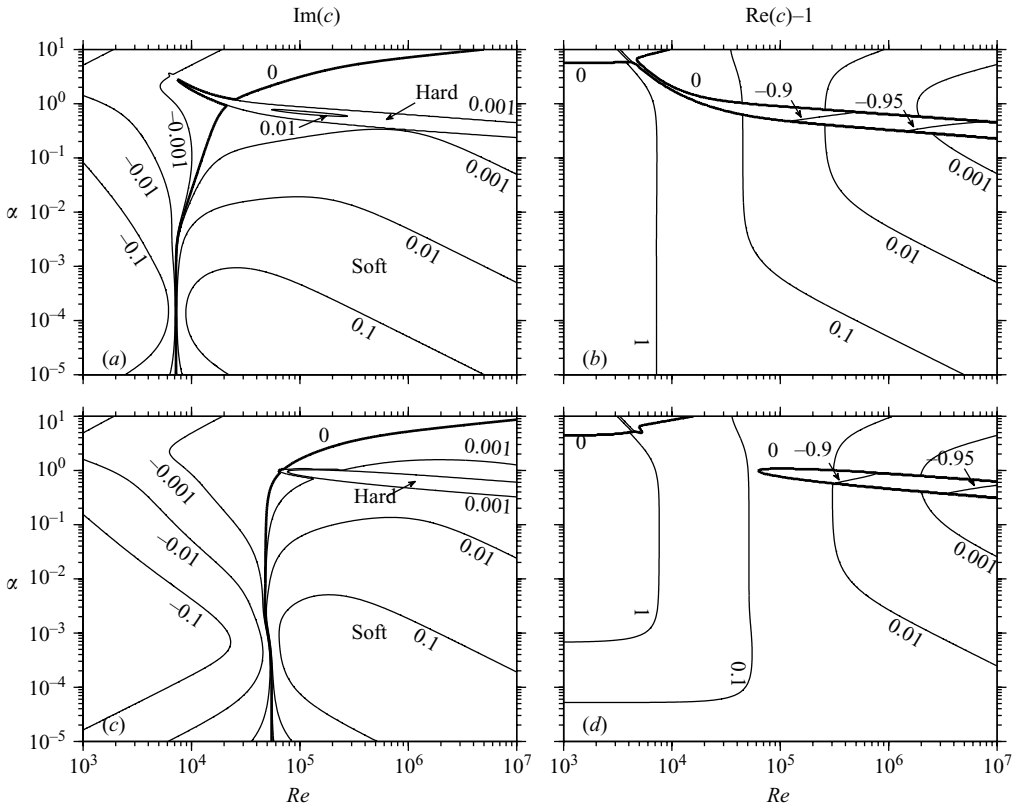


FIGURE 4. (a,c) Imaginary and (b,d) real parts of the complex phase velocity c of the least stable mode in the (Re, α) plane, computed at constant Galilei and capillary numbers $Ga = 8.3 \times 10^7$ and $Ca = 0.07$, (a,b) for non-MHD free-surface flow and (c,d) inductionless free-surface Hartmann flow with $Ha = 3$. The regions of instability for the soft and hard modes, indicated in (a) and (c), are distinguishable by the corresponding phase velocity $Re(c)$, which exceeds unity in the case of the soft mode, but is less than the mean steady-state speed $\langle U \rangle$ for the hard mode. In (a,b) and (c,d), $\langle U \rangle$ is equal to $2/3$ and 0.742 , respectively.

Besides mode F, whenever the speed of propagation of surface waves in the absence of a basic flow is large compared to the steady-state velocity, the spectrum also contains an upstream-propagating ($Re(c) < 0$) surface mode (e.g. figure 4 in Giannakis *et al.* 2009). As Re grows, that mode joins the A branch and eventually becomes unstable. The latter instability, oftentimes referred to as the ‘hard instability’ (Lin 1967; De Bruin 1974; Floryan *et al.* 1987), is the free-surface analogue of the Tollmien–Schlichting wave in plane Poiseuille flow (Lin 1944); i.e. it is caused by positive Reynolds stress associated with a critical layer that develops for suitable values of the mode’s phase velocity.

As shown in figure 4(a), the growth-rate contours of the hard mode in the (Re, α) plane are qualitatively similar to those of the unstable mode in channel flow (Shen 1954). In fact, if gravitational and surface-tension forces are decreased to zero the critical parameters of the hard mode approach the $(Re_c, \alpha_c, C_c) = (5772.2, 1.021, 0.264)$ values computed for plane Poiseuille flow (Orszag 1971), revealing their common nature. Increasing Ga results in the instability region extending to progressively larger wavenumbers (see e.g. the $Ha = 0$ results in table 2),

Ha	Re_c	α_c	C_c
$Ga = 8.3 \times 10^6$			
0	3.7113036×10^3	1.87198×10^0	2.49413×10^{-1}
0.5	4.5019913×10^3	1.59323×10^0	2.48917×10^{-1}
1	8.5959446×10^3	1.13443×10^0	2.34231×10^{-1}
2	2.8176098×10^4	9.41259×10^{-1}	1.92059×10^{-1}
5	1.6404990×10^5	1.13450×10^0	1.56426×10^{-1}
10	4.3981065×10^5	1.73916×10^0	1.54789×10^{-1}
20	9.6176655×10^5	3.23761×10^0	1.55011×10^{-1}
50	2.4155501×10^6	8.07657×10^0	1.55029×10^{-1}
100	4.8311017×10^6	1.61537×10^1	1.55030×10^{-1}
$Ga = 8.3 \times 10^7$			
0	7.3610164×10^3	2.81462×10^0	1.84251×10^{-1}
0.5	7.4343292×10^3	2.77817×10^0	1.85689×10^{-1}
1	7.7154319×10^3	2.64647×10^0	1.89974×10^{-1}
2	2.3929863×10^4	1.10416×10^0	1.91208×10^{-1}
5	1.6378495×10^5	1.13615×10^0	1.56420×10^{-1}
10	4.3979016×10^5	1.73922×10^0	1.54788×10^{-1}
20	9.6176624×10^5	3.23764×10^0	1.55011×10^{-1}
50	2.4155501×10^6	8.07657×10^0	1.55029×10^{-1}
100	4.8311017×10^6	1.61537×10^1	1.55030×10^{-1}
$Ga = 8.3 \times 10^8$			
0	1.9476764×10^4	3.30597×10^0	1.33088×10^{-1}
0.5	1.9531440×10^4	3.29373×10^0	1.34239×10^{-1}
1	1.9704003×10^4	3.25532×10^0	1.37611×10^{-1}
2	2.0605875×10^4	3.06079×10^0	1.50076×10^{-1}
5	1.6107058×10^5	1.15339×10^0	1.56349×10^{-1}
10	4.3958470×10^5	1.73985×10^0	1.54786×10^{-1}
20	9.6176320×10^5	3.23764×10^0	1.55011×10^{-1}
50	2.4155501×10^6	8.07657×10^0	1.55029×10^{-1}
100	4.8311017×10^6	1.61537×10^1	1.55030×10^{-1}

TABLE 2. Critical Reynolds number Re_c , wavenumber α_c and phase velocity C_c of the hard mode in inductionless free-surface Hartmann flow, computed for Galilei number $Ga/(8.3 \times 10^7) \in \{0.1, 1, 10\}$, capillary number $Ca = 0.07$ and representative values of the Hartmann number Ha in the interval $[0, 100]$.

where the upper and lower branches of the neutral-stability curve $\text{Im}(c) = 0$ intersect in a cusp-like manner. However, the hard mode's critical Reynolds number does not vary monotonically with the strength of the flow-normal gravitational force (De Bruin 1974; Floryan *et al.* 1987). In particular, for the $Ca = 0.07$ capillary number used here, Re_c decreases with $Ga \lesssim 10^7$ (e.g. in table 2, Re_c drops to 3711.3 for $Ga = 8.3 \times 10^6$) but becomes an increasing function of the Galilei number for sufficiently strong gravitational fields, eventually exceeding the corresponding critical Reynolds number for channel flow. For instance, in figure 4(a) the hard mode's critical parameters are $(Re_c, \alpha_c, C_c) = (7361.0, 2.815, 0.184)$.

As for the soft mode, it is evident from the structure of the $\text{Im}(c) = 0$ contour in figure 4(a), which runs parallel to the $\log(\alpha)$ axis for $\alpha \ll 1$, that its region of instability in the (Re, α) plane extends to arbitrarily small wavenumbers. This makes the soft mode amenable to study using regular perturbation theory for large wavelengths ($\alpha \searrow 0$), when, in contrast, an analytic treatment of the hard mode would require

the full machinery of singular asymptotic expansions (e.g. Drazin & Reid 2004). In particular, Yih (1963) has established that the lower branch of the soft mode's neutral-stability curve is the $\alpha = 0$ axis and, further, that its upper branch, shown in figure 4(a), emanates from a bifurcation point located at $(Re_b, 0) = ((5Ga/8)^{1/2}, 0)$, with corresponding phase velocity $C_b = 2$ (see also §A.1 of the Appendix).

As a check on the proximity of the bifurcation point $(Re_b, 0)$ to the critical point (Re_c, α_c) of the soft mode for the problem in figure 4(a), which is strongly suggested by the direction of the $\text{Im}(c) = 0$ contour for $\alpha \ll 1$, we have numerically computed the minimum Reynolds number Re_m for instability at fixed $\alpha = 10^{-5}$. The $Re_m = 7202.4298$ numerical result is very close to the analytically determined value $Re_b = 7202.4301$ for the Reynolds number at the bifurcation point, as was also observed in a number of calculations with $Ga \in [10^3, 10^9]$. Still, for our reference problem with $(Ga, Ca) = (8.3 \times 10^7, 0.07)$, Re_m is smaller than the corresponding Re_b by an amount of order 10^{-8} , which in all likelihood is not due to numerics (e.g. the discrepancy did not disappear by increasing the polynomial degree of the discretization scheme). This observation is consistent with a fourth-order asymptotic result that for any capillary number Ca there exists a lower bound in Ga above which $dRe/d\alpha$ is negative on the $\text{Im}(c) = 0$ contour, in the neighbourhood of the bifurcation point (see §A.1.3 of the Appendix). For $Ca = 0.07$ that lower bound amounts to $Ga \approx 3.13 \times 10^5$, indicating that for the problem in figure 4(a), $\alpha_c = 0$ is not an exact statement. However, we expect the smallness of α_c to render any unstable modes with $Re < Re_b$ irrelevant in a laboratory context, even if the true critical Reynolds number were to deviate significantly from Re_b .

4.2. Inductionless free-surface Hartmann flow

In inductionless Hartmann flow the magnetic field is treated as a background variable, unaffected by the motion of the fluid. However, it influences normal-mode stability on one hand by modifying the steady-state velocity profile (2.26a), therefore altering the energy transfer to the perturbations mediated by viscosity (represented by the terms Γ_R and Γ_{aU} in (3.26)), and on the other hand by means of the Lorentz force (2.7b), whose only non-zero component $f_x := -Ha^2 Re^{-1} u_x$ is streamwise. The latter has a direct dissipative effect associated with resistivity (the energy transfer rate Γ_η) but may also indirectly affect Γ_R , Γ_{aU} and the viscous-dissipation rate Γ_v by modifying the perturbed velocity field. In free-surface problems, as is the case with their fixed-boundary counterparts (Lock 1955; Potter & Kutchev 1973; Takashima 1996), the combined outcome of the flow-normal external magnetic field is to suppress instabilities (Hsieh 1965; Ladikov 1966; Gupta & Rai 1968). In fact, even moderate Hartmann numbers ($Ha \sim 3$) are sufficient to shift the onset of the soft and hard instabilities to Reynolds numbers significantly higher than in non-MHD flows, in the manner illustrated by the eigenvalue contour plots in figure 4(c).

The critical Reynolds number, wavenumber and phase velocity of the hard mode, computed numerically in figure 5 as a function of the Hartmann number $Ha \in [0.1, 200]$ for representative values of the Galilei number $Ga/(8.3 \times 10^7) \in \{0.1, 1, 10\}$, exhibit two distinct types of behaviour, depending on the relative strength of the gravitational and Lorentz forces. The first of these occurs when the Lorentz force is weak compared to gravity (e.g. the $Ga = 8.3 \times 10^8$ example in figure 5 for $Ha \lesssim 2$) and is characterized by small variation of the critical parameters with Ha . As observed in the (Re, α) plane, the main influence of the applied field in this regime is to reduce the wavenumber bandwidth of the cusp-like tip of the hard mode's instability region, with little change in the position (Re_c, α_c) of the intersection point between

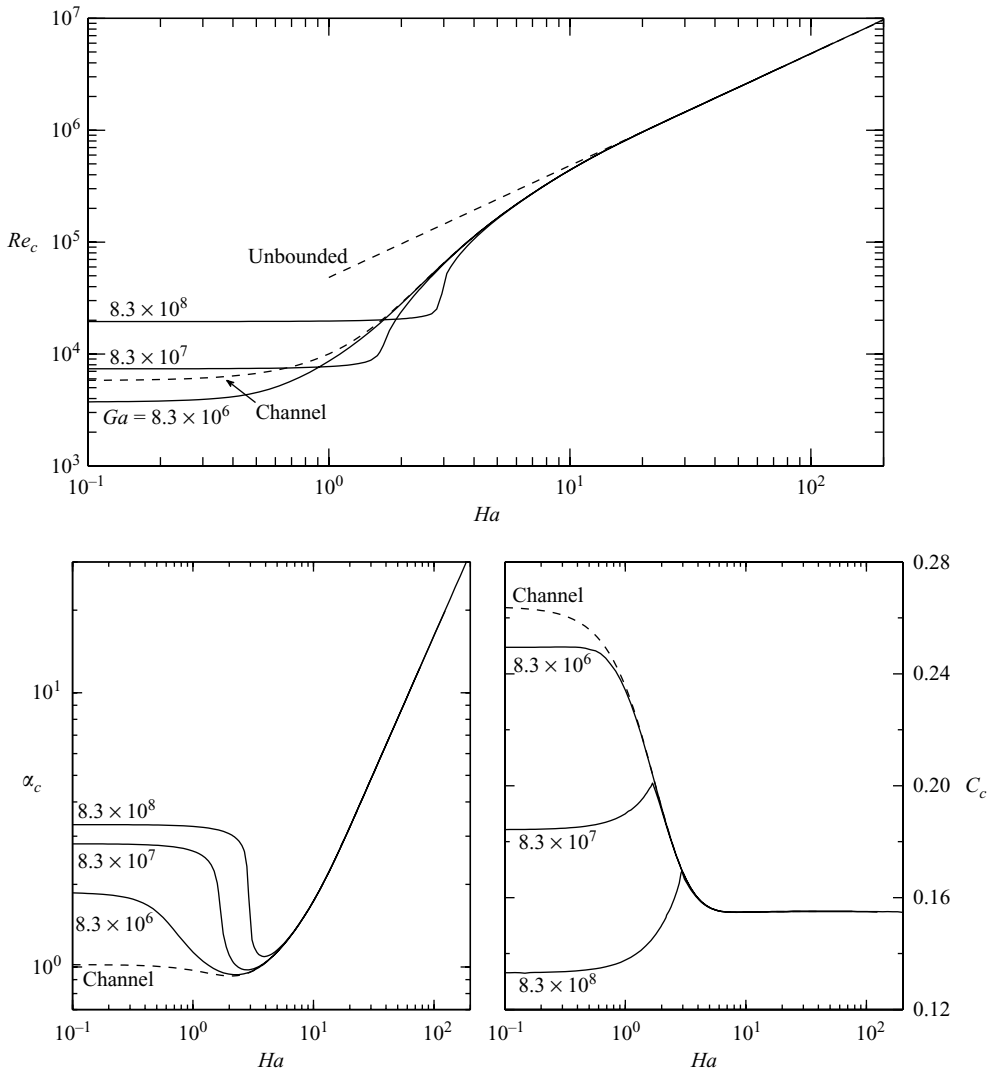


FIGURE 5. Critical Reynolds number Re_c , wavenumber α_c and phase velocity C_c of the hard mode in inductionless free-surface Hartmann flow with $Ga/(8.3 \times 10^7) \in \{0.1, 1, 10\}$, and values of the Hartmann number Ha logarithmically spaced on the interval $[0.1, 200]$. The capillary number is $Ca = 0.07$ throughout. The critical parameters for channel Hartmann flow (Takashima 1996) and the result $Re_c = 48\,250 Ha$ for the unbounded Hartmann layer (Lingwood & Alboussiere 1999) are plotted in dashed lines for reference.

the upper and lower branches of the neutral-stability curve. Eventually, however, the tip collapses, and α_c rapidly decreases towards the corresponding channel-flow result. For Hartmann numbers larger than that threshold the behaviour of the hard mode's critical parameters changes character, and as can be deduced by comparing table 2 to the calculations in table 1 of Takashima (1996), it becomes nearly identical to that of the unstable mode in inductionless channel Hartmann flow. In particular, the wavelength of the critical mode becomes shorter, as expected from the decreasing thickness of the Hartmann layer (Lock 1955), and for sufficiently strong fields the critical Reynolds number as a function of Ha is well described by the $Re_c = 48\,250 Ha$

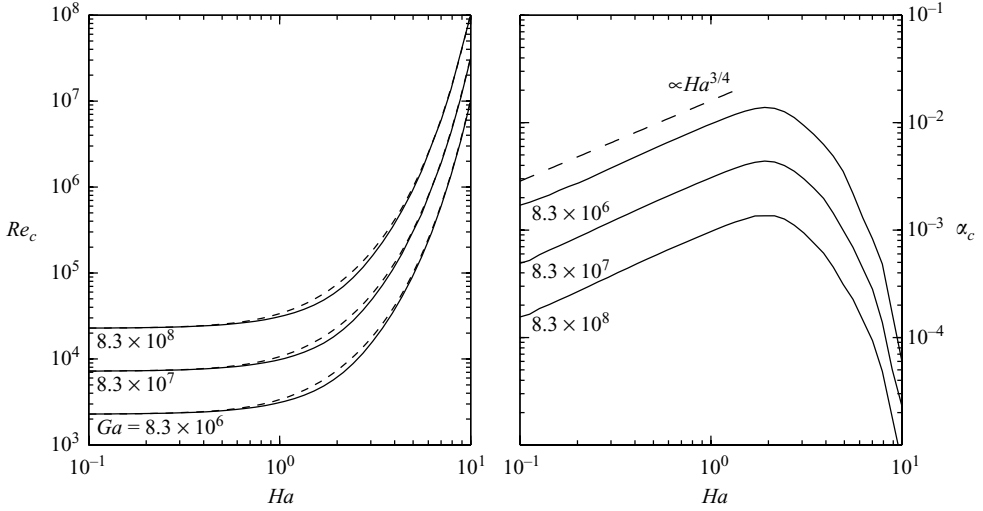


FIGURE 6. Critical Reynolds number Re_c and wavenumber α_c as functions of the Hartmann number for the soft mode in inductionless free-surface Hartmann flow with $Ga/(8.3 \times 10^7) \in \{0.1, 1, 10\}$. The capillary number is $Ca = 0.07$ throughout. The Reynolds number at the bifurcation point $Re_b(Ha)$, given by (4.1a), is plotted as the dotted lines. The critical phase velocity C_c for $Ga = 8.3 \times 10^7$ is shown in figure 11. The fluctuations present in the $Ha \lesssim 0.2$ and $Ha \gtrsim 3$ results for α_c are a consequence of the ill conditioning of the calculation described in the caption to table 3.

linear increase computed by Lingwood & Alboussiere (1999) for the unbounded Hartmann layer. In separate test calculations, where the Lorentz-force terms in (2.46) were set to zero but the Hartmann velocity profile was retained, we have observed that the critical parameters of the hard mode remain close to the results in table 2, in agreement with the observation by Lock (1955) that the principal contribution to the behaviour of (Re_c, α_c, C_c) comes from the modification of basic flow, rather than electromagnetic forces acting on the perturbed velocity field.

As for the soft mode, it follows from the large-wavelength analysis in §A.1 of the Appendix (see also Hsieh 1965; Ladikov 1966; Gupta & Rai 1968) that when Ha is non-zero the $\alpha = 0$ axis remains part of its neutral-stability curve, and a bifurcation point $(Re_b, 0)$, from which the upper part of the neutral-stability curve branches off, is again present in the (Re, α) plane. In particular, the position of the bifurcation point on the $\alpha = 0$ axis and the corresponding modal phase velocity C_b , respectively determined from the coefficients γ_2 and γ_1 in the perturbative expansion $\gamma = \gamma_1\alpha + \gamma_2\alpha^2 + O(\alpha^3)$ for the complex growth rate γ , are given by

$$Re_b = \frac{(8Ga)^{1/2} \sinh(Ha/2)(Ha - \tanh(Ha))^{1/2}}{(Ha \coth(Ha/2) \operatorname{sech}^3(Ha)(2Ha(2 + \cosh(2Ha)) - 3 \sinh(2Ha)))^{1/2}}, \quad (4.1a)$$

$$C_b = 1 + \operatorname{sech}(Ha), \quad (4.1b)$$

where $Re_b \searrow (5Ga/8)^{1/2}$ and $C_b \nearrow 2$ tend to their non-MHD values when Ha is decreased to zero. We remark that (4.1a) agrees with the corresponding expression derived by Hsieh (1965) upon substitution for Ga using (2.41a). However, contrary to the non-MHD case examined in §4.1, for Hartmann numbers lying in a relatively narrow band the bifurcation point becomes clearly separated from the critical point (Re_c, α_c) . This is illustrated in figure 6 and table 3, where for the examined values of

Ha	$Re_c/Ga^{1/2}$	$Re_b/Ga^{1/2}$	$\alpha_c Ga^{1/2}$	C_c	C_b
$Ga = 8.3 \times 10^6$					
0.1	7.9405×10^{-1}	7.9417×10^{-1}	4.850×10^0	1.9950×10^0	1.9950×10^0
0.2	8.0418×10^{-1}	7.7498×10^{-1}	7.854×10^0	1.9810×10^0	1.9803×10^0
1	1.0784×10^0	1.1687×10^0	2.795×10^1	1.7026×10^0	1.6481×10^0
2	2.1251×10^0	2.5619×10^0	3.978×10^1	1.3185×10^0	1.2658×10^0
5	3.2659×10^1	3.5000×10^1	8.500×10^0	1.0137×10^0	1.0135×10^0
8	5.2610×10^2	5.4649×10^2	1.448×10^0	1.0007×10^0	1.0007×10^0
$Ga = 8.3 \times 10^7$					
0.1	7.9405×10^{-1}	7.9417×10^{-1}	4.483×10^0	1.9951×10^0	1.9950×10^0
0.2	8.0417×10^{-1}	8.0498×10^{-1}	7.779×10^0	1.9810×10^0	1.9803×10^0
1	1.0783×10^0	1.1687×10^0	2.776×10^1	1.7027×10^0	1.6481×10^0
2	2.1249×10^0	2.5619×10^0	3.984×10^1	1.3186×10^0	1.2658×10^0
5	3.2666×10^1	3.5000×10^1	8.254×10^0	1.0137×10^0	1.0135×10^0
8	5.2616×10^2	5.4649×10^2	1.342×10^0	1.0007×10^0	1.0007×10^0
$Ga = 8.3 \times 10^8$					
0.1	7.9405×10^{-1}	7.9417×10^{-1}	4.453×10^0	1.9951×10^0	1.9950×10^0
0.2	8.0417×10^{-1}	8.0498×10^{-1}	7.702×10^0	1.9810×10^0	1.9803×10^0
1	1.0783×10^0	1.1687×10^0	2.799×10^1	1.7027×10^0	1.6481×10^0
2	2.1249×10^0	2.5619×10^0	3.942×10^1	1.3186×10^0	1.2658×10^0
5	3.2644×10^1	3.5000×10^1	9.348×10^0	1.0137×10^0	1.0135×10^0
8	5.2632×10^2	5.4649×10^2	1.225×10^0	1.0007×10^0	1.0007×10^0

TABLE 3. Critical Reynolds number Re_c , wavenumber α_c and phase velocity C_c of the soft mode in inductionless free-surface Hartmann flow, computed for Galilei number $Ga/(8.3 \times 10^7) \in \{0.1, 1, 10\}$, capillary number $Ca = 0.07$ and representative values of the Hartmann number Ha in the interval $[0.1, 8]$. Also shown are the Reynolds number Re_b at the bifurcation point and the corresponding phase velocity C_b , determined by (4.1). In order to illustrate the dependence of the critical parameters on Ga , the results for Re_c and Re_b have been scaled by $Ga^{1/2}$, while α_c has been scaled by $Ga^{-1/2}$. We remark that because the $\text{Im}(c)$ contours for the soft mode are nearly parallel to the $\log(\alpha)$ axis when $\alpha \ll 1$ (see figure 4c), and the gradient of $\text{Re}(\gamma(Re, \alpha))$ becomes shallow as Ha grows (this is a consequence of the strong-field neutrality of mode F discussed in the main text), critical-parameter calculations for the soft instability are significantly more poorly conditioned than the corresponding ones for the hard mode. As a result, the number of attained significant digits in the calculations is smaller than in table 2, especially so for α_c . In addition, there is evidence of an $O(10^{-4})$ systematic drift in the results for α_c when the optimization solver used to compute (Re_c, α_c, C_c) is restarted with initial conditions determined from the output of preceding iterations, indicating that with the current computational resources, some of our results have not yet reached an asymptotic limit. However, we do not expect this to impart significant changes to the shape of the curves in figure 6.

the Galilei number $Ga/8.3 \times 10^7 \in \{0.1, 1, 10\}$ the critical wavenumber follows an $\alpha_c \propto Ha^{3/4}$ increase for $Ha \lesssim 2$ (e.g. reaching $\alpha \approx 0.0044$ for $Ha \approx 1.9$ and $Ga = 8.3 \times 10^7$), before rapidly diminishing again at larger Hartmann numbers. As is the case with the $Re_b \propto Ga^{1/2}$ scaling in (4.1a), all the Re_c results nearly collapse to a single curve when scaled by $Ga^{1/2}$. The calculations also suggest that an $\alpha_c \propto Ga^{-1/2}$ scaling applies for the critical wavenumber, but this cannot be firmly confirmed with the presently attainable level of numerical accuracy and precision. As expected, whenever α_c is small, the deviation of the critical Reynolds number and phase velocity from (4.1) is less significant, but even when α_c is close to its maximum value the relative error is still acceptable. In table 3, for instance, Re_b overestimates Re_c by approximately 20% when $Ha = 2$, while C_b underestimates C_c by 4%. The influence of $\alpha_c > 0$ on the

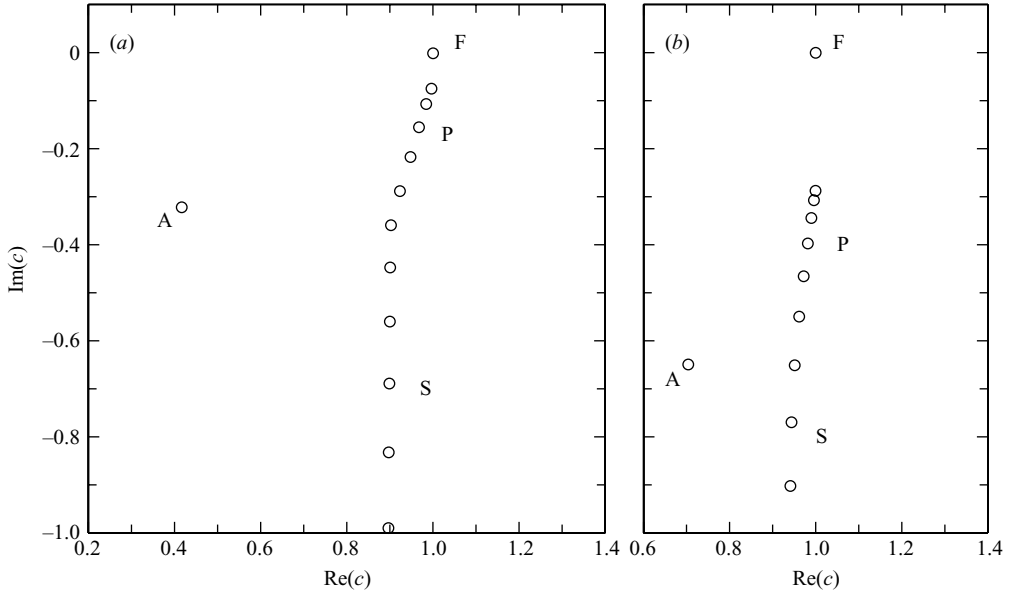


FIGURE 7. Eigenvalues of inductionless free-surface Hartmann flow at $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-5}$, $Ga = 8.3 \times 10^7$ and $Ca = 0.07$. The Hartmann number in (a) and (b) is $Ha = 10$ and 20 , respectively. The evolution of this spectrum with $Ha \in [0.1, 50]$ is shown in movie 1, available with the online version of the paper.

critical Reynolds number can also be observed by examining the $\text{Im}(c) = 0$ contour in figure 4(c), where Re decreases from 5.49×10^4 when $\alpha = 10^{-5}$ to $4.74 \times 10^4 \approx Re_c$ when $\alpha = 0.0032 \approx \alpha_c$.

The agreement between the analytical results for (Re_b, C_b) and the numerically computed values for (Re_c, C_c) steadily improves as $\alpha_c(Ha)$ enters the decreasing phase ($Ha \gtrsim 2$ in figure 6). As such, (4.1a) can be used to deduce that at sufficiently large Ha the soft mode's critical Reynolds number $Re_c \sim (Ga/Ha)^{1/2} \exp(Ha)$ increases exponentially with the Hartmann number, and its critical phase velocity $C_c \sim 1 + 2 \exp(-Ha)$ decreases exponentially towards unity. Similar small- α calculations (see (A 28) and (A 29)) lead to the results that Re_b also increases exponentially in (physically unrealistic) non-MHD problems with the Hartmann velocity profile but only quadratically when the Lorentz-force terms in (2.46) are retained, while the velocity profile keeps its non-MHD parabolic form. Therefore, the formation of the Hartmann velocity profile is the main driver of the critical-parameter behaviour of the soft instability as well, although it should be noted that the exponent in (A 28a) is smaller than the corresponding one derived from (4.1a), and as a result, the critical Reynolds number of the full problem, including both Lorentz forces and the Hartmann velocity profile, outgrows that of the non-MHD test problem without bound.

Turning now to the behaviour of the eigenvalues on the complex- c plane, a prominent feature of inductionless Hartmann flow, illustrated in figure 7 and movie 1 (see table 4 for the corresponding numerical data), is that as Ha increases the P branch of the spectrum becomes aligned with the S branch, and the eigenvalues in the A branch collapse towards the P-S branch intersection point. In addition, with the exception of mode F, which is seen to move along the $\text{Re}(c)$ axis towards $\text{Re}(c) = 1$, the eigenvalues are translated into smaller values of $\text{Im}(c)$ (quadratically

		c	E_a/E
$Ha = 10$			
1	F	$1.000478880697718 \times 10^0 - 1.492458547790363 \times 10^{-3} i$	9.80634×10^{-1}
2	P ₁	$9.969844758638947 \times 10^{-1} - 7.510300218671238 \times 10^{-2} i$	1.55113×10^{-2}
3	P ₂	$9.844830185724478 \times 10^{-1} - 1.070009578761852 \times 10^{-1} i$	1.56260×10^{-3}
4	P ₃	$9.679739162321193 \times 10^{-1} - 1.555307117857878 \times 10^{-1} i$	3.70125×10^{-4}
5	P ₄	$9.480545293986525 \times 10^{-1} - 2.173575052123932 \times 10^{-1} i$	1.08068×10^{-4}
6	P ₅	$9.235179572370349 \times 10^{-1} - 2.886322049592563 \times 10^{-1} i$	3.89742×10^{-5}
7	A ₁	$4.169901573651648 \times 10^{-1} - 3.220427370877234 \times 10^{-1} i$	7.72718×10^{-5}
8	P ₆	$9.026456030169425 \times 10^{-1} - 3.595290667757633 \times 10^{-1} i$	1.62104×10^{-5}
9	S ₁	$9.009193226866442 \times 10^{-1} - 4.475126687270328 \times 10^{-1} i$	4.35020×10^{-6}
10	S ₂	$9.003564254536676 \times 10^{-1} - 5.601694489236487 \times 10^{-1} i$	1.00325×10^{-6}
$Ha = 20$			
1	F	$1.000045818436596 \times 10^0 - 5.289119738767267 \times 10^{-4} i$	9.98203×10^{-1}
2	P ₁	$9.994955777811616 \times 10^{-1} - 2.877934996693214 \times 10^{-1} i$	1.41502×10^{-3}
3	P ₂	$9.960450826999606 \times 10^{-1} - 3.075429925109489 \times 10^{-1} i$	1.54941×10^{-4}
4	P ₃	$9.898991606163317 \times 10^{-1} - 3.445398689126118 \times 10^{-1} i$	5.56023×10^{-5}
5	P ₄	$9.817920008849399 \times 10^{-1} - 3.974550352653800 \times 10^{-1} i$	2.52511×10^{-5}
6	P ₅	$9.721963507775145 \times 10^{-1} - 4.656744531110017 \times 10^{-1} i$	1.23326×10^{-5}
7	P ₆	$9.615513110612295 \times 10^{-1} - 5.497038985606164 \times 10^{-1} i$	6.15471×10^{-6}
8	A ₁	$7.040044446493452 \times 10^{-1} - 6.496646531013073 \times 10^{-1} i$	2.32334×10^{-5}
9	S ₁	$9.510925679889382 \times 10^{-1} - 6.510431012818730 \times 10^{-1} i$	3.02892×10^{-6}
10	S ₂	$9.439623776920884 \times 10^{-1} - 7.698041542899734 \times 10^{-1} i$	1.41918×10^{-6}

TABLE 4. Complex phase velocity c and free-surface energy E_a , normalized by the total energy $E = E_u + E_a$, of the 10 least stable modes of the inductionless problems in figure 7. The mean steady-state velocity $\langle U \rangle$, given by (2.29), is 0.9001 ($Ha = 10$) and 0.9500 ($Ha = 20$). Due to the alignment of the P and S branches, there exists ambiguity in distinguishing between the most stable P mode and the least stable S mode. Here we consider that the P branch comprises of the first six modes (in order of decreasing $\text{Im}(c)$) with $\text{Re}(c) > \langle U \rangle$.

with Ha , as shown in figure 8). As in non-MHD problems, the phase velocity of the S-family modes is (asymptotically) equal to the average steady-state speed (2.29), which approaches unity as Ha grows, and $\text{Re}(c)$ lies in the interval $(\langle U \rangle, 1)$ for modes in the P branch. Moreover, the phase velocity of mode F remains greater than unity, even for strong fields ($Ha \sim 10^3$). By performing suitable test calculations, we have verified that the branch alignment and $\text{Im}(c)$ decrease observed for the A, P and S modes are independently caused by the formation of the Hartmann velocity profile and the Lorentz force, respectively.

The exponential $Re_b(Ha)$ growth in (4.1a) is a somewhat misleading indicator for the magnetic field's stabilizing effect on mode F, which participates in the soft instability. The reason is that unlike the remaining modes in the spectrum (as well as all channel modes), whose decay rate increases quadratically with Ha as a consequence of Lorentz damping, mode F becomes asymptotically neutral for large magnetic field strengths. This behaviour is illustrated in figure 8, where the complex phase velocity and the results for the energy components and energy transfer rates are plotted as functions of $Ha \in [10^{-2}, 10^3]$ for the 10 least stable modes of the non-MHD problem in figure 3. As the Hartmann number grows, the total mechanical energy transfer rate $\Gamma_{mech} := \Gamma_R + \Gamma_v + \Gamma_{aU}$ (the inductionless version of (3.27a)) to mode F experiences a sharp drop, caused by a decrease in Γ_{aU} associated with the flattening of the velocity profile. This, in conjunction with resistive dissipation Γ_η , which in inductionless problems is the only component of the electromagnetic energy transfer

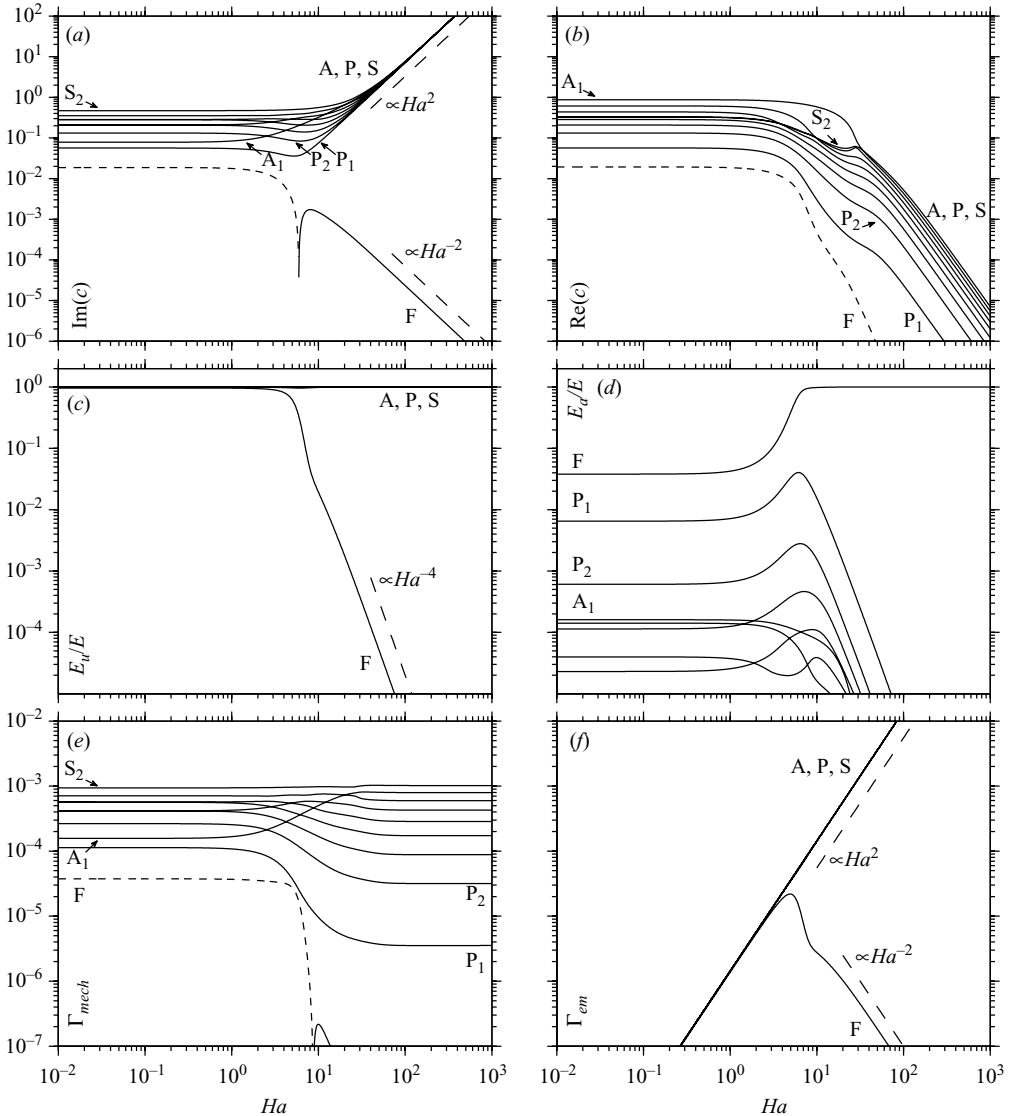


FIGURE 8. Complex phase velocity c , kinetic and surface energies E_u and E_a (normalized by the total energy $E = E_u + E_a$) and mechanical and electromagnetic energy transfer rates Γ_{mech} and Γ_{em} for the 10 least stable modes of inductionless free-surface Hartmann flow at $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-3}$, $Ga = 8.3 \times 10^7$ and $Ca = 0.07$, showing the qualitatively different dependence of the F mode and the A, P and S modes on the Hartmann number Ha . In (a), (b), (e) and (f), the solid and dashed lines respectively correspond to negative and positive values. Besides mode F, the curves for modes A_1 , P_1 , P_2 and S_2 (the modes indexed according to their $Ha = 0$ values; see table 1) are indicated.

rate Γ_{em} , suffices to stabilize the mode for all $Ha \gtrsim 6$. However, instead of growing quadratically with Ha , as it does for the A, P and S families of modes, the decay rate $-\Gamma$ of mode F turns around and approaches zero following an Ha^{-2} scaling. At the same time, the mode's energy content becomes almost entirely potential, with the kinetic energy following the power law $E_u/E \propto Ha^{-4}$. In contrast, for sufficiently

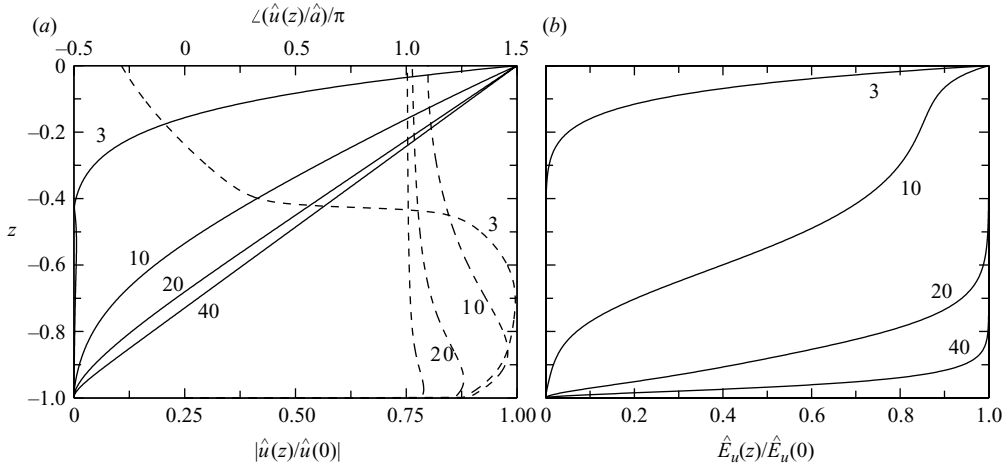


FIGURE 9. (a) Modulus (solid lines) and phase (dashed lines) of the velocity eigenfunction $\hat{u}(z)$ and (b) kinetic energy density $\hat{E}_u(z)$ of mode F for $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-3}$, $Ga = 8.3 \times 10^7$, $Ca = 0.07$ and Hartmann number $Ha \in \{3, 10, 20, 40\}$. The phase of the eigenfunction is computed relative to the free-surface oscillation amplitude \hat{a} . As Ha grows, \hat{u} develops a linear profile away from the wall, which corresponds to a uniform streamwise velocity amplitude (because u_x is proportional to $D\hat{u}$).

large Hartmann numbers, free-surface oscillations become negligible for the A, P and S modes, as manifested by their decaying surface energy E_a .

Figure 9 shows that as the Hartmann number is increased, the velocity eigenfunction $\hat{u}(z)$ corresponding to mode F evolves from a typical surface-wave-like profile at small Hartmann numbers to a state of nearly z -independent streamwise flow, characterized by uniform distribution of the kinetic energy away from the wall. Moreover, in line with the kinematic boundary condition (2.48b) with $C \approx 1$ (i.e. $\gamma \approx -i\alpha$), at large Hartmann numbers $\hat{u}(0)$ exhibits a 180° phase difference relative to the free-surface oscillation amplitude \hat{a} , which in the real representation corresponds to the streamwise velocity perturbations $u_x(0)$ being 90° out of phase with the free-surface oscillation amplitude a (recall that in accordance with (2.42a), $u_x = \text{Im}(D\hat{u}/\alpha \exp(\gamma t + i\alpha x))$).

The observed scaling of the kinetic energy of mode F for strong magnetic fields is dimensionally consistent with a time-averaged equilibrium determined by the work done by Lorentz and gravitational stresses acting on the free surface. We approximate this balance by setting $f \sim g$, where $f \sim Ha^2 Re^{-1} |u_x(0)|$ and $g \sim \cos(\theta) Fr^{-2} |a| = Ga Re^{-2} |a|$ are respectively estimates of the Lorentz and gravitational forces. Because at large Ha the velocity-eigenfunction gradient $D\hat{u}$ is nearly constant over the inner part of the domain, and at large wavelengths the ratio $(\|u_x\|/\|u_z\|)^2 \sim \alpha^{-2}$ is expected to be large, $f \sim g$ leads to $E_u/E_a \sim (|u_x(0)| \cos(\theta)/(Fr^2 |a|))^2 \sim Ga/Ha^4$. The latter scaling is consistent with the E_u/E results in figure 8 (note that $E_u/E \approx E_u/E_a$ for $E_u \ll E_a$), and in separate calculations we have checked that the $E_u/E_a \propto Ga$ scaling applies at fixed Ha . Aside from figure 8, a $|\Gamma| \propto Ha^{-2}$ strong-field behaviour for mode F was also recorded in trial inductionless problems with $U(z)$ set to the Poiseuille profile and is also expected on the basis of large-wavelength approximations (see (A 29c)). On the other hand, in non-MHD calculations with the Hartmann velocity profile, as well as in the corresponding small- α expansion (A 28c), the modal growth rate Γ tends to a Ha -independent negative value for $Ha \gg 1$. These

observations, coupled with the dimensional argument for E_u/E_a , suggest that the strong-field neutrality of mode F is the outcome of a balance between gravitational and Lorentz forces and does not rely on the form of the steady-state velocity profile.

4.3. Free-surface Hartmann flow at $Pm \leq 10^{-4}$

In low- Pm channel Hartmann flow with insulating boundary conditions the critical Reynolds number, wavenumber and phase velocity are known to be well approximated by the inductionless scheme. In particular, the calculations by Takashima (1996) have established that for $Pm \leq 10^{-4}$ the relative error incurred in Re_c is less than 0.004, even at Hartmann numbers as high as 100, where Re_c is of order 10^7 . In free-surface flow (again with an insulating wall), however, we find that while the critical parameters of the hard mode are equally insensitive to $Pm \ll 1$ as in channel problems, the soft mode's behaviour differs markedly between the small- Pm and inductionless cases. Moreover, the boundary conditions now support a pair of travelling Alfvén waves, the upstream propagating of which may become unstable at sufficiently high Alfvén numbers. When conducting boundary conditions are enforced, the Alfvén modes are removed from the spectrum, and the soft mode's critical Reynolds number becomes a decreasing function of $Ha \gg 1$. In general, these observations indicate that the dynamical response of the magnetic field to the flow, which is neglected in the inductionless approximation, plays an important role in the linear stability of free-surface MHD flows, even when the working fluid has large magnetic diffusivity.

4.3.1. Properties of the least stable modes

We illustrate the behaviour of the top end of the spectrum for problems with an insulating wall in figure 10, where contours of the complex phase velocity in the (Re, α) plane are plotted for the least stable mode at fixed $Pm = 10^{-5}$ (a value lying in the upper end of the Pm regime for liquid metals) and moderately small Hartmann number $Ha \in [3, 10]$. It is evident from the proximity of the portions of the inductionless and $Pm = 10^{-5}$ neutral-stability curves corresponding to the hard mode, as well as from the close agreement between the critical-Reynolds-number calculations in tables 2 and 5, that the influence of a finite magnetic diffusivity on the hard instability is weak, with Re_c being slightly smaller when Pm is non-zero compared to its value in the inductionless limit. In the case of the soft mode, however, prominent differences in the stability properties exist even at small Hartmann numbers.

First, the structure of the $\text{Im}(c)$ contours in figure 10 suggests that the $\alpha = 0$ axis is no longer part of the neutral-stability curve $\text{Im}(c) = 0$, and this can be confirmed by means of large-wavelength perturbation theory. In particular, according to the discussion in §A.2 of the Appendix, free-surface Hartmann flow with an insulating wall supports, besides mode F, a second mode with vanishing complex growth rate γ in the limit $\alpha \searrow 0$, of magnetic origin. The zeroth-order degeneracy between mode F and this magnetic mode is broken at first order in α , where there exist two distinct solutions, respectively $\gamma_1^{(F)}$ and $\gamma_1^{(M)}$, for the coefficient γ_1 in the perturbative series $\gamma = \gamma_0 + \gamma_1\alpha + \gamma_2\alpha^2 + O(\alpha^3)$. Both solutions have negative real part for all $Ha > 0$ and $Pm > 0$ (note that $\text{Re}(\gamma_1^{(M)})$ is negative even when Ha equals zero), which implies that for any Reynolds number there exists an upper bound α_m in α , below which mode F is stable. That is $\text{Re}(\gamma)$ is negative for $0 < \alpha < \alpha_m$ or, as observed in figure 10, $\text{Im}(c)$ is negative for $0 \leq \alpha < \alpha_m$ (cf. inductionless flow). We remark that because γ vanishes in the limit $\alpha \searrow 0$, it is important to distinguish between the definitions $\text{Im}(c) = 0$ and $\text{Re}(\gamma) = 0$ for the soft mode's neutral-stability curve, since with the latter definition the $\alpha = 0$ axis remains part of the curve even when $\text{Re}(\gamma_1) \neq 0$. In separate numerical

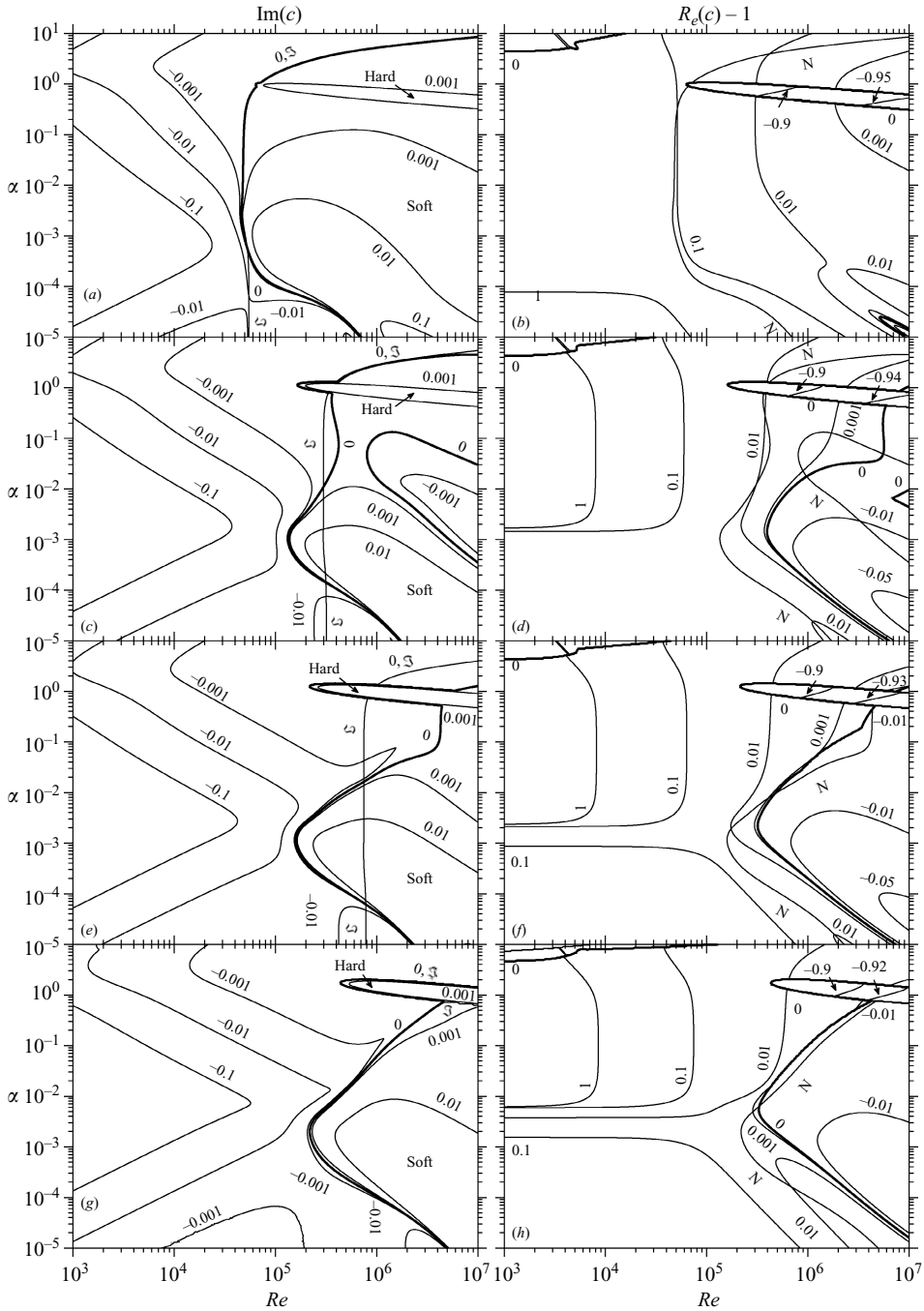


FIGURE 10. Contours of the complex phase velocity c in the (Re, α) plane for the least stable mode of free-surface Hartmann flow with an insulating wall at $Pm = 10^{-5}$, $Ga = 8.3 \times 10^7$, and $Ca = 0.07$. The Hartmann number Ha is (a,b) 3, (c,d) 5, (e,f) 6 and (g,h) 10. The curves labelled \Im in the panels for $Im(c)$ are the $Im(c) = 0$ contours of the corresponding inductionless problems. The neutral-stability curves for $Pm = 10^{-5}$, labelled N, are drawn in the $Re(c)$ panels for reference.

Ha	Re_c	α_c	C_c
$Pm = 10^{-5}$			
0.5	7.4343262×10^3	2.77817×10^0	1.85689×10^{-1}
1	7.7154109×10^3	2.64640×10^0	1.89960×10^{-1}
2	2.3923849×10^4	1.10426×10^0	1.91216×10^{-1}
5	1.6371768×10^5	1.13613×10^0	1.56438×10^{-1}
10	4.3954479×10^5	1.73924×10^0	1.54813×10^{-1}
20	9.6100175×10^5	3.23776×10^0	1.55044×10^{-1}
50	2.4134695×10^6	8.07606×10^0	1.55064×10^{-1}
100	4.8268720×10^6	1.61512×10^1	1.55064×10^{-1}
$Pm = 10^{-4}$			
0.5	7.4342966×10^3	2.77815×10^0	1.85683×10^{-1}
1	7.7152014×10^3	2.64657×10^0	1.89973×10^{-1}
2	2.3879649×10^4	1.10492×10^0	1.91273×10^{-1}
5	1.6340601×10^5	1.13611×10^0	1.56539×10^{-1}
10	4.3859195×10^5	1.73911×10^0	1.54934×10^{-1}
20	9.5885884×10^5	3.23738×10^0	1.55171×10^{-1}
50	2.4078809×10^6	8.07604×10^0	1.55197×10^{-1}
100	4.8155345×10^6	1.61542×10^1	1.55200×10^{-1}

TABLE 5. Critical Reynolds number Re_c , wavenumber α_c and phase velocity C_c of the hard mode in free-surface Hartmann flow with insulating boundary conditions, computed at Galilei number $Ga = 8.3 \times 10^7$, capillary number $Ca = 0.07$, magnetic Prandtl number $Pm \in \{10^{-5}, 10^{-4}\}$ and Hartmann number $Ha \in [0.5, 100]$.

calculations we have checked that α_m becomes smaller when Pm is decreased at fixed Ha , which is consistent with the large-wavelength result (A 41) that in the limit $Pm \searrow 0$, $\gamma_1^{(F)}$ reaches the inductionless value (A 22), while $\gamma_1^{(M)}$ is singular.

Performing a similar type of analysis establishes that (i) when the induced magnetic field B is set to zero, $\text{Re}(\gamma_1)$ is still negative for mode F, as well as for the magnetic mode; (ii) when U and B are both set to zero, γ_1 , now given by (A 42), is negative for the magnetic mode but vanishes for mode F; and (iii) in Hartmann flow with a perfectly conducting wall, the $\hat{b}(-1) = 0$ constraint imposed on the magnetic field eigenfunction eliminates the magnetic mode, and $\gamma_1^{(F)}$ becomes equal to the corresponding expansion coefficient in the inductionless limit. It therefore appears that the suppression of the soft instability for $\alpha \searrow 0$ is the combined outcome of the boundary conditions, which allow for the presence of the magnetic mode and the coupling between mode F and the magnetic mode provided by the steady-state flow.

The soft mode's departure from inductionless behaviour is also prominent at larger values of αRe . As can be seen in figure 10, at moderate Hartmann numbers ($Ha \sim 5$) regions of stability emerge in the (Re, α) plane that would contain unstable modes in the inductionless limit. Moreover, as Ha grows, a wedge-like instability region forms, extending to Reynolds numbers significantly smaller than in the corresponding inductionless problems. Unstable modes may now have phase velocity smaller than unity, but $\text{Re}(c) > 1$ is found to apply for the modes close to the tip of the wedge-like region (including the critical mode), at least for the $Ha \leq 10^3$ interval covered in our calculations.

The critical parameters of the soft mode as a function of $Ha \in [10^{-1}, 10^3]$ are plotted in figure 11 for logarithmically spaced values of the magnetic Prandtl number $Pm \in \{10^{-6}, 10^{-5}, 10^{-4}\}$ (see also table 6). As expected from the contour plots in figure 10, when the Hartmann number is small, Re_c is close to its value in the

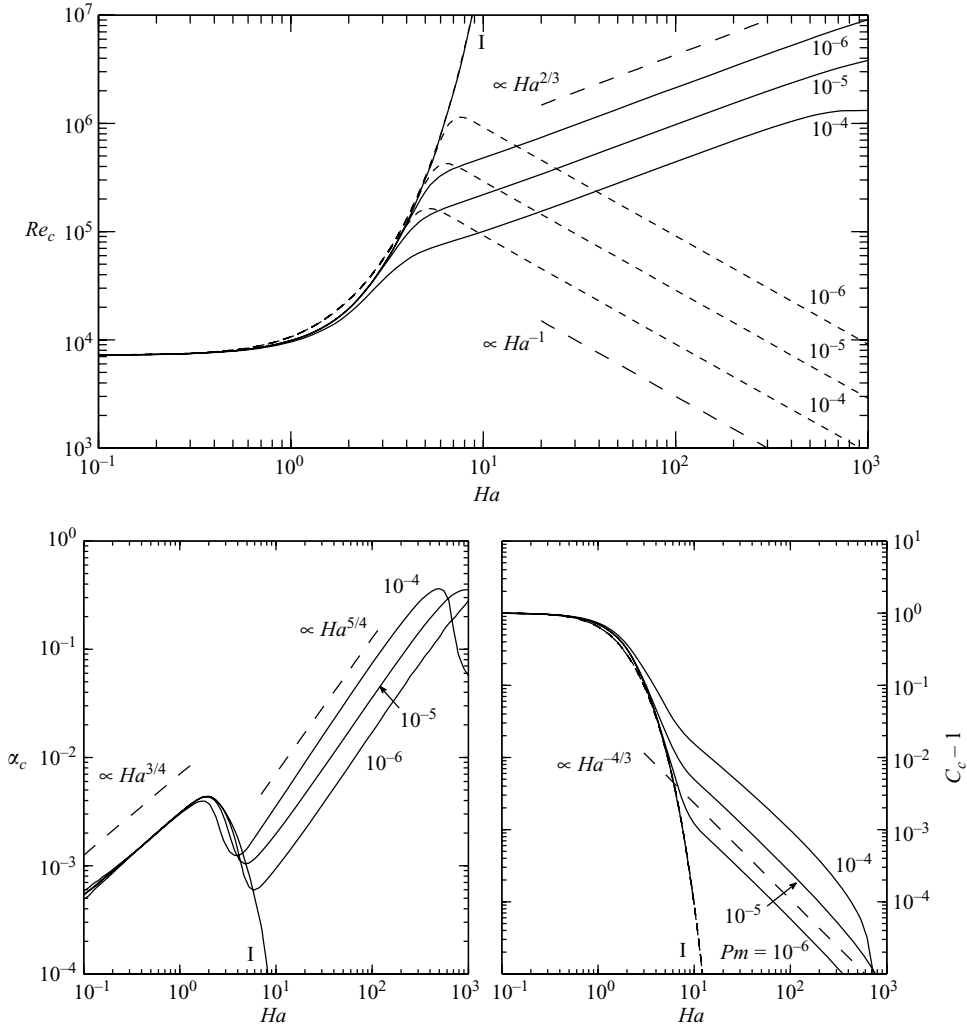


FIGURE 11. Critical Reynolds number Re_c , wavenumber α_c and phase velocity C_c of the soft mode as functions of the Hartmann number $Ha \in [10^{-1}, 10^3]$ for inductionless problems (curves labelled I) and insulating-wall problems with $Pm \in \{10^{-6}, 10^{-5}, 10^{-4}\}$. Also shown, as the dotted lines, are the Reynolds number Re_b and the corresponding phase velocity C_b at the bifurcation point of the neutral-stability curve, evaluated for conducting-wall problems by means of the large-wavelength results (A 43) and (4.1b). The Galilei and capillary numbers are $Ga = 8.3 \times 10^7$ and $Ca = 0.07$ throughout. As in figure 6, the fluctuations in the $\alpha_c(Ha)$ curves are due to the ill conditioning of critical-parameter calculations for the soft mode. Aside from these fluctuations, we do not expect significant effects on the shape of the curves due to ill conditioning.

inductionless limit. For instance, the relative difference between the $Ha = 1$ results in table 6 and the corresponding inductionless results in table 3 is less than 3.5%. However, once the magnetic field strength exceeds a threshold, which decreases with Pm , $Re_c(Ha)$ branches off from the exponential growth (4.1a) and follows closely the power law $Re_c \propto Ha^{2/3}$. During that transition, the decrease of the wavenumber with Ha observed in the inductionless limit is reversed, switching over to an $\alpha_c \propto Ha^{5/4}$ scaling. Moreover, the exponential decrease (4.1b) of the critical phase velocity relative

Ha	Re_c	α_c	$C_c - 1$
$Pm = 10^{-6}$			
0.1	7.2341×10^3	5.353×10^{-4}	9.9504×10^{-1}
1	9.8246×10^3	3.069×10^{-3}	7.0268×10^{-1}
10	4.7810×10^5	9.369×10^{-4}	1.2076×10^{-3}
100	2.1205×10^6	1.670×10^{-2}	5.7707×10^{-5}
1000	9.3869×10^6	2.113×10^{-1}	1.8874×10^{-6}
$Pm = 10^{-5}$			
0.1	7.2343×10^3	5.355×10^{-4}	9.9505×10^{-1}
1	9.8253×10^3	3.072×10^{-3}	7.0314×10^{-1}
10	2.1891×10^5	1.978×10^{-3}	4.9470×10^{-3}
100	9.7469×10^5	3.552×10^{-2}	2.5559×10^{-4}
1000	3.8912×10^6	2.244×10^{-1}	4.1975×10^{-6}
$Pm = 10^{-4}$			
0.1	7.2322×10^3	6.005×10^{-4}	9.9563×10^{-1}
1	9.5341×10^3	2.979×10^{-3}	7.3307×10^{-1}
10	1.0034×10^5	3.571×10^{-3}	1.5546×10^{-2}
100	4.4148×10^5	7.375×10^{-2}	9.8053×10^{-4}
1000	1.3161×10^6	6.202×10^{-2}	1.4324×10^{-6}

TABLE 6. Critical Reynolds number Re_c , wavenumber α_c and phase velocity C_c of the soft mode in free-surface Hartmann flow with insulating boundary conditions, computed at Galilei number $Ga = 8.3 \times 10^7$, capillary number $Ca = 0.07$, magnetic Prandtl number $Pm \in \{10^{-6}, 10^{-5}, 10^{-4}\}$ and Hartmann number $Ha \in [10^{-1}, 10^3]$. These calculations are affected by a similarly ill conditioning as the corresponding ones for inductionless problems in table 3. In particular, we have observed an $O(10^{-4})$ systematic drift in some of the results for α_c , arising when the optimization solver used to compute (Re_c, α_c, C_c) is restarted using the output of previous calculations for initialization. With the presently available computational resources we were not able to perform a sufficiently large number of iterations so as to establish convergence in α_c . However, we expect the results for Re_c and C_c to be affected by this issue to a lesser extent.

to the steady-state flow at the free surface becomes a $C_c - 1 \propto Ha^{-4/3}$ power law. In this intermediate Hartmann-number regime, the results for $Re_c(Ha)$, $\alpha_c(Ha)$ and $C_c(Ha) - 1$ collapse to nearly single curves if scaled by $Pm^{1/3}$, $Pm^{-1/3}$ and $Pm^{-2/3}$, respectively (though the agreement is not as good for the $Pm = 10^{-4}$ data for $C_c - 1$). The power-law behaviour of the critical parameters is only transient, however. Eventually, at sufficiently large Hartmann numbers, $Re_c(Ha)$ levels off (for $Pm = 10^{-4}$ this occurs around $Ha = 500$), and $\alpha_c(Ha)$ becomes a decreasing function once again.

The deviation of the critical Reynolds number of the soft instability from (4.1a) is even more pronounced in problems with a perfectly conducting wall. As outlined in §A.2 of the Appendix, in this case the first-order coefficient in the perturbation series for γ is given by the same expression as in inductionless flows (i.e. (A 22)), which has vanishing real part, and as a result the $\alpha = 0$ axis remains part of the neutral-stability curve. This enables the derivation of the closed-form expression (A 43) for the Reynolds number Re_b at the bifurcation point, which, in the manner shown in figure 11, becomes a decreasing function of Ha , varying like $Re_b \sim (Ga/Pm)^{1/2} Ha^{-1}$ at large Hartmann numbers. Even though we have not explicitly computed the soft mode's critical parameters for conducting-wall problems, we have verified in eigenvalue contour plots that as in inductionless flows, Re_b is close to Re_c . In any case, since Re_b is an upper bound for Re_c , the behaviour of $Re_b(Ha)$ suffices to

	Inductionless	Insulating	Conducting	Insulating ($B = 0$)	Conducting ($B = 0$)
Γ	-1.0578×10^{-6}	9.2461×10^{-6}	2.2910×10^{-5}	-1.1177×10^{-6}	-1.0578×10^{-6}
$C - 1$	4.5818×10^{-5}	3.9237×10^{-3}	-9.1720×10^{-4}	3.3397×10^{-5}	4.5808×10^{-5}
E_u/E	1.7966×10^{-3}	6.8769×10^{-2}	3.3217×10^{-2}	1.9035×10^{-3}	1.7965×10^{-3}
E_{bi}/E		1.6250×10^{-3}	9.2557×10^{-1}	2.5348×10^{-6}	2.6228×10^{-6}
E_{b+}/E		4.3846×10^{-1}	1.8511×10^{-3}	8.9635×10^{-4}	3.9822×10^{-9}
E_{b-}/E		4.3696×10^{-1}		8.9621×10^{-4}	
E_a/E	9.9820×10^{-1}	5.4185×10^{-2}	3.9363×10^{-2}	9.9630×10^{-1}	9.9820×10^{-1}
Γ_R	-9.2340×10^{-9}	6.8264×10^{-6}	-1.6850×10^{-7}	8.3862×10^{-9}	-9.2227×10^{-9}
Γ_M		1.1921×10^{-4}	2.9758×10^{-8}	3.0503×10^{-7}	9.7837×10^{-12}
Γ_J		4.0665×10^{-5}	2.1215×10^{-5}	0	0
Γ_v	-2.1990×10^{-8}	-4.2321×10^{-5}	-3.9619×10^{-7}	-4.3489×10^{-8}	-2.2006×10^{-8}
Γ_η	-1.0266×10^{-6}	-1.2435×10^{-4}	-1.9008×10^{-5}	-1.3873×10^{-6}	-1.0323×10^{-6}
Γ_{aU}	2.4801×10^{-15}	-1.1324×10^{-12}	5.8983×10^{-14}	4.7636×10^{-15}	2.0486×10^{-15}
Γ_{aJ}		9.2090×10^{-6}	2.1239×10^{-5}	0	0
Γ_{mech}	-3.1224×10^{-8}	5.1710×10^{-6}	2.0650×10^{-5}	-3.5102×10^{-8}	-3.1229×10^{-8}
Γ_{em}	-1.0266×10^{-6}	4.0697×10^{-6}	2.2610×10^{-6}	-1.0823×10^{-6}	-1.0323×10^{-6}

TABLE 7. Growth rate and phase velocity, energy components and energy transfer rates for mode F at $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-3}$, $Ga = 8.3 \times 10^7$, $Ca = 0.07$, $Ha = 20$ and $Pm = 10^{-5}$. The data in the leftmost column are for the corresponding inductionless problem, and therefore all entries involving the magnetic field eigenfunction are omitted. Counting from the left, the results in columns 2 and 4 are for insulating boundary conditions, while for those in columns 3 and 5 conducting boundary conditions have been imposed (i.e. the external magnetic energy component E_{b-} is omitted). For the calculations in columns 4 and 5 the induced magnetic field B has been set to zero, and as a result Γ_J and Γ_{aJ} vanish.

conclude that in free-surface Hartmann flow with a perfectly conducting wall the external magnetic field leads to a reduction of the critical Reynolds number for instability for all $Pm > 0$.

4.3.2. The role of the steady-state induced magnetic field

Except for the large-wavelength instability suppression observed in problems with insulating boundary conditions, where, as stated in §4.3.1, the modal decay rate is non-zero to linear order in α even when B vanishes, the discrepancy between inductionless and non-zero- Pm behaviour for mode F is mainly caused by the steady-state induced magnetic field (2.26b), through the contribution $f_J := Rm \mathbf{J} \times \mathbf{b} \sim Pm^{1/2} Ha \|DB\| \|\mathbf{b}\|$ to the linearized Lorentz force (2.7b) associated with the spanwise current $\mathbf{J} := Rm^{-1} \nabla \times \mathbf{B} = Rm^{-1} Ha Pm^{1/2} DB \mathbf{y}$. As a demonstration, in figure 12 and table 7 we have computed the complex phase velocity of mode F, as well as certain energy components and energy transfer rates, as a function of $Ha \in [10^{-2}, 10^3]$ for (i) $Pm = 10^{-5}$ flows with insulating and perfectly conducting walls, (ii) the corresponding inductionless problems and (iii) insulating and conducting-wall problems with $Pm = 10^{-5}$ and B set to zero. The $B = 0$ calculations are physically unrealistic, but when compared with the complete ones that include B help to bring out the influence of \mathbf{J} in the observed instabilities.

The results for the test problems with $B = 0$ agree fairly well with the corresponding ones in the inductionless limit. Here the main differences are that the total electromagnetic energy transfer rate $\Gamma_{em} := \Gamma_\eta + \Gamma_M$ now includes a small, positive contribution from the Maxwell stress and, for $Ha \gtrsim 30$, that the modal phase velocity

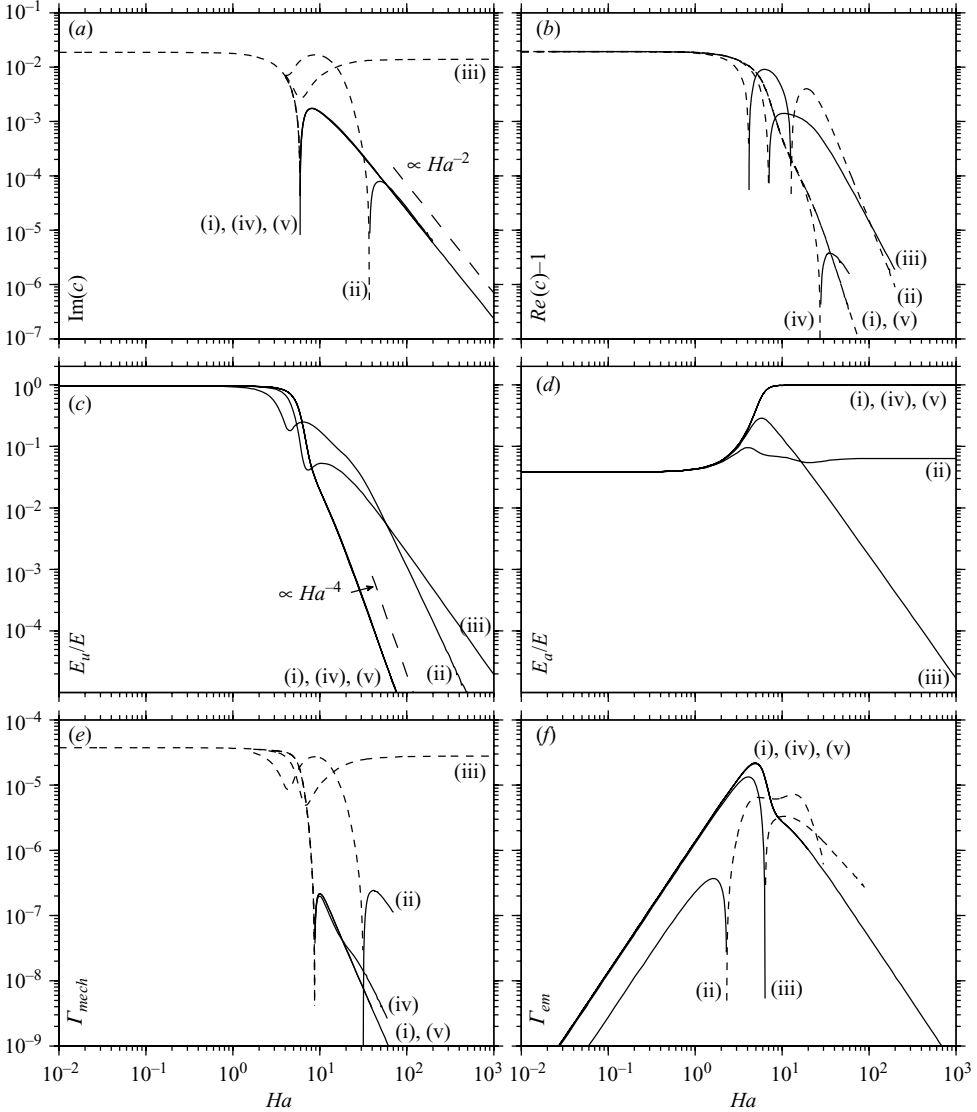


FIGURE 12. Complex phase velocity c , kinetic and surface energies E_u and E_a (normalized by the total energy E) and mechanical and electromagnetic energy transfer rates Γ_{mech} and Γ_{em} for mode F in free-surface Hartmann flow at $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-3}$, $Ga = 8.3 \times 10^7$, $Ca = 0.07$ and $Ha \in [10^{-2}, 10^3]$. The curves labelled (i) correspond to inductionless flow, while (ii) and (iii) were evaluated at $Pm = 10^{-5}$, respectively with insulating and perfectly conducting boundary conditions. Curves (iv) and (v) are for the same problems as (ii) and (iii), respectively, but with the magnetic field profile B set to zero. In (a), (b), (e) and (f), the solid (dashed) lines correspond to negative (positive) values. As discussed in Giannakis *et al.* (2009), accurate numerical evaluation of some of the energy transfer rates can be problematic, especially when a large polynomial degree is required for the spectral solution to (2.43) to converge. For this reason, we have not been able to evaluate Γ_{mech} and Γ_{em} for Hartmann numbers as large as 10^3 . Roundoff errors also limit the convergence of the eigenvalue for mode F to about five significant digits when Ha becomes large in cases (ii)–(v). Apart from the $Re(c)$ graph for (iii), this level of numerical precision is not sufficient to continue the logarithmic plots in (a) and (b) to $Ha \gtrsim 100$, where both of $|Im(c)|$ and $|Re(c) - 1|$ become small compared to $|c| \approx 1$.

is less than the free-surface steady-state velocity. The error is particularly small for the conducting-wall problem, since in that case the energy transfer to the modes via Maxwell stress, which is not captured by the inductionless scheme, is suppressed due to the nature of the boundary conditions. In contrast, when B is included, the current-interaction term Γ_J causes the total mechanical energy transfer rate $\Gamma_{mech} := \Gamma_v + \Gamma_R + \Gamma_{aU} + \Gamma_J$ to remain positive for Hartmann numbers larger than the $Ha \approx 9$ value above which it becomes negative in inductionless and $B = 0$ problems. The total electromagnetic energy transfer rate $\Gamma_{em} := \Gamma_\eta + \Gamma_M + \Gamma_{aJ}$, where the surface term Γ_{aJ} is appreciable and positive, also deviates markedly from its Ha dependence in the inductionless limit.

In the insulating-wall example, the combined effect produces a more than twofold increase of the Hartmann number required for instability suppression relative to inductionless flow. Moreover, the modal energy in the strong-field limit, instead of becoming almost exclusively gravitational, is split into an Ha -independent mix between magnetic and surface parts. Although we have observed a scaling of the form $E_b/E_a \propto Pm/Ga$ for $Ha \gg 1$, we have not been able to account for it by invoking a work-balance argument (cf. §4.2).

If now the wall is perfectly conducting, the current interaction term Γ_J becomes sufficiently large so as to cause the growth rate $\text{Im}(c)\alpha$ to asymptote to a positive value, rather than approach zero from below. In addition, the energy in the magnetic degrees of freedom dominates, with both surface and kinetic contributions decaying to zero. The greater influence of the steady-state current in problems with a perfectly conducting wall is consistent with the fact that $|B(z)|$ is of order unity throughout the core of the flow domain, while it is of order $1/Ha$ when the wall is insulating (see §2.4).

The data for Γ_R and Γ_v in table 7 exhibit a particularly large discrepancy between the non-zero- B problem with an insulating wall and its inductionless counterpart, signalling that the Lorentz force associated with \mathbf{J} causes significant changes in the structure of the velocity eigenfunction $\hat{u}(z)$. Indeed, as illustrated in figure 13, the perturbed velocity field of the full MHD problem bears little resemblance to the inductionless examples in figure 9. In particular, instead of evolving towards a state of uniform streamwise-velocity amplitude as Ha grows, $|\hat{u}(z)|$ and the kinetic energy density $\hat{E}_u(z)$ develop a maximum in the wall region, where $|\mathbf{J}|$ is concentrated (see figure 2). The increased eigenfunction curvature leads in turn to higher viscous and resistive dissipation, but these are more than counter-balanced by positive current interaction and by positive energy transfer due to Reynolds and Maxwell stresses. As for the magnetic field eigenfunction $\hat{b}(z)$, its modulus varies by less than 10^{-2} over the fluid domain, and since the modal wavenumber $\alpha = 0.002$ is small, the energy of the magnetic field penetrating into the exterior region, E_b (3.21), exceeds the internal magnetic energy E_{bi} (3.19) by two orders of magnitude (see table 7). We remark that in problems with a perfectly conducting wall, where the current distribution over the inner part of the domain is nearly uniform, $\hat{u}(z)$ is qualitatively similar to the inductionless case, and $\hat{b}(z)$ varies nearly linearly from zero at the wall to its free-surface value.

4.3.3. Travelling Alfvén modes

Having studied the behaviour of the least stable modes in some detail, we now examine the influence of a small, but non-zero, magnetic Prandtl number on the more stable modes. As illustrated by the spectra in figure 14 and table 8, computed for $Ha = 0.1$ and $Pm \in \{10^{-5}, 10^{-4}\}$, when the applied magnetic field is weak,

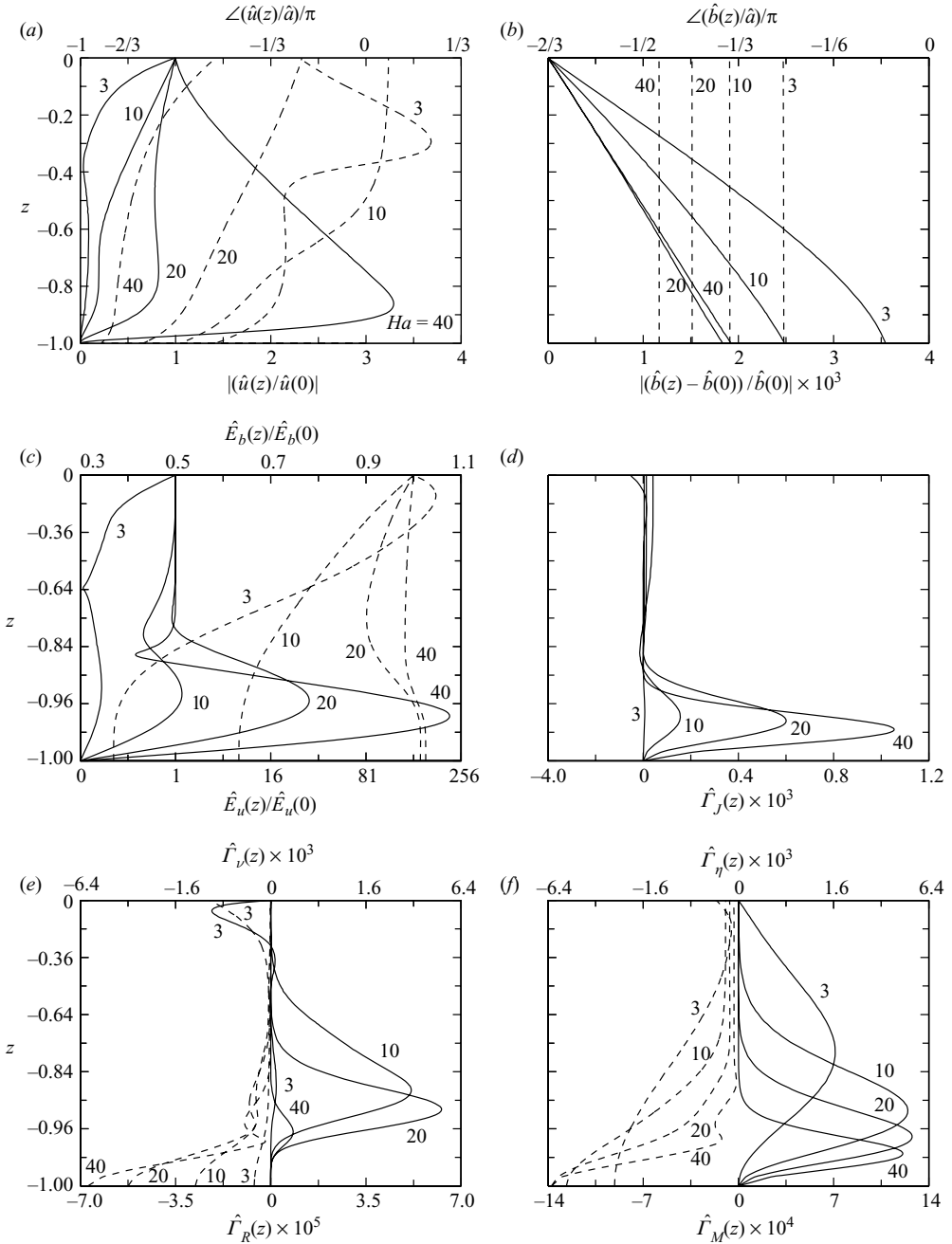


FIGURE 13. (a) Velocity eigenfunction, (b) magnetic field eigenfunction, (c) kinetic and magnetic energy densities, (d) current interaction, (e) viscous dissipation and Reynolds stress (f) and resistive dissipation and Maxwell stress, for mode F in insulating-wall problems with $Pm = 10^{-5}$, $Ha \in \{3, 10, 20, 40\}$ and remaining flow parameters equal to those in the inductionless problems in figure 9. In (a), (b), (e) and (f) the solid and dotted lines are associated with the lower and upper horizontal axes, respectively. In order to better depict the peaks in $\hat{E}_u(z)$, the corresponding axis has quartic scaling. Likewise, quadratic scaling has been used for the z coordinate in (c)–(f), as well as for the axes for $\hat{\Gamma}_v(z)$ and $\hat{\Gamma}_\eta(z)$.

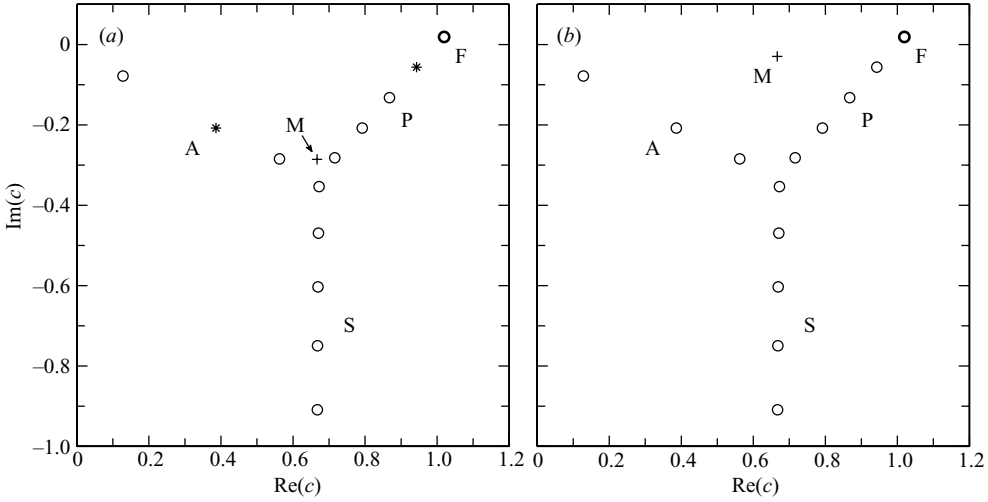


FIGURE 14. Eigenvalues of free-surface Hartmann flow with an insulating wall at $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-3}$, $Ga = 8.3 \times 10^7$, $Ca = 0.07$ and $Ha = 0.1$. The magnetic Prandtl number Pm in (a) and (b) is 10^{-5} and 10^{-4} , respectively. Mode M, plotted using a + marker, is singular in the inductionless limit $Pm \searrow 0$, while mode F, plotted in boldface, is unstable in both panels. Modes P_1 and A_2 in (a), plotted using * markers, become converted to modes L_+ and L_- in figure 15 as the Hartmann number is increased. The dependence of this spectrum on $Pm \in [10^{-6}, 10^{-4}]$ is shown in movie 2, available with the online version of the paper.

	c	E_a/E	E_b/E
$Ha = 0.1, Pm = 10^{-5}$			
1	F $1.01931082772748 \times 10^0 + 1.87122221676069 \times 10^{-2}i$	3.82063×10^{-2}	2.65603×10^{-4}
2	P_1 $9.43120008162654 \times 10^{-1} - 5.65860384497908 \times 10^{-2}i$	6.53040×10^{-3}	4.87128×10^{-5}
3	A_1 $1.28101973089488 \times 10^{-1} - 7.85027707446042 \times 10^{-2}i$	1.61230×10^{-4}	1.74331×10^{-6}
4	P_2 $8.67716150616648 \times 10^{-1} - 1.32222546160657 \times 10^{-1}i$	6.09816×10^{-4}	6.65946×10^{-6}
5	P_3 $7.92170269201228 \times 10^{-1} - 2.07817958769442 \times 10^{-1}i$	1.14325×10^{-4}	3.72558×10^{-6}
6	A_2 $3.86411583077811 \times 10^{-1} - 2.07964549091180 \times 10^{-1}i$	1.41756×10^{-4}	2.47046×10^{-6}
7	P_4 $7.16273931735328 \times 10^{-1} - 2.81864800130393 \times 10^{-1}i$	2.31289×10^{-5}	9.27739×10^{-6}
8	A_3 $5.62415456020230 \times 10^{-1} - 2.84607742157634 \times 10^{-1}i$	3.99484×10^{-5}	4.07061×10^{-6}
9	M $6.66774912099173 \times 10^{-1} - 2.86025163476446 \times 10^{-1}i$	6.24179×10^{-7}	9.74910×10^{-1}
10	S_1 $6.72566612117371 \times 10^{-1} - 3.53685916601131 \times 10^{-1}i$	3.85519×10^{-6}	1.26283×10^{-6}
$Ha = 0.1, Pm = 10^{-4}$			
1	F $1.01931125301428 \times 10^0 + 1.87093734887185 \times 10^{-2}i$	3.82168×10^{-2}	6.24640×10^{-5}
2	M $6.66800739433602 \times 10^{-1} - 2.97757500101643 \times 10^{-2}i$	1.47480×10^{-6}	9.97323×10^{-1}
3	P_1 $9.43117677138117 \times 10^{-1} - 5.65832503068096 \times 10^{-2}i$	6.53056×10^{-3}	1.04209×10^{-5}
4	A_1 $1.28101057320598 \times 10^{-1} - 7.85034486458773 \times 10^{-2}i$	1.61230×10^{-4}	3.43338×10^{-7}
5	P_2 $8.67714460364094 \times 10^{-1} - 1.32221228532799 \times 10^{-1}i$	6.09793×10^{-4}	1.03611×10^{-6}
6	P_3 $7.92167689972354 \times 10^{-1} - 2.07816923033732 \times 10^{-1}i$	1.14320×10^{-4}	2.11886×10^{-7}
7	A_2 $3.86416377565185 \times 10^{-1} - 2.07965044026100 \times 10^{-1}i$	1.41753×10^{-4}	2.75247×10^{-7}
8	P_4 $7.16262532911781 \times 10^{-1} - 2.81865240487700 \times 10^{-1}i$	2.31293×10^{-5}	4.63160×10^{-8}
9	A_3 $5.62410360672946 \times 10^{-1} - 2.84606171228795 \times 10^{-1}i$	3.99490×10^{-5}	7.99622×10^{-8}
10	S_1 $6.72561149596221 \times 10^{-1} - 3.53688962352034 \times 10^{-1}i$	3.85565×10^{-6}	1.00596×10^{-8}

TABLE 8. Complex phase velocity c , free-surface energy E_a and magnetic energy E_b of the 10 least stable modes of the spectra in figure 14. The energies E_a and E_b have been normalized by the total energy $E = E_u + E_b + E_a$.

free-surface flows with an insulating wall exhibit (in addition to the A, F, P and S modes) a mode labelled M that is not present in inductionless flows. Mode M is stable, and like S-family modes, its phase velocity is close to the mean steady-state speed. However, it stands out from the remaining modes because of (i) the strong Pm dependence of its decay rate, which decreases by an order of magnitude between the $Pm = 10^{-5}$ and $Pm = 10^{-4}$ calculations in table 8 (the corresponding relative variation for the A, F, P, and S modes is less than 10^{-4}), and (ii) its mostly magnetic energy content (e.g. in table 8, $E_b/E \approx 0.95$ for mode M, whereas $E_b/E \lesssim 10^{-4}$ for modes in the A, F, P and S families). Although we have not confirmed this analytically, numerical calculations strongly suggest that mode M is singular in the inductionless limit $Pm \searrow 0$. In particular, as shown in movie 2, when Pm is increased from small values the complex phase velocity of mode M is seen to approach the upper part of the spectrum from arbitrarily small values of $\text{Im}(c)$, moving along the S eigenvalue branch. We remark, however, that the complex phase velocity does not cross the $\text{Im}(c) = 0$ axis. Instead, if Pm is allowed to be of order unity, mode M eventually participates in the formation of magnetic eigenvalue branches (Giannakis *et al.* 2009).

The existence of modes of magnetic origin (hence the designation M) in the spectrum of the coupled OS and induction equations (2.43) is consistent with the fact that the limit $Pm \searrow 0$ at fixed Ha , which as discussed in §2.6 leads to the approximate stability equation (2.46), is singular. (Effectively, the differential order of the stability problem is reduced from six to four.) Modes of this type are also present in channel Hartmann flow, as well as in test problems with $B = 0$. However, we have found no evidence of mode M in numerical calculations with conducting boundary conditions, which correlates with the absence of the $\gamma_1^{(M)}$ magnetic solution in the large-wavelength approximations for conducting-wall problems in §A.2 of the Appendix.

As shown in the spectra in figure 15, evaluated for insulating-wall problems with $Pm = 10^{-5}$, $Ha \in \{10, 20, 50\}$ and otherwise the same parameters as the inductionless calculations in figure 7, when the external magnetic field is of appreciable strength the collapse of the A eigenvalue branch and the alignment of the P and S branches observed in the inductionless limit (see §4.2) are also present in the $Pm > 0$ problems. In addition, according to the data in table 9, the magnetic energy for all but the first handful of modes is relatively small ($E_b/E \lesssim 10^{-1}$), and in those cases the accuracy of the inductionless approximation is very acceptable. (For instance a comparison with table 4 shows that the relative error for mode P_4 at $Ha = 10$ is at the 1% level.) Still, as already discussed in §4.3.1 and §4.3.2, the non-zero- Pm spectra deviate substantially from the corresponding inductionless ones in the behaviour of mode F, whose main distinguishing features in figure 15 and table 9 in comparison with figure 7 and table 4 are (i) sub-unity phase velocity $C \approx 0.9959$ when $Ha = 10$, (ii) positive growth rate in both of the $Ha = 10$ and $Ha = 20$ calculations and (iii) magnetic-energy predominance for strong background fields (e.g. $E_b/E \approx 0.93$ for $Ha = 50$).

Aside from the discrepancies associated with mode F, however, the spectra in figure 15 differ from those in figure 4 in that they contain two travelling modes, labelled L_- and L_+ , which have no counterparts in the inductionless limit. As illustrated in movie 3, these modes are the outcome of a mode-conversion process, whereby the weak-field modes A_2 and P_1 separate from the A and P eigenvalue branches when Ha is increased from small values and move towards nearly symmetric positions on the complex plane about $\text{Re}(c) = 1$. At the same time, mode M joins the P eigenvalue branch and, having lost the majority of its magnetic energy, behaves

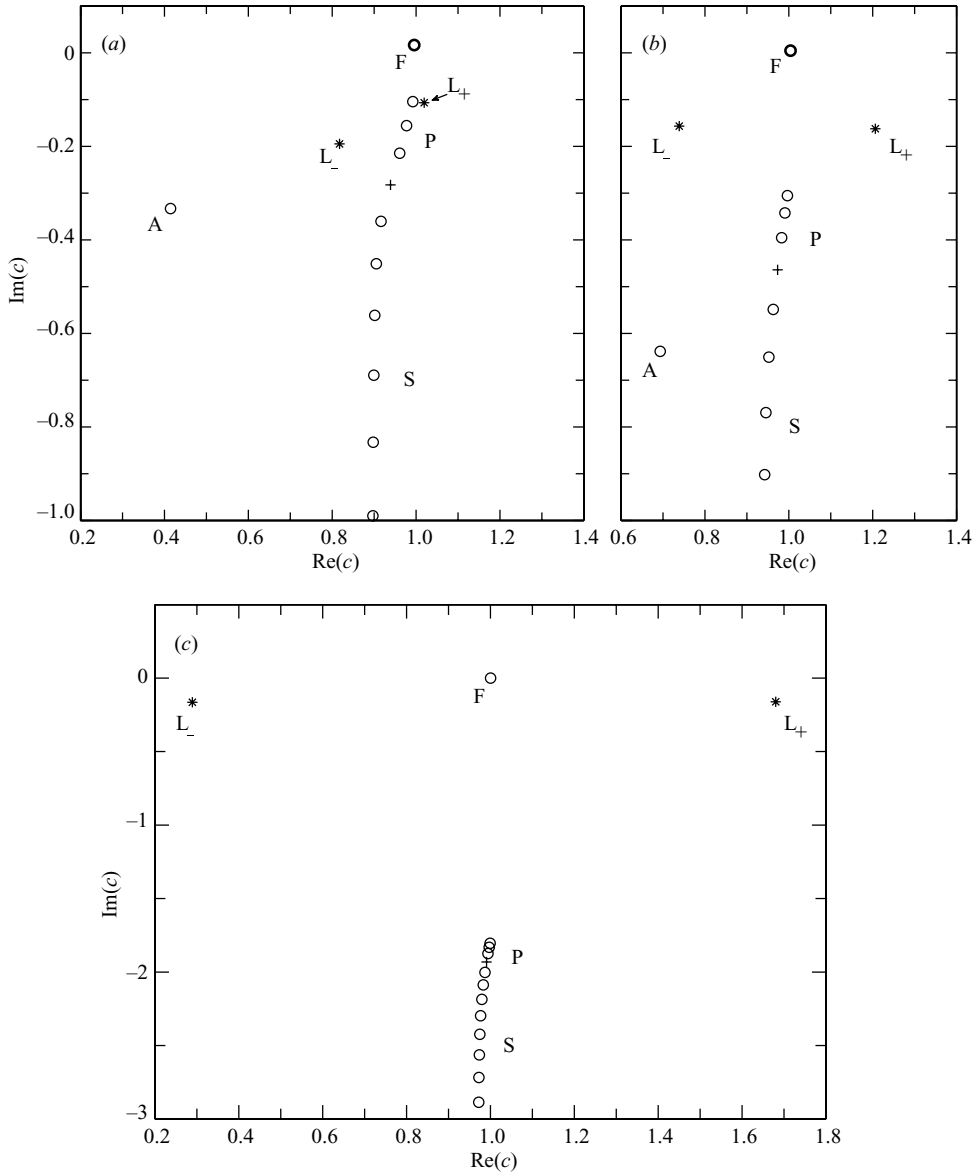


FIGURE 15. Eigenvalues of free-surface Hartmann flow with an insulating wall at $Re = 7 \times 10^5$, $\alpha = 2 \times 10^{-3}$, $Pm = 10^{-5}$, $Ga = 8.3 \times 10^7$, $Ca = 0.07$ and (a) $Ha = 10$, (b) $Ha = 20$ and (c) $Ha = 50$. The modes labelled L_- and L_+ , and plotted using * markers, are travelling Alfvén waves and can be continuously traced to modes A_2 and P_1 , respectively, as $Ha \searrow 0$. The mode plotted using a + marker originates from mode M in figure 14(a). In (a) and (b), mode F, plotted in boldface, is unstable. The evolution of this spectrum with $Ha \in [0.1, 50]$ is shown in movie 3, available with the online version of the paper.

in the same manner as the remaining P and S modes. A principal feature of the L modes for sufficiently strong magnetic fields, which can be observed in the $Ha = 20$ and $Ha = 50$ results in table 9, is a near equipartition between magnetic and kinetic energies. Because of this, we classify these modes as ‘travelling Alfvén waves’. In separate numerical calculations, we have confirmed that modes of this type are also

	c	E_a/E	E_b/E	
$Ha = 10, Pm = 10^{-5}$				
1	F	$9.95865078137089 \times 10^{-1} + 1.63947948356842 \times 10^{-2}i$	6.67566×10^{-2}	7.56599×10^{-1}
2	P ₁	$9.92557588155474 \times 10^{-1} - 1.04442847126442 \times 10^{-1}i$	1.82412×10^{-3}	1.03289×10^{-1}
3	L ₊	$1.01939554477557 \times 10^0 - 1.06858631729338 \times 10^{-1}i$	5.76706×10^{-3}	3.85449×10^{-1}
4	P ₂	$9.77461544779890 \times 10^{-1} - 1.55881324364227 \times 10^{-1}i$	6.76741×10^{-4}	1.08003×10^{-1}
5	L ₋	$8.17555458976949 \times 10^{-1} - 1.94975997718683 \times 10^{-1}i$	7.43663×10^{-4}	2.66480×10^{-1}
6	P ₃	$9.61162906229426 \times 10^{-1} - 2.14936006245129 \times 10^{-1}i$	1.26044×10^{-4}	8.66194×10^{-2}
7	P ₄	$9.39093462022514 \times 10^{-1} - 2.82501396482664 \times 10^{-1}i$	5.08031×10^{-6}	3.25970×10^{-2}
8	A ₁	$4.14592505991546 \times 10^{-1} - 3.33142243705258 \times 10^{-1}i$	7.03352×10^{-5}	1.24080×10^{-2}
9	P ₅	$9.16439057608324 \times 10^{-1} - 3.60617428043375 \times 10^{-1}i$	2.76783×10^{-6}	7.44498×10^{-3}
10	S ₁	$9.05320512052477 \times 10^{-1} - 4.51161148416211 \times 10^{-1}i$	1.69292×10^{-6}	1.52332×10^{-3}
$Ha = 20, Pm = 10^{-5}$				
1	F	$1.00392370142334 \times 10^0 + 4.62308174479437 \times 10^{-3}i$	5.41852×10^{-2}	8.77046×10^{-1}
2	L ₋	$7.38547682046289 \times 10^{-1} - 1.56955992195965 \times 10^{-1}i$	8.21253×10^{-4}	4.47778×10^{-1}
3	L ₊	$1.20624039578785 \times 10^0 - 1.62495095508186 \times 10^{-1}i$	1.00742×10^{-3}	5.53021×10^{-1}
4	P ₁	$9.96643310724506 \times 10^{-1} - 3.05478418809574 \times 10^{-1}i$	2.85312×10^{-8}	7.90718×10^{-4}
5	P ₂	$9.90773359402505 \times 10^{-1} - 3.42351571140559 \times 10^{-1}i$	1.12321×10^{-7}	1.41202×10^{-3}
6	P ₃	$9.82893615854751 \times 10^{-1} - 3.95487920055681 \times 10^{-1}i$	3.08386×10^{-7}	1.84037×10^{-3}
7	P ₄	$9.73387208655838 \times 10^{-1} - 4.64261831294372 \times 10^{-1}i$	5.33617×10^{-7}	1.74777×10^{-3}
8	P ₅	$9.62772461311780 \times 10^{-1} - 5.48990582273123 \times 10^{-1}i$	6.23475×10^{-7}	1.32879×10^{-3}
9	A ₁	$6.93299438967882 \times 10^{-1} - 6.38530573016983 \times 10^{-1}i$	8.03501×10^{-6}	9.71982×10^{-3}
10	S ₁	$9.52461437608548 \times 10^{-1} - 6.50819443090838 \times 10^{-1}i$	5.46661×10^{-7}	8.54110×10^{-4}
$Ha = 50, Pm = 10^{-5}$				
1	F	$1.00024009887062 \times 10^0 - 7.84769189348587 \times 10^{-5}i$	6.17833×10^{-2}	9.29735×10^{-1}
2	L ₊	$1.68062858014303 \times 10^0 - 1.61493055991922 \times 10^{-1}i$	1.67082×10^{-4}	5.14154×10^{-1}
3	L ₋	$2.89175320132634 \times 10^{-1} - 1.64256263206813 \times 10^{-1}i$	1.57691×10^{-4}	4.87064×10^{-1}
4	P ₁	$9.99199429127421 \times 10^{-1} - 1.80434774096787 \times 10^0i$	1.82872×10^{-10}	1.94749×10^{-3}
5	P ₂	$9.97091976769849 \times 10^{-1} - 1.83142407634326 \times 10^0i$	7.93664×10^{-10}	7.16630×10^{-4}
6	P ₃	$9.94227660233984 \times 10^{-1} - 1.87446928135769 \times 10^0i$	1.52677×10^{-9}	3.71281×10^{-4}
7	P ₄	$9.90706905162818 \times 10^1 - 1.93185106397859 \times 10^0i$	2.45478×10^{-9}	2.35469×10^{-4}
8	P ₅	$9.86809861524976 \times 10^{-1} - 2.00299291310038 \times 10^0i$	3.38590×10^{-9}	1.68562×10^{-4}
9	P ₆	$9.82936143590023 \times 10^{-1} - 2.08763002827334 \times 10^0i$	4.23074×10^{-9}	1.30181×10^{-4}
10	S ₁	$9.79496738581810 \times 10^{-1} - 2.18575887355621 \times 10^0i$	4.81819×10^{-9}	1.05130×10^{-4}

TABLE 9. Complex phase velocity c , surface energy E_a and magnetic energy E_b of the 10 least stable modes of the spectra in figure 15. The energies E_a and E_b have been normalized by the total energy $E = E_u + E_b + E_a$. If Ha is decreased to 0.1, mode P₄ (in figure 15, plotted using a + marker) can be continuously traced to mode M in the $Pm = 10^{-5}$ part of table 8. The average steady-state velocity $\langle U \rangle$ is, in accordance with (2.29), 0.9001, 0.9500 and 0.9800, respectively for $Ha = 10, 20$ and 50 . Due to the alignment of the P and S branches, the classification of the sixth least stable mode for $Ha = 10$, the eighth least stable mode for $Ha = 20$ and the ninth least stable mode for $Ha = 50$ as members of the P family is somewhat arbitrary; these modes could equally be treated as members of the S branch.

part of the spectrum when the background fluid is at rest. In channel problems with insulating walls, the pair of travelling waves becomes replaced by a single frozen-in magnetic mode (Betchov & Criminale 1967, §IX), whose phase velocity and kinetic energy are nearly equal to unity and zero, respectively. However, as with mode M, both of the travelling and frozen-in Alfvén modes are removed from the spectrum when conducting boundary conditions are enforced.

When a steady-state flow is present, the upstream-propagating wave L₋ may become unstable if the Alfvén number $Al = RePm^{1/2}/Ha$ of the flow is sufficiently large. This

	$Ha = 0.02$			$Ha = 1$		
	F	M	P_1	F	M	P_1
Γ	2.817×10^{-6}	-3.708×10^{-7}	-8.451×10^{-6}	2.582×10^{-6}	-3.737×10^{-7}	-8.082×10^{-6}
$C - 1$	2.818×10^{-2}	-3.333×10^{-1}	-8.452×10^{-2}	2.639×10^{-2}	-3.226×10^{-1}	-8.107×10^{-2}
E_u/E	9.997×10^{-1}	1.685×10^{-3}	1.000×10^0	9.978×10^{-1}	8.054×10^{-1}	9.997×10^{-1}
E_{bi}/E	4.076×10^{-7}	1.436×10^{-1}	4.650×10^{-8}	1.122×10^{-3}	2.766×10^{-2}	1.233×10^{-4}
E_{b+}/E	1.299×10^{-7}	4.273×10^{-1}	2.181×10^{-8}	3.800×10^{-4}	8.344×10^{-2}	6.086×10^{-5}
E_{b-}/E	1.296×10^{-7}	4.273×10^{-1}	2.186×10^{-8}	3.794×10^{-4}	8.345×10^{-2}	6.100×10^{-5}
E_a/E	2.697×10^{-4}	1.465×10^{-8}	4.487×10^{-5}	3.157×10^{-4}	7.628×10^{-6}	5.008×10^{-5}
Γ_R	-6.428×10^{-7}	-5.542×10^{-9}	-2.715×10^{-6}	-6.135×10^{-7}	-2.473×10^{-6}	-2.594×10^{-6}
Γ_M	1.710×10^{-9}	2.393×10^{-3}	2.365×10^{-10}	4.768×10^{-6}	4.591×10^{-4}	6.328×10^{-7}
Γ_J	-7.523×10^{-11}	6.136×10^{-9}	3.776×10^{-11}	-1.993×10^{-7}	2.880×10^{-6}	9.784×10^{-8}
Γ_v	-8.586×10^{-6}	-7.040×10^{-9}	-3.732×10^{-6}	-8.549×10^{-6}	-3.302×10^{-6}	-3.552×10^{-6}
Γ_η	-1.838×10^{-9}	-2.393×10^{-3}	-2.416×10^{-10}	-5.097×10^{-6}	-4.511×10^{-4}	-6.407×10^{-7}
Γ_{aU}	1.205×10^{-5}	-2.702×10^{-10}	-2.004×10^{-6}	1.206×10^{-5}	-1.354×10^{-7}	-1.923×10^{-6}
Γ_{aJ}	7.858×10^{-11}	-1.139×10^{-8}	-3.945×10^{-11}	2.083×10^{-7}	-5.316×10^{-6}	-1.022×10^{-7}
Γ_{mech}	2.817×10^{-6}	-6.716×10^{-9}	-8.451×10^{-6}	2.703×10^{-6}	-3.030×10^{-6}	-7.972×10^{-6}
Γ_{em}	-4.866×10^{-11}	-3.641×10^{-7}	-4.452×10^{-11}	-1.207×10^{-7}	2.656×10^{-6}	-1.101×10^{-7}
	$Ha = 15$			$Ha = 200$		
	L_+	L_-	F	L_+	L_-	F
Γ	-1.363×10^{-5}	9.339×10^{-8}	8.941×10^{-6}	-1.593×10^{-5}	-1.621×10^{-5}	-3.877×10^{-9}
$C - 1$	3.470×10^{-2}	-7.181×10^{-2}	-3.757×10^{-2}	4.141×10^{-1}	-4.216×10^{-1}	4.120×10^{-5}
E_u/E	9.726×10^{-1}	9.389×10^{-1}	9.303×10^{-1}	4.936×10^{-1}	5.052×10^{-1}	6.098×10^{-3}
E_{bi}/E	1.637×10^{-3}	3.508×10^{-3}	3.360×10^{-3}	1.636×10^{-4}	9.185×10^{-5}	2.603×10^{-4}
E_{b+}/E	1.284×10^{-2}	2.866×10^{-2}	3.310×10^{-2}	2.531×10^{-1}	2.474×10^{-1}	4.969×10^{-1}
E_{b-}/E	1.289×10^{-2}	2.876×10^{-2}	3.312×10^{-2}	2.531×10^{-1}	2.474×10^{-1}	4.968×10^{-1}
E_a/E	4.606×10^{-5}	1.667×10^{-4}	1.304×10^{-4}	5.226×10^{-6}	5.107×10^{-6}	1.430×10^{-5}
Γ_R	-3.430×10^{-7}	2.355×10^{-6}	3.419×10^{-6}	-1.644×10^{-8}	-1.657×10^{-8}	1.280×10^{-10}
Γ_M	1.908×10^{-5}	3.724×10^{-5}	4.905×10^{-5}	3.653×10^{-5}	3.262×10^{-6}	3.952×10^{-5}
Γ_J	7.926×10^{-6}	2.389×10^{-5}	2.081×10^{-5}	3.335×10^{-6}	3.570×10^{-5}	3.872×10^{-5}
Γ_v	-1.177×10^{-5}	-1.729×10^{-5}	-1.820×10^{-5}	-4.404×10^{-5}	-1.101×10^{-5}	-3.873×10^{-5}
Γ_η	-3.028×10^{-5}	-3.655×10^{-5}	-4.088×10^{-5}	-4.458×10^{-5}	-1.146×10^{-5}	-3.951×10^{-5}
Γ_{aU}	-9.529×10^{-12}	-1.792×10^{-10}	-1.001×10^{-10}	$< 10^{-10}$	$< 10^{-10}$	$< 10^{-10}$
Γ_{aJ}	1.750×10^{-6}	-9.544×10^{-6}	-5.251×10^{-6}	3.284×10^{-5}	-3.268×10^{-5}	2.595×10^{-9}
Γ_{mech}	-4.183×10^{-6}	8.948×10^{-6}	6.029×10^{-6}	-4.072×10^{-5}	2.467×10^{-5}	-1.219×10^{-8}
Γ_{em}	-9.442×10^{-6}	-8.854×10^{-6}	2.915×10^{-6}	2.479×10^{-5}	-4.088×10^{-5}	1.004×10^{-8}

TABLE 10. Growth rate and phase velocity, energy components, and energy transfer rates for modes F, L_- , L_+ , M, and P_1 in figure 16 for representative values of the Hartmann number in the interval $[0.02, 200]$. For the reasons stated in the caption to figure 12, the relative numerical error in the energy-transfer-rate calculations for mode F at $Ha = 200$ is of order 0.3.

situation is illustrated by the eigenvalue and energy calculations in figure 16 and table 10, evaluated at $Re = 6.3 \times 10^6$, $\alpha = 10^{-4}$, $Pm = 10^{-4}$ and $Ha \in [10^{-2}, 10^3]$, where the latter Hartmann-number interval corresponds to an Alfvén number decrease from 6.3×10^6 ($Ha = 10^{-2}$) to 63 ($Ha = 10^3$). The resulting evolution of the eigenvalues in the complex- c plane is shown in movie 4.

When the Hartmann number is large ($Ha \gtrsim 200$), the travelling Alfvén modes are clearly distinguishable by the linear Ha dependence of their decay rate $|\text{Im}(c)\alpha|$ and of their phase velocity relative to the free-surface steady-state velocity, $\text{Re}(c) - 1$.

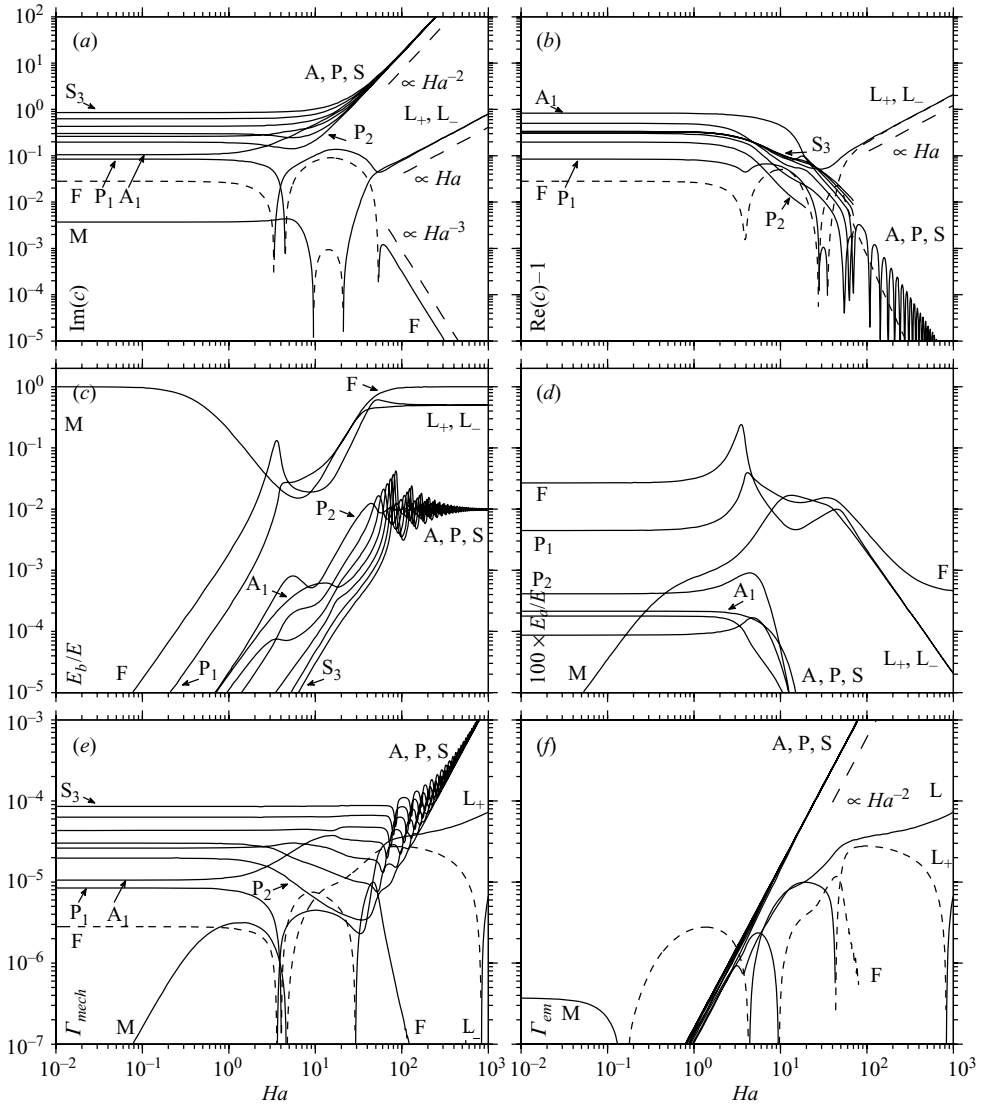


FIGURE 16. Complex phase velocity c , magnetic and surface energies E_b and E_a (normalized by the total energy $E = E_u + E_b + E_a$) and mechanical and surface energy transfer rates Γ_{mech} and Γ_{em} for the 10 least stable modes of free-surface Hartmann flow with insulating boundary conditions at $Re = 6.3 \times 10^6$, $\alpha = 10^{-4}$, $Pm = 10^{-4}$, $Ga = 8.3 \times 10^7$, $Ca = 0.07$ and $Ha \in [10^{-2}, 10^3]$. In (a), (b), (e) and (f), the solid and dashed lines respectively correspond to negative and positive values. The weak-field ($Ha = 0.1$) modes F, M and P_1 respectively become converted to modes L_+ , L_- and F as Ha grows. For $Ha \gtrsim 50$, the $Re(c) - 1$, E_b/E and Γ_{mech} results for modes in the A, P and S families become highly oscillatory. In order to prevent overlapping plotted lines from obscuring this oscillatory behaviour, the $Re(c) - 1$ plots for modes P_2 and higher (in the sense of the growth-rate ordering at $Ha \ll 1$) were terminated at values of the Hartmann number less than 1000. The corresponding Ha evolution of this spectrum in the complex plane is shown in movie 4, available with the online version of the paper.

The nearly equal split between kinetic and magnetic energies remarked upon above is also evident, both in figure 16 and in the $Ha = 200$ results in table 10. The latter also indicate that in light of the smallness of the wavenumber employed in the calculation, the magnetic energy contained in the exterior region exceeds the internal one by more than two orders of magnitude. Interestingly, a duality between the mechanical and electromagnetic energy transfer rates appears to apply between the downstream and upstream waves, in the sense that the mechanical energy transfer rate $\Gamma_{mech} = -4.072 \times 10^{-5}$ for mode L_+ (the downstream-propagating mode) is nearly equal to the Γ_{em} term for mode L_- , and likewise, the $\Gamma_{mech} = 2.467 \times 10^{-5}$ term for mode L_- is close to the electromagnetic energy transfer rate Γ_{em} for mode L_+ . In both cases, however, the energy transfer rates due to Maxwell stress and the current interaction, respectively Γ_M and Γ_J , as well as the surface term Γ_{aJ} are positive, whereas the energy transfer rate due to Reynolds stress, Γ_R , is negative.

At smaller Hartmann numbers (equivalently, larger Alfvén numbers), the upstream-propagating mode tends to be advected along the direction of the basic flow, and for $10 \lesssim Ha \lesssim 20$, the positive mechanical energy transfer rate, driven in part by positive Reynolds stress (see the $Ha = 15$ calculation in table 10), exceeds the rate of energy dissipated electromagnetically, resulting in an instability. As Ha is further decreased, mode L_- is stabilized and becomes converted to mode M; i.e. its energy becomes predominantly magnetic, and its phase velocity C approaches the mean value of the steady-state flow. This mode conversion is different from the one observed in figure 15 and movie 3, where mode L_- develops from weak-field mode A_2 , indicating that the precursors of the Alfvén modes in the weak-field spectrum are not universal.

As for the downstream-propagating wave, L_+ , instead of joining the P eigenvalue branch when Ha is decreased (which would be the case for the flow parameters in figure 15), becomes converted around $Ha = 3$ to mode F; i.e. it has greater than unity phase velocity and for the chosen values of the Reynolds and Galilei numbers, is unstable for $Ha = 0$. At the same time, the strong-field ($Ha \gtrsim 80$) mode labelled F in figure 16, which exhibits the asymptotic neutrality that we ascribed to mode F in figure 8, turns into mode P_1 . This exchange of identity between modes F and P_1 takes place at Reynolds numbers greater than the one employed in our earlier examples at $(Re, \alpha) = (7 \times 10^5, 2 \times 10^{-3})$ and, as can be seen in figure 16 and movie 4, is accompanied by a small Hartmann-number interval in which both modes are stable. The latter gives rise to regions of stability in the (Re, α) plane which would contain unstable modes in the inductionless limit (see figure 10).

The results for mode F in figure 16 also show that the $|\Gamma| \propto Ha^{-2}$ strong-field scaling observed in inductionless problems (e.g. figure 8) does not necessarily apply in the non-zero- Pm flows. In particular, while no such evidence was observed in the calculations in figure 13 for $(Re, \alpha, Pm) = (7 \times 10^5, 2 \times 10^{-3}, 10^{-5})$, the growth rate of mode F for $(Re, \alpha, Pm) = (6.3 \times 10^6, 10^{-4}, 10^{-4})$ follows an inverse-cubic decrease. This is most likely caused by the steady-state current, since, as we have numerically confirmed, setting B to zero restores the $|\Gamma| \propto Ha^{-2}$ scaling.

Before closing, we note that the A, P and S modes that do not participate in the modal interactions described above also exhibit new aspects of behaviour compared to inductionless problems. In particular, as the magnetic field strength grows, their phase velocity experiences a series of oscillations about $C = 1$, of diminishing amplitude (cf. the inductionless calculations in figure 8, where C monotonically approaches unity from below), and so does their magnetic energy as it settles towards an Ha -independent equilibrium value. An intricate pattern of oscillation is also observed for

the mechanical energy dissipation rate $-\Gamma_{mech}$, which now exhibits an increasing trend with $Ha \gg 1$ instead of asymptoting towards Ha -independent values. However, at least for the examined Hartmann-number interval, $|\Gamma_{mech}|$ remains small compared to the rate of electromagnetic energy dissipation $-\Gamma_{em}$, which, dominated by the resistive term Γ_η , grows quadratically with Ha . As a result, the decay rate $-\Gamma = -(\Gamma_{mech} + \Gamma_{em})$ of the A, P and S modes exhibits to a good approximation a $\Gamma \propto Ha^2$ scaling for strong applied fields, as it does in the inductionless limit.

5. Conclusions

A numerical investigation of the stability of temporal normal modes of free-surface Hartmann flow at low magnetic Prandtl numbers ($Pm \leq 10^{-4}$, including the inductionless limit $Pm \searrow 0$) has been presented. Our main objective has been to study the influence of a flow-normal magnetic field (of associated Hartmann number $Ha \leq 1000$) on the soft and hard instability modes present in non-MHD flow down an inclined plane (Yih 1963, 1969; De Bruin 1974; Floryan *et al.* 1987), imposing either insulating or perfectly conducting boundary conditions at the wall.

We have confirmed that the Squire transformation for MHD (Betchov & Criminale 1967) is compatible with the kinematic, stress and magnetic field continuity boundary conditions for free-surface problems, but we found that unless the flow is driven at constant capillary and Galilei numbers, respectively parameterizing the surface tension and the flow-normal gravitational force, the onset of instability as the Reynolds number Re grows is not necessarily governed by a two-dimensional mode.

In inductionless flows, where the magnetic field is treated as a constant background variable, we have observed that the critical Reynolds number Re_c of both of the hard and soft instability modes increases monotonically with Ha . In particular, except for applied fields sufficiently weak for gravity to dominate over Lorentz forces, the hard mode's critical Reynolds number as well as its critical wavenumber α_c and phase velocity C_c were found to be very close to the corresponding parameters of the even unstable mode in channel Hartmann flow (Takashima 1996), reflecting the common, critical layer, nature of these two instabilities. In fact, for sufficiently large Hartmann numbers, the critical Reynolds number of both is well approximated by the linear power law $Re_c(Ha) = 48\,250 Ha$ computed for the critical Reynolds number of the unbounded Hartmann layer (Lingwood & Alboussiere 1999).

As for the soft mode, our numerical calculations have yielded non-zero values for its critical wavenumber α_c (here α denotes the wavenumber) in inductionless problems. Nevertheless, the corresponding values of the critical Reynolds number and phase velocity were found to be in moderately good agreement with closed-form expressions derived under the assumption that α_c is zero (Hsieh 1965; Gupta & Rai 1968; Korsunsky 1999). In particular, using the Galilei number Ga to parameterize the normal gravitational force, from the analytical results it follows that $Re_c \sim (Ga/Ha)^{1/2} \exp(Ha)$ increases exponentially with $Ha \gg 1$, and $C_c \sim 1 + \text{sech}(Ha)$ decreases from its non-MHD value of twice the free-surface steady-state velocity to unity.

As is also the case in channel flow (Takashima 1996), we recorded little variation in the hard mode's critical parameters between the small- Pm problems with insulating boundary conditions and the corresponding inductionless flows. On the other hand, we encountered considerable differences in the stability properties of the soft mode, manifested in the structure of eigenvalue contours in the (Re, α) plane, as well

as in the dependence of its critical parameters on Ha and Pm . Specifically, in problems with an insulating wall, our numerical results, supported by large-wavelength asymptotics, indicate that the $\alpha_c = 0$ axis ceases to be part of the soft mode's neutral-stability curve, and the exponential growth of the critical Reynolds number becomes, for sufficiently large Ha , suppressed to a sub-linearly increasing function. When perfectly conducting boundary conditions are imposed, $Re_c \sim (Ga/Pm)^{1/2} Ha^{-1}$ becomes a decreasing function of the Hartmann number.

The observed Pm sensitivity of the soft instability was attributed to the strong-field behaviour of the participating inductionless mode (here called mode F), which, even though stabilized by the magnetic field, approaches neutral stability as Ha grows and whose energy content becomes almost exclusively gravitational. In particular, its decay rate and kinetic energy respectively decrease like Ha^{-2} and Ha^{-4} , where the latter scaling is consistent with a work balance between gravitational and Lorentz forces. The resulting near equilibrium is distinct from the quadratically increasing Lorentz damping experienced by the shear modes in the A, P and S families (labelled according to the convention of Mack 1976). In particular, it renders mode F susceptible to effects associated the response of the magnetic field to the flow (neglected in the inductionless limit), even when the magnetic diffusivity of the working fluid is large.

Our analysis has identified two ways that non-zero magnetic field perturbations influence the soft instability, both of which depend strongly on the wall boundary conditions. The first is through the component $RePm\mathbf{J} \times \mathbf{b}$ of the Lorentz force associated with the steady-state current \mathbf{J} and the perturbed magnetic field \mathbf{b} . That force, which vanishes in the inductionless limit, results in a positive net energy transfer to mode F, leading in turn to the observed deviation of the critical Reynolds number from its behaviour in the inductionless limit. The fact that \mathbf{J} depends, through the boundary conditions, on the wall conductivity, accounts for the different Re_c results between insulating and conducting-wall problems. In particular, when perfectly conducting boundary conditions are enforced, the magnitude of \mathbf{J} increases without bound with Ha , and the resulting energy transfer to mode F causes $Re_c(Ha)$ to become a decreasing function. On the other hand, in insulating-wall problems \mathbf{J} becomes constant throughout the inner part of the fluid domain, which is consistent with the comparatively milder modification of the soft mode's critical parameters. In this case, however, the boundary conditions are compatible with a stable, large-wavelength mode, which, as we have confirmed by means of asymptotic approximations, is singular in the inductionless limit $Pm \searrow 0$. When Pm is non-zero this magnetic mode couples with mode F, causing the growth rate of the latter to become negative for sufficiently small α , irrespective of the value of the Reynolds number. The resulting large-wavelength instability suppression for all Re is the second major influence of non-zero magnetic field perturbations on the soft instability. As with the effects associated with \mathbf{J} , it too depends strongly on the boundary conditions. That is the magnetic mode is absent from the spectrum when perfectly conducting boundary conditions are imposed, and in the same manner as inductionless flow, the soft instability takes place for arbitrarily small wavenumbers.

Besides the large-wavelength magnetic mode, the spectrum of free-surface Hartmann flow with an insulating wall was found to contain a pair of travelling Alfvén waves, characterized by a near equipartition of the modal energy between the kinetic and magnetic degrees of freedom. At sufficiently high Alfvén numbers, the upstream-propagating wave undergoes an instability where both Reynolds and

Maxwell stresses are positive. Frozen-in analogues of the travelling Alfvén modes (in the sense described by Betchov & Criminale 1967) were encountered in channel Hartmann flow with insulating walls, but they are absent from conducting-wall problems in both free-surface and channel geometries.

To conclude, the analysis presented in this paper highlights the important role played by the magnetic field dynamics and boundary conditions in free-surface Hartmann flow and identifies potential shortcomings of the inductionless approximation. Future work will explore signatures of departure from inductionless behaviour in fully nonlinear time-dependent simulations of free-surface MHD flows and in experiments (Nornberg *et al.* 2008) currently underway at Princeton Plasma Physics Laboratory.

We thank H. Ji and M. Nornberg for useful conversations and the three referees for their constructive comments and criticism. This work was supported by the Mathematical, Information, and Computational Science Division sub-programme of the Office of Advanced Scientific Computing Research and by the Office of Fusion Energy Sciences (field work proposal no. 25145), Office of Science, US Department of Energy, under contract DE-AC02-0611357. DG acknowledges support from the Alexander S. Onassis Public Benefit Foundation.

Appendix. Large-wavelength approximations

A.1. Non-MHD and inductionless problems

A.1.1. Formulation

In non-MHD and inductionless free-surface problems, the Reynolds number Re_b at the bifurcation point $(Re_b, 0)$ of the soft mode's neutral-stability curve, as well as the corresponding phase velocity C_b , can be evaluated in closed form using regular perturbation theory about $\alpha = 0$. Following the standard approach in the literature (e.g. Yih 1963, 1969; Hsieh 1965; Ladikov 1966; Gupta & Rai 1968; Smith & Davis 1982), we start with the expansions $\hat{u}(z) = u_0(z) + \alpha u_1(z) + \alpha^2 u_2(z) + O(\alpha^3)$, $\hat{a} = a_0 + \alpha a_1 + \alpha^2 a_2 + O(\alpha^3)$ and $\gamma = \gamma_0 + \alpha \gamma_1 + \alpha^2 \gamma_2 + O(\alpha^3)$, which, when substituted into the modified OS equation (2.46), lead to a series of ordinary differential equations of the form

$$D^4 u_n + \mu^2 D^2 u_n = s_n, \quad (\text{A } 1)$$

where $n = 0, 1, 2, \dots$ and $\mu^2 := -(H_z^2 + Re\gamma_0)$. Here the source terms s_n vanish for $n = 0$ and depend on the solutions up to order $n - 1$ for $n \geq 1$. In particular, for the first two orders we have

$$\left. \begin{aligned} s_1 &:= Re(\gamma_1 + iU)D^2 u_0 - iRe(D^2 U)u_0 + 2H_x H_z Du_0, \\ s_2 &:= Re(\gamma_1 + iU)D^2 u_1 - iRe(D^2 U)u_1 + 4H_x H_z Du_1 \\ &\quad + (Re\gamma_2 + 2)D^2 u_0 - (H_x^2 + Re\gamma_0)u_1. \end{aligned} \right\} \quad (\text{A } 2)$$

Similarly, the five boundary conditions (2.48*a-c*) and (2.52) lead to

$$u_n(-1) = Du_n(-1) = 0, \quad D^2 u_n(0) = S_n^{(3)}, \quad (\text{A } 3a, b)$$

$$D^3 u_n(0) - \mu^2 Du_n(0) = S_n^{(4)}, \quad u_n(0) - \gamma_0 a_n = S_n^{(5)}, \quad (\text{A } 3c, d)$$

where $S_0^{(4)}, \dots, S_0^{(5)}$ vanish and

$$\left. \begin{aligned} S_1^{(3)} &:= iD^2U(0)a_0, & S_2^{(3)} &:= iD^2U(0)a_1 - u_0(0), \\ S_1^{(4)} &:= Re(\gamma_1 + iU(0))Du_0(0) + i(H_x H_z - ReDU(0))u_0(0), \\ S_2^{(4)} &:= Re(\gamma_1 + iU(0))Du_1(0) + i(H_x H_z - ReDU(0))u_1(0) \\ &\quad + (3 + Re\gamma_2)Du_0(0) + GaRe^{-1}a_0, \\ S_1^{(5)} &:= (\gamma_1 + iU(0))a_0, & S_2^{(5)} &:= (\gamma_1 + iU(0))a_1 + a_0\gamma_2. \end{aligned} \right\} \quad (A 4)$$

We express the general solution to (A 1) as

$$u_n = \sum_{i=0}^3 K_{ni}u_i^{(h)} + u_n^{(p)}, \quad (A 5)$$

where $u_i^{(h)}$ are four linearly independent functions satisfying $D^4u_i^{(h)} + \mu^2D^2u_i^{(h)} = 0$; K_{ni} are constants; and $u_n^{(p)}(z)$ are particular solutions associated with the source terms s_n . The constants K_{ni} and the expansion coefficients a_n for the free-surface oscillation amplitude are to be determined by systems of algebraic equations of the form

$$A_0\mathbf{w}_n = \mathbf{t}_n \quad (A 6)$$

that follow by substituting for u_n in the boundary conditions (A 3) using (A 5). Here

$$A_0 := \begin{pmatrix} u_0^{(h)}(-1) & \dots & u_3^{(h)}(-1) & 0 \\ Du_0^{(h)}(-1) & \dots & Du_3^{(h)}(-1) & 0 \\ D^2u_0^{(h)}(0) & \dots & D^2u_3^{(h)}(0) & 0 \\ (D^3 - \mu^2)u_0^{(h)}(0) & \dots & (D^3 - \mu^2)u_3^{(h)}(0) & 0 \\ u_0^{(h)}(0) & \dots & u_3^{(h)}(0) & \gamma_0 \end{pmatrix} \quad (A 7)$$

is a 5×5 matrix acting on five-element column vectors $\mathbf{w}_n := (K_{n0}, \dots, K_{n3}, a_n)^T$. Also, the column vectors \mathbf{t}_n , which vanish for $n = 0$, are given by

$$\mathbf{t}_n := \begin{pmatrix} -u_n^{(p)}(-1) \\ -Du_n^{(p)}(-1) \\ S_n^{(3)} - D^2u_n^{(p)}(0) \\ S_n^{(4)} - (D^3 - \mu^2D)u_n^{(p)}(0) \\ S_n^{(5)} - u_n^{(p)}(0) \end{pmatrix} \quad (A 8)$$

for $n \geq 1$. Note that A_0 is generally a nonlinear function of γ_0 , while the source vectors \mathbf{t}_n are linear functions of γ_n .

Assuming that A_0 has a q_0 -dimensional right nullspace, denoted by $\ker(A_0)$ (as discussed below, γ_0 will be chosen such that $\ker(A_0)$ is non-trivial), the solution to (A 6) can be expressed as

$$\mathbf{w}_n = R_{A_0}\mathbf{\Pi}_n + \mathbf{w}_n^{(p)}, \quad (A 9)$$

where R_{A_0} is a $5 \times q_0$ matrix whose columns form a basis for $\ker(A_0)$; $\mathbf{\Pi}_n$ is a q_0 -dimensional column vector of free parameters; and $\mathbf{w}_n^{(p)}$ is a particular solution associated with the source term \mathbf{t}_n . Therefore, introducing the notation $\mathbf{v}_n := (u_n, a_n)^T$ and $\mathbf{v}_n^{(p)} := (u_n^{(p)}, 0)^T$, as well as the matrix

$$M := \begin{pmatrix} u_0^{(h)} & \dots & u_3^{(h)} & 0 \\ 0 & \dots & 0 & 1 \end{pmatrix}, \quad (A 10)$$

the solution for the velocity field and the free-surface oscillation amplitude at n th order in perturbation theory becomes

$$\mathbf{v}_n = M R_{A_0} \mathbf{\Pi}_n + M \mathbf{w}_n^{(p)} + \mathbf{v}_n^{(p)}. \tag{A 11}$$

In what follows, we choose the homogeneous solutions

$$u_0^{(h)} := 1, \quad u_1^{(h)} := z, \quad u_2^{(h)} := (1 - \cos(\mu z))/\mu^2, \quad u_3^{(h)} := (\mu z - \sin(\mu z))/\mu^3, \tag{A 12}$$

all of which are well behaved in the limit $\mu \rightarrow 0$, giving, upon substitution into (A 7),

$$A_0 = \begin{pmatrix} 1 & -1 & (1 - \cos \mu)/\mu^2 & (\sin \mu - \mu)/\mu^3 & 0 \\ 0 & 1 & -\sin \mu/\mu & (1 - \cos \mu)/\mu^2 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & \mu^2 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & -\gamma_0 \end{pmatrix}. \tag{A 13}$$

At zeroth order, the homogeneous problem $A_0 \mathbf{w}_0 = 0$ has a non-trivial solution only if A_0 has a non-trivial nullspace or, equivalently,

$$\det(A_0) = \cos(\mu)\gamma_0 = 0. \tag{A 14}$$

The equation above has two distinct classes of roots, given by $\gamma_0 = 0$ and $\gamma_0 = -(H_z^2 + (2n + 1)^2 \pi^2/4)$, where $n = 0, 1, 2, \dots$. Among these, only the zero solution can potentially be connected to a large-wavelength unstable mode, since the eigenvalues associated with the first class of roots approach zero from below as $\alpha \searrow 0$. Setting therefore $\gamma_0 = 0$ equips A_0 with a one-dimensional nullspace spanned by the column vector $\boldsymbol{\xi} := (0, 0, 0, 0, 1)^T$. Thus, the parameter vectors $\mathbf{\Pi}_n$ become scalars, playing the role of normalization constants, and through (A 11), we obtain $\mathbf{v}_0 = (u_0, a_0) = \Pi_0(0, 1)$. We remark that channel problems do not admit asymptotically neutral solutions as $\alpha \searrow 0$; in this case $\det(A_0) = 4(\sin(\mu) - \mu \cos(\mu))/\mu^4$ tends to $4/3$ in the limit $\gamma_0 \rightarrow 0$.

At higher orders in α one has to find solutions to inhomogeneous systems of equations of the form (A 6). Here we will outline an inductive procedure which, given a zeroth-order solution, can be applied to obtain solutions at successively higher orders in α and can also be generalized to treat the coupled differential equations (2.43) governing the non-zero- Pm problems (see § A.2).

First, assume that the eigenvalue coefficients $\gamma_0, \dots, \gamma_{n-1}$ and the corresponding eigenvectors $\mathbf{v}_0, \dots, \mathbf{v}_{n-1}$ have been evaluated to some order $n - 1$, where $n \geq 1$. Moreover, assume that $\{\mathbf{v}_i\}_{i=0}^{n-1}$ are linear and homogeneous functions of q_0 free parameters $\Pi_{n-1,1}, \dots, \Pi_{n-1,q_0}$, i.e.

$$\mathbf{v}_i = D_{i,n-1} \mathbf{\Pi}_{n-1} \tag{A 15}$$

for $2 \times q_0$ matrices $D_{0,n-1}, \dots, D_{n-1,n-1}$ and a q_0 -dimensional column vector $\mathbf{\Pi}_{n-1} := (\Pi_{n-1,1}, \dots, \Pi_{n-1,q_0})^T$. Under these conditions, the particular solution $u_n^{(p)}$, the boundary-condition source terms $S_n^{(1)}, \dots, S_n^{(5)}$ and, by construction, the elements of \mathbf{t}_n at order n are also homogeneous linear functions of $\{\Pi_{n-1,i}\}_{i=1}^{q_0}$. That is we can write

$$\mathbf{t}_n = T_n \mathbf{\Pi}_{n-1}, \tag{A 16}$$

where T_n is a $5 \times q_0$ matrix.

In general, a solution \mathbf{w}_n to (A 6) will only exist if \mathbf{t}_n lies in the range of A_0 , denoted by $\text{ran}(A_0)$. According to the fundamental theorem of linear algebra (e.g. Strang 2005), $\text{ran}(A_0)$ is the orthogonal complement, in the sense of the Euclidean inner

product, of the left nullspace of A_0 , which we denote by $\ker(A_0^T)$. Thus, noting that $\ker(A_0^T)$ is q_0 -dimensional (this is a further consequence of the fundamental theorem), a solution to (A 6) exists if and only if $L_{A_0}^T t_n = 0$, where L_{A_0} is a $5 \times q_0$ matrix whose columns form a basis of $\ker(A_0^T)$. It therefore follows from (A 16) that a solvability condition for (A 6) is that the $q_0 \times q_0$ matrix $A_n := L_{A_0}^T T_n$ has a non-trivial nullspace, i.e. $\det(A_n) = 0$. Since $\det(A_n)$ is a polynomial in γ_n of degree no greater than q_0 (recall that the elements of t_n depend linearly on γ_n), the latter equation yields up to q_0 distinct solutions for the n th order expansion coefficient γ_n .

Denoting the dimension of $\ker(A_n)$ corresponding to a given solution for γ_n by $q_n \leq q_0$ (the procedure can be repeated for each of the roots of $\det(A_n) = 0$), we now express the parameter vector Π_{n-1} as

$$\Pi_{n-1} = R_{A_n} \tilde{\Pi}_n, \tag{A 17}$$

where R_{A_n} is a $q_0 \times q_n$ matrix whose columns are basis vectors for $\ker(A_n)$ and $\tilde{\Pi}_n := (\tilde{\Pi}_{n,1}, \dots, \tilde{\Pi}_{n,q_n})^T$ is an updated vector of free parameters in the solution. We note that the column rank of the $q_0 \times q_n$ matrix R_{A_n} is q_n by construction. (Its columns are linearly independent vectors.) Moreover, because the row rank and the column rank of any matrix are equal, its row space (i.e. $\text{ran}(R_{A_n}^T)$) is q_n -dimensional, and its left nullspace $\ker(R_{A_n}^T)$ is $(q_0 - q_n)$ -dimensional.

Upon substitution into (A 15), (A 17) leads potentially to a decrease in the number of degrees of freedom in the eigenfunctions of order up to $n - 1$, as well as in $w_n^{(p)}$ (through its dependence on t_n), from q_0 to q_n . Moreover, since the particular solution $u_n^{(p)}$ to (A 1) also depends linearly and homogeneously on $\tilde{\Pi}_n$, it is possible to recast (A 11) as

$$v_n = M R_{A_0} \Pi'_n + \tilde{D}_n \tilde{\Pi}_n, \tag{A 18}$$

where Π'_n is a (provisional) q_0 -dimensional column vector of free parameters and \tilde{D}_n is a $2 \times q_n$ matrix such that $\tilde{D}_n \tilde{\Pi}_n = M w_n^{(p)} + v_n^{(p)}$. Although (A 18) may contain up to $q_0 + q_n$ arbitrary constants, the part of Π'_n that is parallel to Π_{n-1} can be set to zero, since its only effect would be a renormalization of the lower-order solutions. We therefore require that $R_{A_n}^T \Pi'_n$ vanishes or, equivalently,

$$\Pi'_n = E_n \hat{\Pi}_n, \tag{A 19}$$

where E_n is a $q_0 \times (q_0 - q_n)$ matrix whose columns form a basis of the left nullspace of R_{A_n} and $\hat{\Pi}_n$ is a $(q_0 - q_n)$ -dimensional column vector. If q_0 happens to equal unity, one can set Π'_n equal to zero. Inserting (A 19) into (A 18), we then obtain $v_n = \hat{D}_n \hat{\Pi}_n + \tilde{D}_n \tilde{\Pi}_n$, where $\hat{D}_n := M R_{A_0} E_n$, or

$$v_n = D_{n,n} \Pi_n, \tag{A 20}$$

where $D_{n,n} := (\hat{D}_n, \tilde{D}_n)$ and $\Pi_n := (\hat{\Pi}_n^T, \tilde{\Pi}_n^T)^T$ are a $2 \times q_0$ matrix and a q_0 -dimensional column vector, respectively. The lower-order solutions can also be written in terms of Π_n using

$$v_i = D_{i,n} \Pi_n, \quad D_{i,n} := (0_{2 \times (q_0 - q_n)}, D_{i,n-1} R_{A_n}), \quad i = 0, \dots, n - 1, \tag{A 21}$$

where $0_{2 \times (q_0 - q_n)}$ denotes the zero matrix of size $2 \times (q_0 - q_n)$.

The matrices $D_{0,n}, \dots, D_{n,n}$ fully specify the perturbative expansion to n th order, which, as assumed above, is a linear homogeneous function of q_0 parameters. The procedure can be repeated for successively higher orders in α , but since the solutions for the expansion coefficients rapidly become complicated beyond first order, it is

convenient to implement it in a symbolic-mathematics programming language so as to minimize effort and error probability.

A.1.2. Results at first and second orders

We now apply the procedure described in § A.1.1 to evaluate the first- and second-order corrections to the zeroth-order solution $(\gamma_0, u_0, a_0) = (0, 0, \Pi_0)$. Setting $U(z)$ equal to the Hartmann velocity profile ((2.26a) with $C_0 = C_1 = 0$) and the streamwise component of the applied magnetic field equal to zero (i.e. $H_x = 0$ and $H_z = Ha$) the first-order expansion terms for the eigenvalue and the velocity eigenfunction are found to be

$$i\gamma_1 = 1 + \operatorname{sech}(Ha), \quad u_1(z) = -i\Pi_0 \operatorname{sech}(Ha) \sinh^2(Ha(1+z)/2) / \sinh^2(Ha/2), \quad (\text{A } 22)$$

while the coefficient for the free-surface amplitude a_1 vanishes. We remark that since γ_1 is purely imaginary, the $\alpha = 0$ axis is part of the neutral-stability curve $0 = \operatorname{Im}(c) = \operatorname{Re}(\gamma_1) + \alpha \operatorname{Re}(\gamma_2) + O(\alpha^2)$ in the (Re, α) plane. Moreover, the leading-order phase velocity $C_0 := i\gamma_1$ is a monotonically decreasing function of the Hartmann number, with $C_0 \searrow 1$ as $Ha \rightarrow \infty$. As for the eigenfunction $u_1(z)$, it varies exponentially with the flow-normal coordinate, and like the Hartmann velocity profile, it possesses a boundary layer of thickness $O(1/Ha)$ near the no-slip wall. In the vanishing magnetic field limit ($Ha \searrow 0$), C_0 is twice the steady-state velocity at the free surface and u_1 reduces to the quadratic function $u_1(z) = -i\Pi_0(1+z)^2$, as computed by Yih (1963, 1969) for non-MHD flow down an inclined plane.

Proceeding now with the second-order approximation

$$\gamma_2 = \frac{Re \operatorname{coth}(Ha/2) \operatorname{sech}^3(Ha)(2Ha(2 + \cosh(2Ha)) - 3 \sinh(2Ha))}{Ha^2(\cosh(Ha) - 1)} - \frac{8Ga \sinh^2(Ha/2)(Ha - \tanh(Ha))}{Ha^3 Re(\cosh(Ha) - 1)} \quad (\text{A } 23)$$

is the leading-order coefficient for γ with non-zero real part, governing the modal stability in the limit $\alpha \searrow 0$. In particular, setting γ_2 equal to zero and solving for Re leads to (4.1a), quoted in the main text for the Reynolds number Re_b at the bifurcation point $(Re_b, 0)$. That is γ_2 is negative for $0 < Re < Re_b$ but becomes positive for all $Re > Re_b$. For weak magnetic fields $Re_b/Ga^{1/2} = (5/8)^{1/2} + 191/(168 \times 10^{1/2})Ha^2 + O(Ha^4)$ grows quadratically with Ha , but when the Hartmann number is large, $Re_b/Ga^{1/2} \sim \exp(Ha)/Ha^{1/2}$ increases exponentially. Moreover, since γ_1 is independent of Re , the phase velocity C_b at the bifurcation point is equal to the zeroth-order phase velocity C_0 , in accordance with (4.1b). We remark that the result $Re_b = (5Ga/8)^{1/2}$ for zero magnetic field strength is consistent with (38) in the paper by Yih (1963), under the proviso that Re is replaced by $Re' := 2Re/3$ (Yih chooses the mean steady-state velocity as the characteristic velocity for reduction to non-dimensional form), and the inclination angle θ is substituted for Ga using (2.41). Likewise, (4.1a) is in agreement with the instability criteria by Hsieh (1965), Gupta & Rai (1968) and Korsunsky (1999). (Note, however, the numerical results in figure 6 and table 3, which indicate that critical Reynolds number Re_c is less than Re_b .)

In order to assess the relative importance of the formation of the Hartmann velocity profile versus the Lorentz force in the behaviour of Re_b and C_b , we have carried out similar large-wavelength calculations for (physically unrealistic) problems with (i) the Hartmann velocity profile but no Lorentz force (i.e. Ha set to zero in (A 1)–(A 4)) and (ii) the Lorentz force included but the velocity profile set to the $U(z) = 1 - z^2$

Poiseuille solution. The results for the perturbation-expansion coefficients for the complex growth rate γ are

$$i\gamma_1 = 1 + (Ha/2)^2 / \sinh^2(Ha/2), \quad (\text{A } 24a)$$

$$\gamma_2 = -\frac{Ga}{3Re} + \frac{Re(432 - 24Ha^2 - 22Ha^4 + 5Ha^6 - 432 \cosh(Ha) + 240Ha \sinh(Ha))}{192Ha^2 \sinh^4(Ha/2)} \quad (\text{A } 24b)$$

and

$$i\gamma_1 = 1 + 2(1 - \text{sech}(Ha))/Ha^2, \quad (\text{A } 25a)$$

$$\begin{aligned} \gamma_2 = & -Ga(Ha - \tanh(Ha))/(ReHa^3) + Re(72 + 12 \text{sech}^2(Ha)(4 + Ha \tanh(Ha)) \\ & - \text{sech}(Ha)(3(40 + 9Ha^2) + Ha(2Ha^2 - 3) \tanh(Ha)))/(6Ha^6), \end{aligned} \quad (\text{A } 25b)$$

respectively for cases (i) and (ii). As above, the phase velocity $C_b = C_0 = -i\gamma_1$ at the bifurcation point follows directly from the first-order coefficients, while setting (A 24b) and (A 25b) to zero and solving for Re leads to the expressions

$$Re_b = \frac{4HaGa^{1/2}(\cosh(Ha) - 1)}{((18 + 5Ha^2)(24 - 8Ha^2 + Ha^4) - 432 \cosh(Ha) + 240Ha \sinh(Ha))^{1/2}} \quad (\text{A } 26)$$

and

$$\begin{aligned} Re_b = & 2Ha(3Ga \cosh(Ha)(Ha \cosh(Ha) - \sinh(Ha)))^{1/2} \\ & \times (-3(40 + 9Ha^2 + (40 + 9Ha^2) \cosh(2Ha) - 12 \cosh(3Ha) - 8Ha \sinh(Ha)) \\ & + \cosh(Ha)(204 + 2Ha(3 - 2Ha^2) \sinh(Ha)))^{-1/2}, \end{aligned} \quad (\text{A } 27)$$

for the position of the bifurcation point on the $\alpha = 0$ axis. These two types of test problems have different strong-field behaviour, with

$$Re_b \sim Ga^{1/2}(Ha/15)^{1/2} \exp(Ha/2), \quad C_b - 1 \sim (Ha/2)^2 \exp(-Ha), \quad \gamma_2 \sim -Ga/3Re \quad (\text{A } 28a-c)$$

and

$$Re_b \sim Ga^{1/2}Ha^2/3, \quad C_b - 1 \sim 2/Ha^2, \quad \gamma_2 \sim -Ga/(ReHa^2), \quad (\text{A } 29a-c)$$

respectively, for $Ha \gg 1$.

A.1.3. Fourth-order analysis for non-MHD flows

The existence of a bifurcation point $(Re_b, 0)$ on the neutral-stability curve $\text{Im}(c(Re, \alpha)) = 0$ provides a lower bound for the critical Reynolds number Re_c , but it is not necessarily true that Re_b and Re_c coincide. Here, by extending the perturbative series to fourth order in α we determine that for sufficiently large Galilei numbers the critical Reynolds number is in fact smaller than Re_b . The objective of the present calculation is to evaluate the gradient $dRe/d\alpha$ of the neutral-stability curve with respect to the wavenumber at the bifurcation point; a negative $dRe/d\alpha|_{Re=Re_b}$ would then imply that there exist unstable modes with $Re < Re_b$ and $\alpha > 0$ in the neighbourhood of $(Re_b, 0)$.

Proceeding in a similar manner as in the preceding sections, we compute the coefficients γ_3 and γ_4 in the expansion $\gamma = \sum_{n>0} \gamma_n \alpha^n$ for the eigenvalue of the soft mode. (We remark that this procedure would be very laborious if carried out by

hand but can be implemented in a relatively straightforward manner using symbolic-mathematics software.) As with γ_1 , the coefficient γ_3 has vanishing real part, which implies that $\Gamma_2(Re, \alpha) + \alpha^2 \Gamma_4(Re, \alpha) + O(\alpha^3) = 0$ holds on the neutral-stability curve (here $\Gamma_k = \text{Re}(\gamma_k)$). By differentiating the latter expression with respect to Re , the relation $dRe/d\alpha = -2\alpha \Gamma_4 / (d\Gamma_2/dRe) + O(\alpha^2)$ follows, which, combined with the result $(d\Gamma_2/dRe)|_{Re=Re_b} = 16/15 > 0$ (obtained e.g. by taking the limit $Ha \searrow 0$ in (A 23) and differentiating with respect to Re), implies in turn that the sign of $dRe/d\alpha|_{Re=Re_b}$ is determined by the sign of $\Gamma_4|_{Re=Re_b}$. In particular, $\Gamma_4|_{Re=Re_b}$ is found to obey

$$\Gamma_4|_{Re=Re_b} = -1/(3Ca) + (Ga/10)^{1/2}(K_1 Ga - K_2) \tag{A 30}$$

with $K_1 = 2/135,135$ and $K_2 = 2581/560$. From this we deduce that for any $Ca > 0$ there exists a minimum Galilei number Ga_m such that $\Gamma_4|_{Re=Re_b}$ is positive for $Ga > Ga_m$, and correspondingly $(dRe/d\alpha)|_{Re=Re_b}$ is negative.

A.2. Non-zero-Pm problems

The method described in §A.1.1 can be used to study the large-wavelength limit of the coupled OS and induction equations (2.43), with the addition that apart from the expansions for γ , \hat{u} and \hat{a} , we write $\hat{b}(z) = b_0(z) + \alpha b_1(z) + \alpha^2 b_2(z) + O(\alpha^3)$ for the magnetic field eigenfunction. Moreover, (A 1) is replaced by coupled differential equations, which, in the special case with flow-normal external magnetic field, have the form

$$\left. \begin{aligned} D^4 u_n - Re \gamma_0 D^2 u_n + Ha Pm^{-1/2} D^3 b_n &= s_n^{(u)}, \\ D^2 b_n - Rm \gamma_0 b_n + Ha Pm^{1/2} D u_n &= s_n^{(b)}. \end{aligned} \right\} \tag{A 31}$$

As in §A.1, we are interested in perturbation order $n \leq 2$, where $s_0^{(u)} = s_0^{(b)} = 0$ and

$$\left. \begin{aligned} s_1^{(u)}/Re &:= (\gamma_1 + iU)D^2 u_0 - i(D^2 U)u_0 + i(D^2 B_x)b_0 - iB_x D^2 b_0, \\ s_1^{(b)}/Rm &:= (\gamma_1 + iU)b_0 - iB_x u_0, \\ s_2^{(u)}/Re &:= (\gamma_1 + iU)D^2 u_1 - i(D^2 U)u_1 + i(D^2 B_x)b_1 - iB_x D^2 b_1 \\ &\quad + (\gamma_2 + 2Re^{-1})D^2 u_0 - \gamma_0 u_0, \\ s_2^{(b)}/Rm &:= (\gamma_1 + iU)b_1 - iB_x u_1 + (\gamma_2 + Rm^{-1})b_0. \end{aligned} \right\} \tag{A 32}$$

Among the boundary conditions, which are now seven, the no-slip, shear-stress and kinematic conditions, respectively (2.48a-c), have the same expansions as (A 3 a, b, d), but the boundary condition for the normal stress (2.48d) now yields

$$D^3 u_n(0) - Re \gamma_0 D u_n(0) + Ha Pm^{-1/2} D b_n(0) = S_n^{(4)}, \tag{A 33}$$

where $S_0^{(4)} = 0$ and

$$\left. \begin{aligned} S_1^{(4)}/Re &:= (\gamma_1 - iU(0))D u_0(0) - i(DU(0))u_0(0) + i(DB_x(0))b_0(0), \\ S_2^{(4)}/Re &:= (\gamma_1 + iU(0))D u_1(0) - i(DU(0))u_1(0) + i(DB_x(0))(0)b_1(0) \\ &\quad + (3Re^{-1} + \gamma_2)D u_0(0) + Ga Re^{-2} a_0 + Ha Pm Re^{-1} b_0(0). \end{aligned} \right\} \tag{A 34}$$

In problems with an insulating wall, the magnetic field boundary conditions (2.50) lead in addition to

$$D b_n(-1) = S_n^{(6)} \quad \text{and} \quad D b_n(0) = S_n^{(7)}, \tag{A 35a, b}$$

respectively, where $S_0^{(6)} = S_0^{(7)} = 0$ and, for $n \in \{1, 2\}$, $S_n^{(6)} := b_{n-1}(-1)$ and $S_n^{(7)} := iDB_x(0)a_{n-1} - b_{n-1}(0)$. When the wall is perfectly conducting, the boundary condition at $z = -1$ is replaced with $b_n(-1) = 0$, in accordance with (2.51).

Following an analogous approach as in (A 5), we express the general solution to (A 31) at order n as

$$(u_n, b_n) = \sum_{i=0}^5 K_{ni}(u_i^{(h)}, b_i^{(h)}) + (u_n^{(p)}, b_n^{(p)}), \tag{A 36}$$

where $\{(u_i^{(h)}, b_i^{(h)})\}_{i=0}^5$ are six linearly independent solutions to the homogeneous parts of (A 31) and $(u_n^{(p)}, b_n^{(p)})$ are particular solutions dependent on the source terms $(s_n^{(u)}, s_n^{(b)})$. Due to the high order of the differential equations involved, instead of seeking expressions for $(u_i^{(h)}, b_i^{(h)})$ for arbitrary γ_0 , we shall set $\gamma_0 = 0$ from the outset, which is the solution of interest for large-wavelength instabilities. We will verify subsequently that the resulting matrix A_0 (the $Pm > 0$ analogue of (A 13)) possesses a non-trivial nullspace. Choosing then

$$\left. \begin{aligned} (u_0^{(h)}(z), b_0^{(h)}(z)) &:= (1, 0), & (u_1^{(h)}(z), b_1^{(h)}(z)) &:= (z, -HaPm^{1/2}z^2/2), \\ (u_2^{(h)}(z), b_2^{(h)}(z)) &:= ((\cosh(Ha z) - 1)/Ha^2, -Pm^{1/2}(\sinh(Ha z) - Ha z)/Ha^2), \\ (u_3^{(h)}(z), b_3^{(h)}(z)) &:= \left(\frac{\sinh(Ha z) - Ha z}{Ha^3}, -Pm^{1/2} \frac{\cosh(Ha z) - 1 - (Ha z)^2/2}{Ha^3} \right), \\ (u_4^{(h)}(z), b_4^{(h)}(z)) &:= (0, 1), & (u_5^{(h)}(z), b_5^{(h)}(z)) &:= (0, z) \end{aligned} \right\} \tag{A 37}$$

as a set of linearly independent solutions to the homogeneous part of (A 31), valid for $\gamma_0 = 0$, and substituting $(u_0, b_0) = \sum_{i=0}^5 K_{0i}(u_i^{(h)}, b_i^{(h)})$ into the zeroth-order boundary conditions leads to the homogeneous algebraic equations $A_0 w_0 = 0$, where $w_0 := (K_{00}, \dots, K_{05}, a_0)^T$ is a seven-element column vector and A_0 is a 7×7 matrix. In problems with an insulating wall, A_0 is given by

$$A_0 = \begin{pmatrix} 1 & -1 & (\cosh(Ha) - 1)/Ha^2 & (Ha - \sinh(Ha))/Ha^3 & 0 & 0 & 0 \\ 0 & 1 & -\sinh(Ha)/Ha & (\cosh(Ha) - 1)/Ha^2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & -Ha^2 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & HaPm^{1/2} & -Pm^{1/2}(\cosh(Ha) - 1)/Ha & Pm^{1/2}(\sinh(Ha) - Ha)/Ha^2 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}, \tag{A 38}$$

where rows 1–7 respectively result from (A 3a, b), (A 33), (A 35a, b) and (A 3d). In conducting-wall problems, A_0 has the same form as above but with the sixth row, originating from the wall boundary condition for \hat{b} , replaced by

$$(A_{6,j}) = \left(0, -\frac{HaPm^{1/2}}{2}, Pm^{1/2} \frac{\sinh(Ha) - Ha}{Ha^2}, Pm^{1/2} \frac{2 + Ha^2 - 2 \cosh(Ha)}{2Ha^3}, 1, -1, 0 \right). \tag{A 39}$$

The presence of all-zero columns in (A 38), as well as in the matrix resulting from (A 38) with the substitution (A 39), confirms our earlier assertion that setting γ_0 equal to zero endows A_0 with a non-trivial nullspace. In the insulating-wall case that nullspace has dimension $q_0 := 2$ and is spanned by the column vectors $\xi_1 := (0, 0, 0, 0, 0, 0, 1)^T$ and $\xi_2 := (0, 0, 0, 0, 1, 0, 0)^T$, respectively corresponding to a free-surface displacement with zero velocity and magnetic field perturbations (as in inductionless problems) and a uniform flow-normal magnetic field perturbation with no change in either \hat{u} or \hat{a} . In problems with a perfectly conducting wall the latter option is not available, since the magnetic field must vanish at the wall; here $\ker(A_0)$ is one-dimensional and spanned by ξ_1 .

According to the discussion in §A.1.1, the two-dimensionality of $\ker(A_0)$ implies that in insulating-wall problems there exist up to two solutions for the first-order expansion coefficient γ_1 , and carrying out the procedure outlined in that section establishes that this is indeed the case. However, unlike inductionless problems, the resulting expressions for γ_1 , which we denote by $\gamma_1^{(F)}$ and $\gamma_1^{(M)}$, both possess negative real parts for all $Ha > 0$. Therefore, when Pm is non-zero all unstable inductionless modes acquire negative growth rate for sufficiently small $\alpha > 0$, and the $\alpha = 0$ axis is no longer part of the neutral-stability curve $\text{Im}(c) = 0$.

Explicit expressions for $\gamma_1^{(F)}$ and $\gamma_1^{(M)}$ in terms of $\{Re, Ha, Pm\}$ are complicated and not particularly illuminating. However, their salient properties are revealed by means of the series approximations

$$\gamma_1^{(F)} = -\frac{32Ha^2Rm}{15(9 + 4Rm^2)} - i \left(2 - \frac{13Ha^2}{90} - \frac{16Ha^2}{5(9 + 4Rm^2)} \right) + O(Ha^4), \tag{A 40a}$$

$$\gamma_1^{(M)} = -\frac{2(3 + Ha^2)}{3Rm} + \frac{32Ha^2Rm}{15(9 + 4Rm^2)} - i \left(\frac{2}{3} + Ha^2 \left(\frac{1}{90} + \frac{16}{5(9 + 4Rm^2)} \right) \right) + O(Ha^4) \tag{A 40b}$$

and

$$\gamma_1^{(F)} = -\frac{Rm(\cosh(4Ha) - 1 - 16Ha^2 - 8Ha^2 \cosh(2Ha)) \tanh(Ha) + 16Ha^3}{64Ha^3 \sinh^4(Ha/2) \cosh^2(Ha)} - i(1 + \text{sech}(Ha)) + O(Pm^2), \tag{A 41a}$$

$$\gamma_1^{(M)} = -\frac{2Ha \coth(Ha)}{Rm} - i \frac{\cosh(Ha) - 2Ha \text{csch}(Ha) + \text{sech}(Ha)}{\cosh(Ha) - 1} + O(Pm), \tag{A 41b}$$

respectively valid for small Ha and Pm . Inspecting (A 40) and (A 41), we deduce that among the two solutions $\gamma_1^{(M)}$ is singular in the inductionless limit $Pm \searrow 0$, whereas $\gamma_1^{(F)}$ tends to the result (A 22) for the first-order expansion coefficient for mode F obtained in §A.1.2. For small Hartmann numbers the mode associated with $\gamma_1^{(M)}$, referred to in §4.3.1 as the magnetic mode, has negative growth rate and propagates with phase velocity close to the $\langle U \rangle = 2/3$ mean value of the Poiseuille profile. On the other hand, mode F becomes neutral as $Ha \searrow 0$ (that is $\text{Re}(\gamma_1^{(F)}) \nearrow 0$) and propagates at twice the steady-state velocity at the free surface irrespective of the value of the magnetic Prandtl number. A similar procedure applied for problems with $U = B = 0$, but $Ha \geq 0$, yields

$$\gamma_1^{(F)} = 0, \quad \gamma_1^{(M)} = -2Ha \coth(Ha)/Rm, \tag{A 42}$$

indicating that the magnetic mode is stable even in the absence of a steady-state flow, whereas mode F becomes neutral to first order in α .

Because in insulating-wall problems $\text{Re}(\gamma_1^{(F)})$ is negative for all $Pm > 0$ and $Ha > 0$, the second-order approximation in α is not relevant for the stability of mode F in the limit $\alpha \searrow 0$, and for this reason we will not pursue it here. On the other hand, the analysis for problems with a perfectly conducting wall, where, as discussed above, $\ker(\mathbf{A}_0)$ is one-dimensional, leads to the result that as in inductionless problems, the leading-order coefficient in the expansion for γ with non-zero real part is γ_2 , which, in addition to Re , Ga and Ha , now depends on Pm . Solving for Re in the equation $\gamma_2(Re, Ga, Ha, Pm) = 0$, we obtain

$$\begin{aligned} Re_b = & 8 \cosh(Ha) \sinh(Ha/2)^2 Ga^{1/2} (Ha \cosh(Ha) - \sinh(Ha))^{1/2} \\ & / (Ha(2(3 + (7 + 17Ha^2)Pm) \cosh(Ha) + ((13Ha^2 - 12)Pm - 6) \cosh(3Ha) \\ & + (Ha^2 - 1)Pm \cosh(5Ha) + Ha(2(6 + 7Pm) \sinh(Ha) + (4 + 5Pm) \sinh(3Ha) \\ & - Pm \sinh(5Ha))))^{1/2} \end{aligned} \quad (\text{A } 43)$$

for the Reynolds number Re_b at the bifurcation point of the neutral-stability curve, which in this case includes the $\alpha = 0$ axis. Moreover, the first-order coefficient γ_1 and, in turn, the phase velocity C_b at the bifurcation point are found to be given by the same expressions as in inductionless problems, namely (A 22) and (4.1b), respectively. For small Hartmann numbers and provided that Pm is also small, $Re_b/Ga^{1/2} = (5/8)^{1/2} + (191 - 25Pm)Ha^2/(168 \times 10^{1/2}) + O(Ha^4)$ increases quadratically with Ha , but for strong magnetic fields $Re_b \sim (Ga/Pm)^{1/2} Ha^{-1}$ becomes inversely proportional to the Hartmann number (cf. the exponentially increasing Re_b in inductionless problems).

REFERENCES

- ABDOU, M. A., THE APEX TEAM, YING, A., MORLEY, N., GULEC, K., SMOLENTSEV, S., KOTSCHENREUTHER, M., MALANG, S., ZINKLE, S., ROGNLIEN, T., FOGARTY, P., NELSON, B., NYGREN, R., MCCARTHY, K., YOUSSEF, M. Z., GHONIEM, N., SZE, D., WONG, C., SAWAN, M., KHATER, H., WOOLLEY, R., MATTAS, R., MOIR, R., SHARAFAT, S., BROOKS, J., HASSANEIN, A., PETTI, D., TILLACK, M., ULRICKSON, M. & UCHIMOTO, T. 2001 On the exploration of innovative concepts for fusion chamber technology. *Fusion Engng Design* **54**, 181.
- ALEXAKIS, A. *et al.* 2004 On heavy element enrichment in classical novae. *Astrophys. J.* **602**, 931.
- ALPHER, R. A., HURWITZ, H., JR., JOHNSON, R. H. & WHITE, D. R. 1960 Some studies of free-surface mercury magnetohydrodynamics. *Rev. Mod. Phys.* **32** (4), 758.
- BALBUS, S. A. & HENRI, P. 2007 On the magnetic Prandtl number behaviour of accretion disks. *Astrophys. J.* **674**, 408.
- BATCHELOR, G. K. 1967 *An Introduction to Fluid Dynamics*. Cambridge University Press.
- BETCHOV, R. & CRIMINALE, O. 1967 *Stability of Parallel Flows*. Academic.
- BILDSTEN, L. & CUTLER, C. 1995 Nonradial oscillations in neutron star oceans: a source of quasi-periodic X-ray oscillations. *Astrophys. J.* **449**, 800.
- BÜHLER, L. 2007 Liquid metal magnetohydrodynamics for fusion blankets. In *Magnetohydrodynamics – Historical Evolution and Trends: Fluid Mechanics and its Applications* (ed. S. Molokov, R. Moreau & H. K. Moffatt), vol. 80, p. 171. Springer.
- DE BRUIN, G. J. 1974 Stability of a layer of liquid flowing down an inclined plane. *J. Engng Math.* **8** (3), 259.
- DONGARRA, J. J., STRAUGHAN, B. & WALKER, D. W. 1996 Chebyshev τ - QZ algorithm methods for calculating spectra of hydrodynamic stability problems. *Appl. Numer. Math.* **22**, 399.
- DRAZIN, P. G. & REID, W. H. 2004 *Hydrodynamic Stability*, 2nd edn. Cambridge University Press.
- FLORYAN, J. M., DAVIS, S. H. & KELLY, R. E. 1987 Instabilities of a liquid film flowing down a slightly inclined plane. *Phys. Fluids* **30** (4), 983.

- GIANNAKIS, D., FISCHER, P. F. & ROSNER, R. 2009 A spectral Galerkin method for the coupled Orr–Sommerfeld and induction equations for free-surface MHD. *J. Comput. Phys.* **228**, 1188. DOI:10.1016/j.jcp.2008.10.016.
- GORDEEV, YU. N. & MURZENKO, V. V. 1990 Wave flows of a conducting viscous fluid film in a transverse magnetic field. *Appl. Math. Theor. Phys.* **3**, 96.
- GROSCH, C. E. & SALWEN, H. 1964 The stability of steady and time-dependent plane Poiseuille flow. *J. Fluid Mech.* **18**, 350.
- GUPTA, A. S. & RAI, L. 1968 Hydromagnetic stability of a liquid film flowing down an inclined conducting plane. *J. Phys. Soc. Jpn* **24** (3), 626.
- HO, L. W. 1989 A Legendre spectral element method for simulation of incompressible unsteady viscous free-surface flows. PhD thesis, Massachusetts Institute of Technology, Cambridge, MA.
- HSIEH, D. Y. 1965 Stability of a conducting fluid flowing down an inclined plane in a magnetic field. *Phys. Fluids* **8** (10), 1785.
- HUNT, J. C. R. 1966 On the stability of parallel flows with parallel magnetic fields. *Proc. R. Soc. A* **293** (1434), 342.
- JI, H., FOX, W., PACE, D. & RAPPAPORT, H. L. 2005 Study of magnetohydrodynamic surface waves on liquid gallium. *Phys. Plasmas* **12**, 012102.
- KELLY, R. E., GOUSSIS, D. A., LIN, S. P. & HSU, F. K. 1989 The mechanism for surface wave instability in film flow down an inclined plane. *Phys. Fluids A* **1**, 819.
- KIRCHNER, N. P. 2000 Computational aspects of the spectral Galerkin FEM for the Orr–Sommerfeld equation. *Intl J. Numer. Meth. Fluids* **32**, 119.
- KORSUNSKY, S. 1999 Long waves on a thin layer of conducting fluid flowing down an inclined plane in an electromagnetic field. *Eur. J. Mech. B* **18** (2), 295.
- LADIKOV, YU. P. 1966 Flow stability of a conducting liquid flowing down an inclined plane in the presence of a magnetic field. *Fluid Dyn.* **1** (1), 1.
- LAM, T. T. & BAYAZITOGU, Y. 1986 Solution to the Orr–Sommerfeld equation for liquid film flowing down an inclined plane: an optimal approach. *Intl J. Numer. Meth. Fluids* **6**, 883.
- LIN, C. C. 1944 On the stability of two-dimensional parallel flows. *Proc. Natl Acad. Sci. USA* **30**, 316.
- LIN, S. P. 1967 Instability of a liquid film flowing down an inclined plane. *Phys. Fluids* **10** (2), 308.
- LINGWOOD, R. J. & ALBOUSSIERE, T. 1999 On the stability of the Hartmann layer. *Phys. Fluids* **11** (8), 2058.
- LOCK, R. C. 1955 The stability of the flow of an electrically conducting fluid between parallel planes under a transverse magnetic field. *Proc. R. Soc. Lond. A* **233**, 1192.
- LU, P. C. & SARMA, G. S. R. 1967 Magnetohydrodynamic gravity–capillary waves in a liquid film. *Phys. Fluids* **10** (11), 2339.
- MACK, L. M. 1976 A numerical study of the temporal eigenvalue spectrum of the Blasius boundary layer. *J. Fluid Mech.* **73** (3), 497.
- MELENK, J. M., KIRCHNER, N. P. & SCHWAB, C. 2000 Spectral Galerkin discretization for hydrodynamic stability problems. *Computing* **65**, 97.
- MUKHOPADHYAY, A., DANDAPAT, B. S. & MUKHOPADHYAY, A. 2008 Stability of conducting liquid flowing down an inclined plane at moderate Reynolds number in the presence of constant electromagnetic field. *Intl J. Non-Linear Mech.* **43**, 632.
- MÜLLER, U. & BÜHLER, L. 2001 *Magneto-fluid dynamics in Channels and Containers*. Springer.
- NORNBERG, M. D., JI, H., PETERSON, J. L. & RHOADS, J. R. 2008 A liquid metal flume for free surface magnetohydrodynamic experiments. *Rev. Sci. Instrum.* **79**, 094501.
- ORSZAG, S. A. 1971 Accurate solution of the Orr–Sommerfeld stability equation. *J. Fluid Mech.* **50**, 689.
- POTTER, M. C. & KUTCHEY, J. A. 1973 Stability of plane Hartmann flow subject to a transverse magnetic field. *Phys. Fluids* **16** (11), 1848.
- RÜDIGER, G., PRIMAVERA, L., ARLT, R. & ELSTNER, D. 1999 Magnetic shear-flow instability in thin accretion disks. *Mon. Not. R. Astron. Soc.* **306**, 913.
- SHANNON, T. E. *et al.* 1998 Conceptual design of the international fusion materials irradiation facility (IFMIF). *J. Nucl. Mater.* **258**, 106.
- SHEN, S. F. 1954 Calculated amplified oscillations in plane Poiseuille and Blasius flows. *J. Aeronaut. Sci.*, **21**, 62–64.

- SHERCLIFF, J. A. 1965 *A Textbook of Magnetohydrodynamics*. Pergamon.
- SMITH, M. K. & DAVIS, S. H. 1982 The instability of sheared liquid layers. *J. Fluid Mech.* **121**, 187.
- SQUIRE, H. B. 1933 On the stability for three-dimensional disturbances of viscous fluid flow between parallel walls. *Proc. R. Soc. Lond. A* **142** (847), 621.
- STRANG, G. 2005 *Linear Algebra and Its Applications*, 4th edn. Brooks Cole.
- STUART, J. T. 1954 On the stability of viscous flow between parallel planes in the presence of a co-planar magnetic field. *Proc. R. Soc. A* **221** (1145), 189.
- TAKASHIMA, M. 1996 The stability of the modified plane Poiseuille flow in the presence of a transverse magnetic field. *Fluid Dyn. Res.* **17**, 293.
- TAKASHIMA, M. 1998 The stability of the modified plane Couette flow in the presence of a transverse magnetic field. *Fluid. Dyn. Res.* **22**, 105.
- YIH, C. S. 1963 Stability of liquid flow down an inclined plane. *Phys. Fluids* **6** (3), 321.
- YIH, C. S. 1969 *Fluid Mechanics*. McGraw-Hill.